

# L-force

## *Servo Drives 9400*

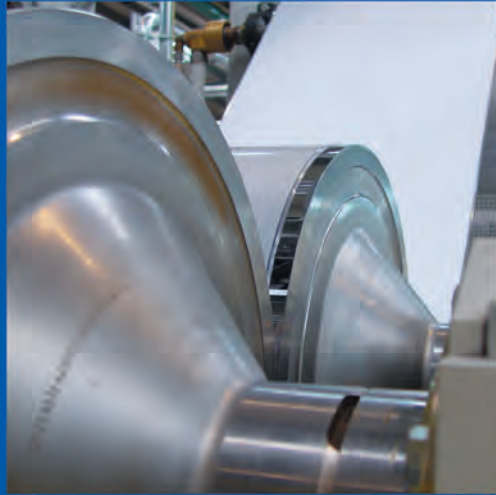


Productive, economical, easy to use

**Lenze**

**This is what we stand for.**

You want to implement your machine and plant concepts efficiently and easily or optimise existing concepts to reduce costs? Then, Lenze is the partner you are looking for. For more than 60 years, drive and automation systems have been our core competence.



Drive and automation technology set in motion by Lenze – for example in logistics centres, in the textile and printing industry, in the automotive industry or as the driving force behind robots.



# Lenze | about us

We can offer you automation solutions, including control, visualisation and drive technology, from a single source. Our drive systems will improve the performance of your machines. From project planning to commissioning, we have the know-how. Our international sales and service network can provide you with expert help and advice at any time.

Cut your process costs and increase your ability to compete. Let us analyse your drive technology tasks and support you with made-to-measure solutions. We can take an integrated approach to projects thanks to the scalability of our products and the scope of the overall portfolio. We can get the best from your machines and systems.



At your side all over the world – with thorough and professional support from our motivated team.

# L-force | Your future is our drive

## L-force - your future is our drive

L-force is our new product philosophy introduced in response to the need to reduce costs, save time and increase efficiency. This generation of drive and automation technology sets innovation, flexibility, usability and system culture in perfect harmony.

## L-force is innovation

In order to offer you more options and (added) value, we are constantly working to improve our solution still further.

## L-force means flexibility

Performance, functional range, software, technical services and after-sales service - you get exactly the combination you need.

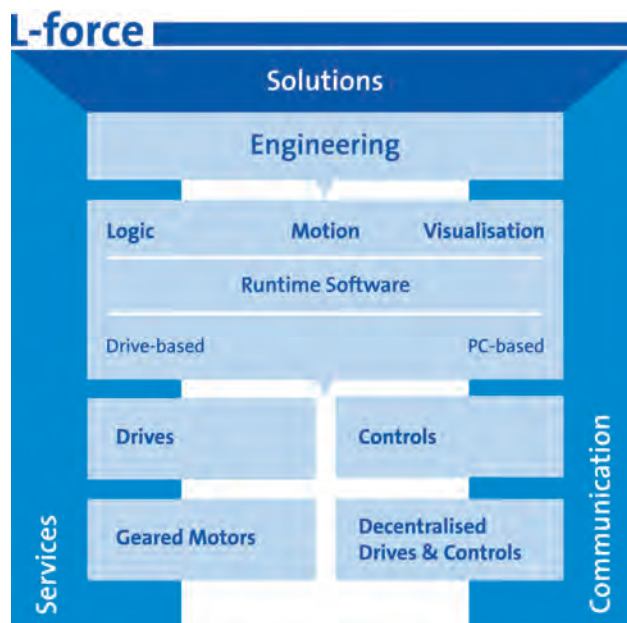
## L-force means usability

Commissioning is made easier thanks to preconfigured solutions and simple, function-based engineering.

## L-force means system

With L-force, everything is perfectly matched.

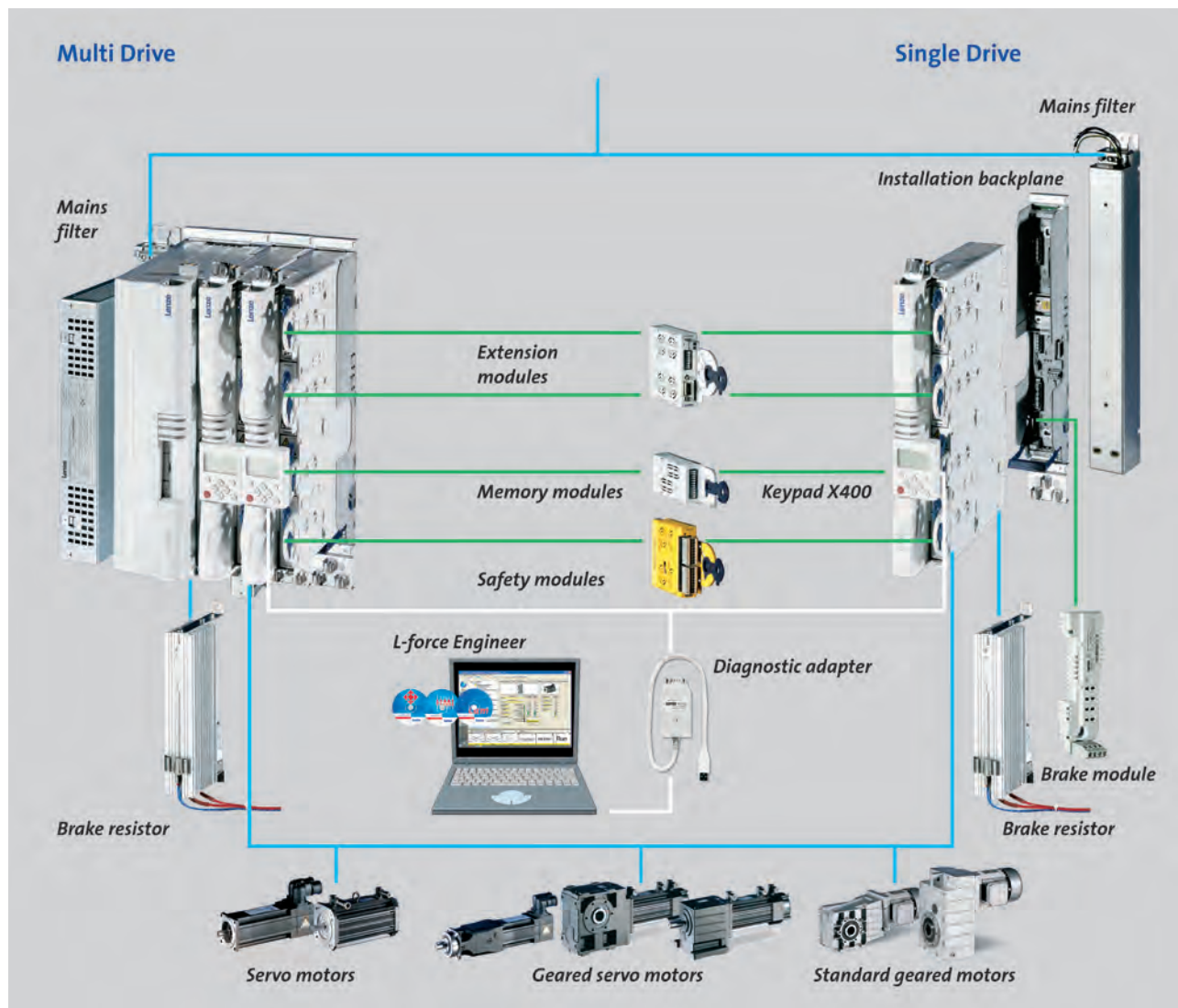
Let us help you shape your future.



*L-force is an integrated range of components, solutions, systems and technical services. The overview shows the overall portfolio along with the individual product/solution segments.*

# System overview | 9400 Servo Drives

## System overview



## Further catalogues

This catalogue describes the 9400 Servo Drives and the accessories directly associated with this servo system. For information about the other components shown in the system overview above, please refer to the corresponding catalogues. In addition, automation components are dealt with in the PC-based Automation catalogue.

components	Catalogue
SERVO MOTORS	▶ Servo motors
Geared servo motors	▶ Geared servo motors
Standard geared motors	▶ Geared motors

# Overview | 9400 Servo Drives

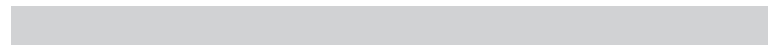
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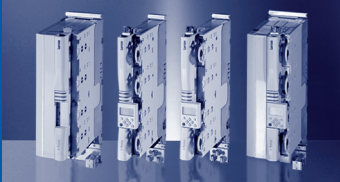
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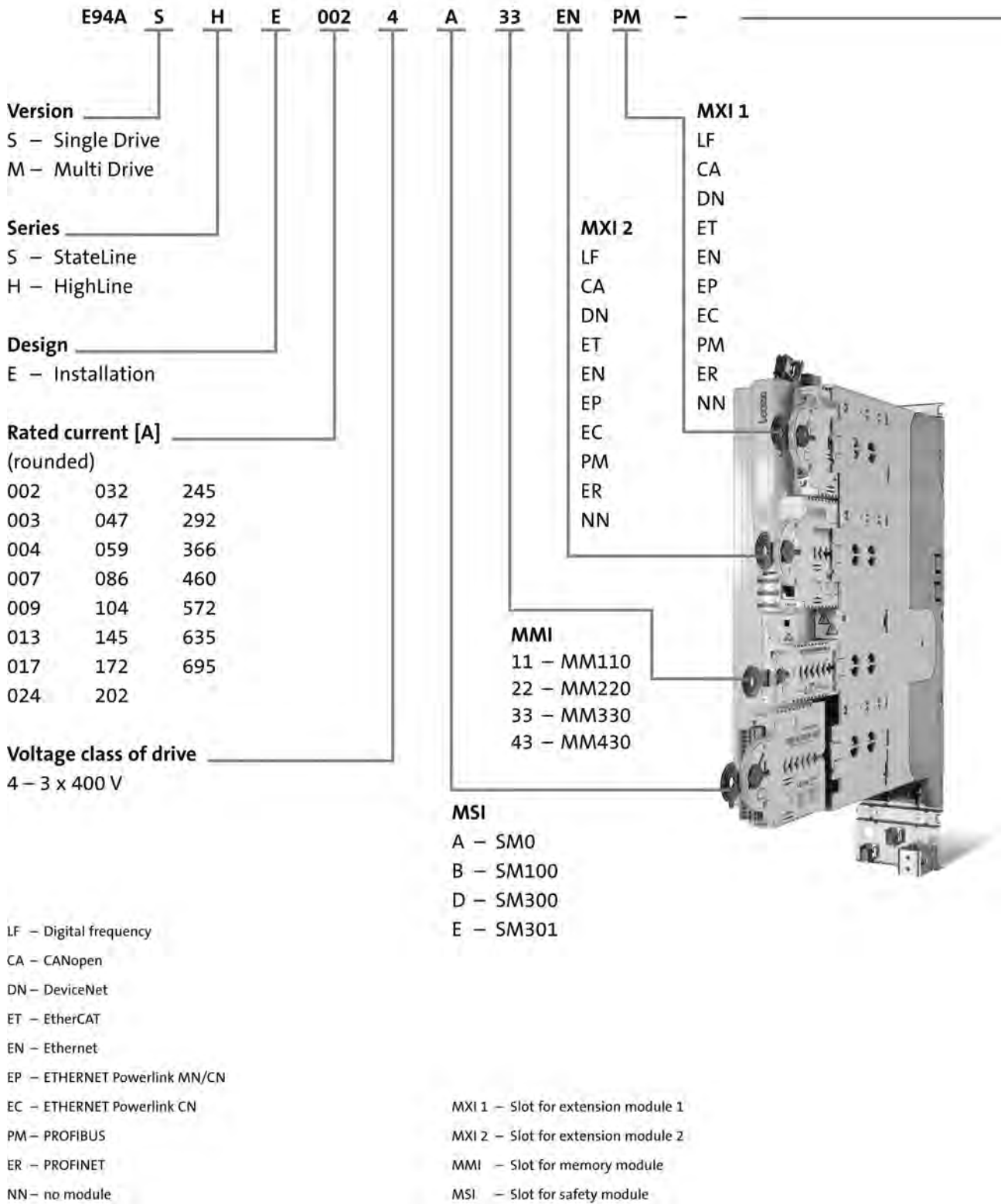
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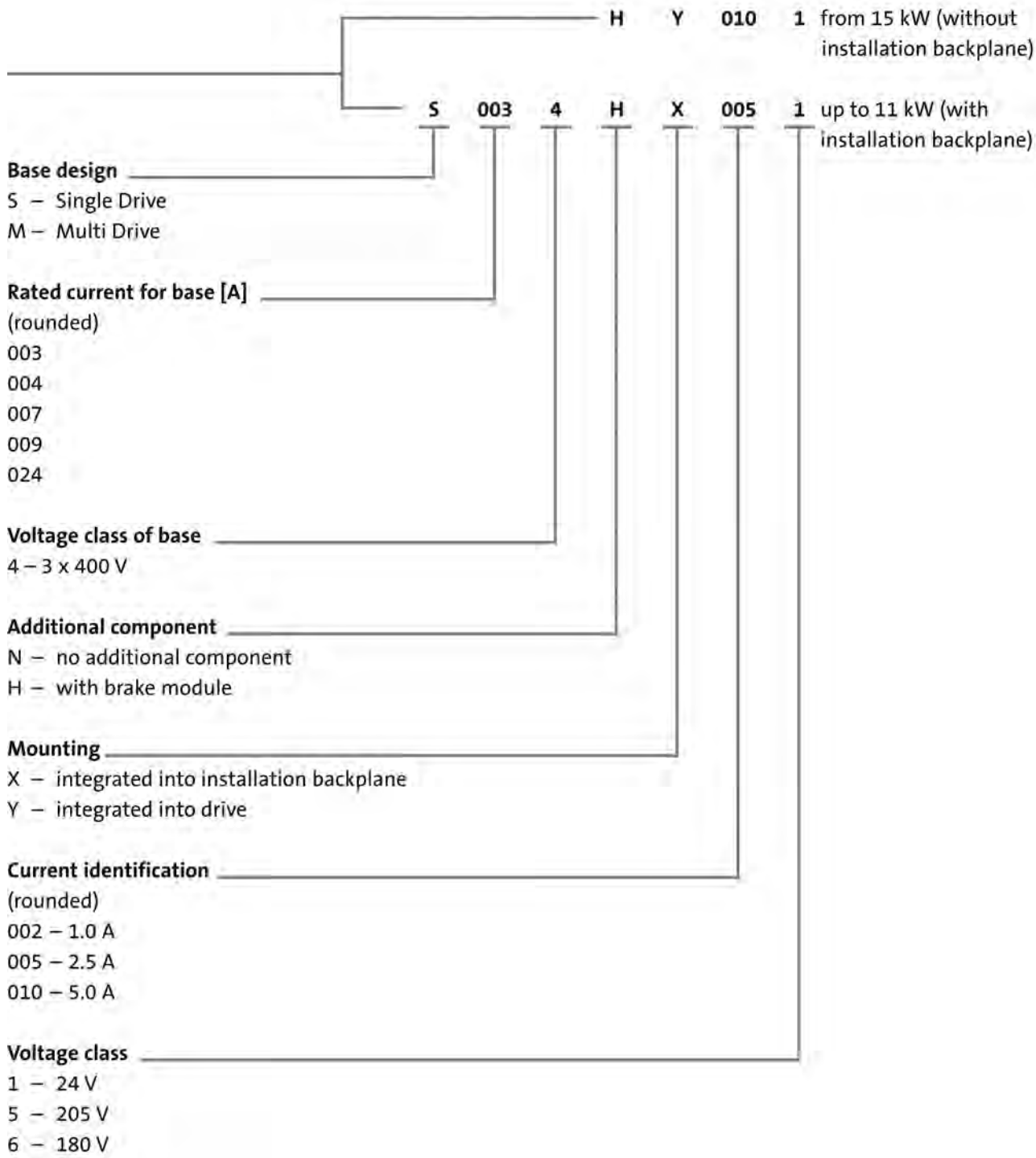
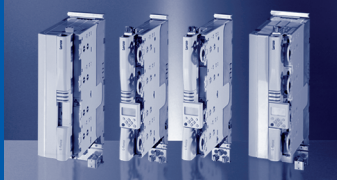


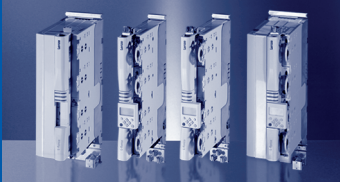
# 9400 Servo Drives

## Selection and ordering

### 9400 Servo Drives product key



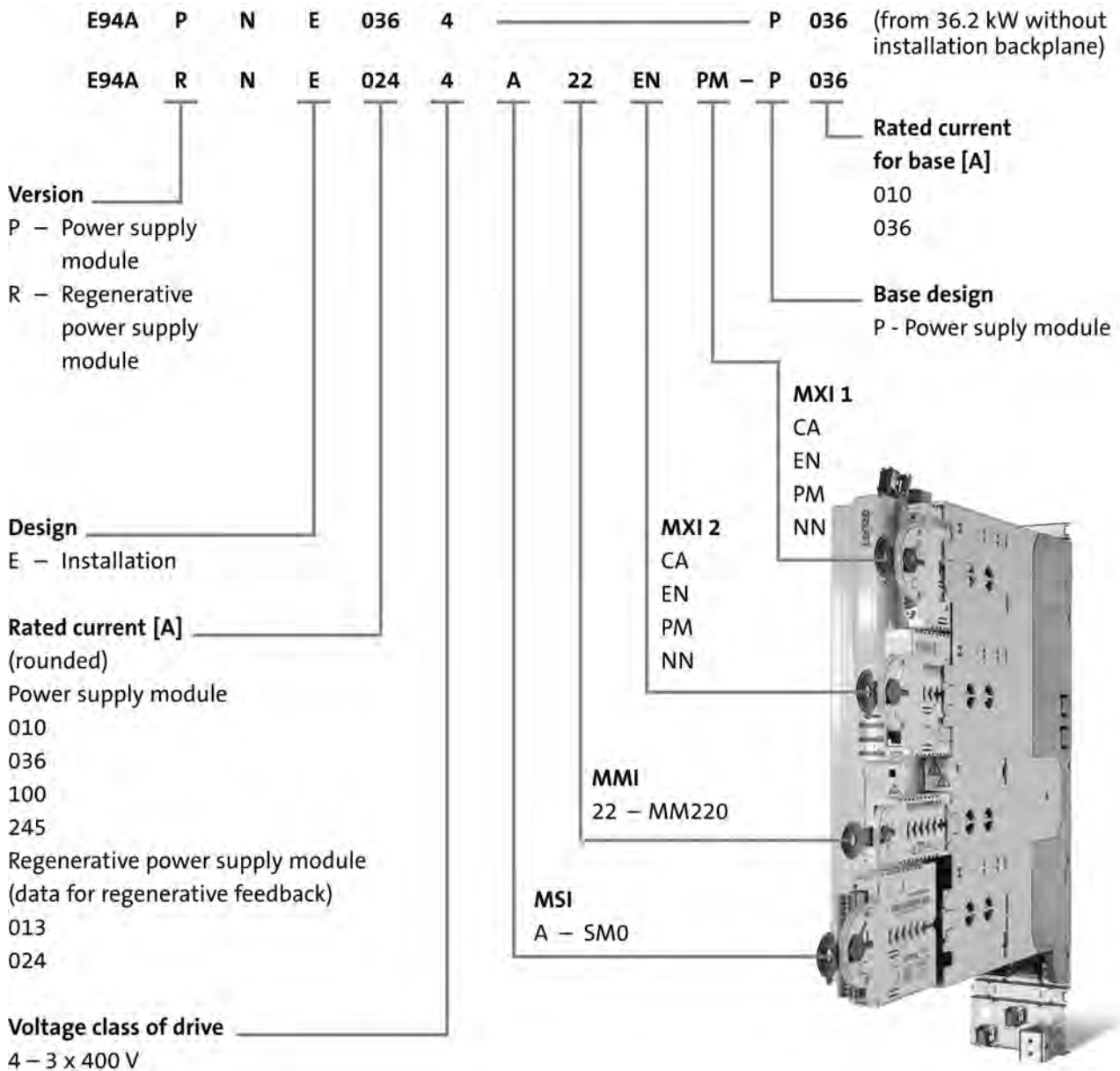




# 9400 Servo Drives

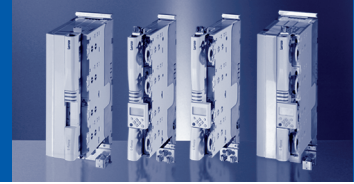
## Selection and ordering

### Power supply module and regenerative power supply module product key for 9400 Servo Drives

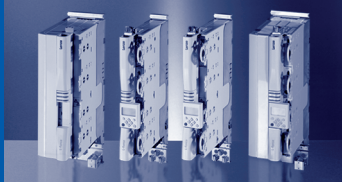


CA – CANopen  
 EN – Ethernet  
 PM – PROFIBUS  
 NN – no module

MXI 1 – Slot for extension module 1  
 MXI 2 – Slot for extension module 2  
 MMI – Slot for memory module  
 MSI – Slot for safety module







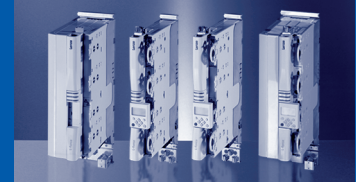
## 9400 Servo Drives

### Selection and ordering

#### List of abbreviations

<b>B</b> [mm]	Width
<b>f<sub>d</sub></b> [Hz]	Field frequency
<b>f<sub>ch</sub></b> [kHz]	Switching frequency
<b>f<sub>max</sub></b> [Hz]	Maximum output frequency
<b>H</b> [mm]	Height
<b>I<sub>max</sub></b> [A]	Maximum output current
<b>I<sub>N</sub></b> [A]	Rated current
<b>I<sub>DC</sub></b> [A]	Rated DC-bus current
<b>I<sub>Netz</sub></b> [A]	Rated mains current
<b>L</b> [mH]	Inductance
<b>l</b> [m]	Motor cable length
<b>m</b> [kg]	Mass
<b>M<sub>max</sub></b> [Nm]	Maximum torque
<b>M<sub>eff</sub></b> [Nm]	Effective torque
<b>n<sub>max</sub></b> [1/min]	Maximum speed
<b>P<sub>BRd</sub></b>	Continuous braking power
<b>P<sub>BRmax</sub></b>	Peak braking power
<b>P<sub>N</sub></b> [kW]	Motor power
<b>P<sub>NDC</sub></b> [kW]	DC-bus rated power
<b>P<sub>v</sub></b> [W]	Power loss
<b>R</b> [Ohm]	Resistance
<b>T</b> [mm]	Depth
<b>t<sub>re</sub></b>	Recovery time
<b>t<sub>on</sub></b>	Running time
<b>t<sub>ol</sub></b>	Overload time
<b>U<sub>Netz</sub></b> [V]	Mains voltage range Rated mains voltage
<b>U<sub>DC</sub></b> [V]	DC input voltage
<b>WK</b> [kWs]	Thermal capacity

<b>MMI</b>	Modular memory interface (memory module)
<b>MSI</b>	Modular safety interface (safety module)
<b>MXI 1</b> <b>MXI 2</b>	Modular extension interface (extension module)
<b>DIAG</b>	Slot for USB diagnostic adapter or X400 keypad
<b>EN 60529</b>	Degrees of protection provided by enclosures (IP code)
<b>EN 60721-3</b>	Classification of environmental conditions; Part 3: Classes of environmental parameters and their limit values
<b>EN 61800-3</b>	Electrical variable speed drives Part 3: EMC requirements including special test methods
<b>IEC 61131-2</b>	Programmable logic controllers Part 2: Equipment and tests
<b>IEC 61508</b>	Functional safety of electrical/electronic/programmable electronic safety-related systems
<b>DIN</b>	Deutsches Institut für Normung e.V.
<b>EN</b>	European standard
<b>IEC</b>	International Electrotechnical Commission
<b>IM</b>	International Mounting Code
<b>IP</b>	International Protection Code
<b>NEMA</b>	National Electrical Manufacturers Association
<b>VDE</b>	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)
<b>UL</b>	Underwriters Laboratory Listed Product
<b>UR</b>	Underwriters Laboratory Recognized Product



### About this catalogue

This catalogue provides an overview of all the components in the 9400 Servo Drive product range. Here you can find the different axis modules (Single Drive and Multi Drive), the corresponding power supply modules, and all accessory components for a complete drive system. The same product range is also covered in the electronic DSC catalogue. The electronic catalogue is available on DVD and on the Internet at: [www.lenze.de/dsc](http://www.lenze.de/dsc).

Additional information can also be downloaded from the Internet (e.g. rated data) for some components. These components are marked accordingly with the following arrow symbol and an identifier printed in bold.

→ Rated data for operation at 3/PE/AC 500 V

**DS\_9400\_0001**

Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

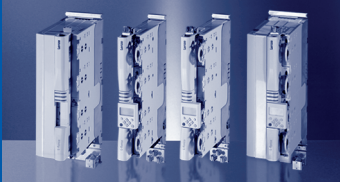
Just enter this identifier (e.g. **DS\_9400\_0001**) as the search term and you will get the information as a PDF file.

### Inverters and accessories

All components of the 9400 Servo Drives range can be selected easily and quickly via a uniform product key.

To improve the clarity, wild cards are used to represent similar designs.

- ▶ The symbol □ stands for all designs carrying the represented designation. The □ is, for instance, used to summarise the different variants: in E94AS□E0174 the □ could be a wildcard for H (HighLine) or S (StateLine).
- ▶ In the type designations of mains/RFI filters (accessory components) the wild cards stand for the different rated currents.



## 9400 Servo Drives

### General information

### 9400 Servo Drives Single Drive and Multi Drive

#### When will it click?

A great many technical achievements make our everyday lives easier.

Just like that, with one click

- ▶ the lights come on
- ▶ a seat belt engages
- ▶ you can surf the World Wide Web
- ▶ take a great photo of your family.

The 9400 Servo Drives will revolutionise your servo technology – with simple clicks.

#### Single Drive

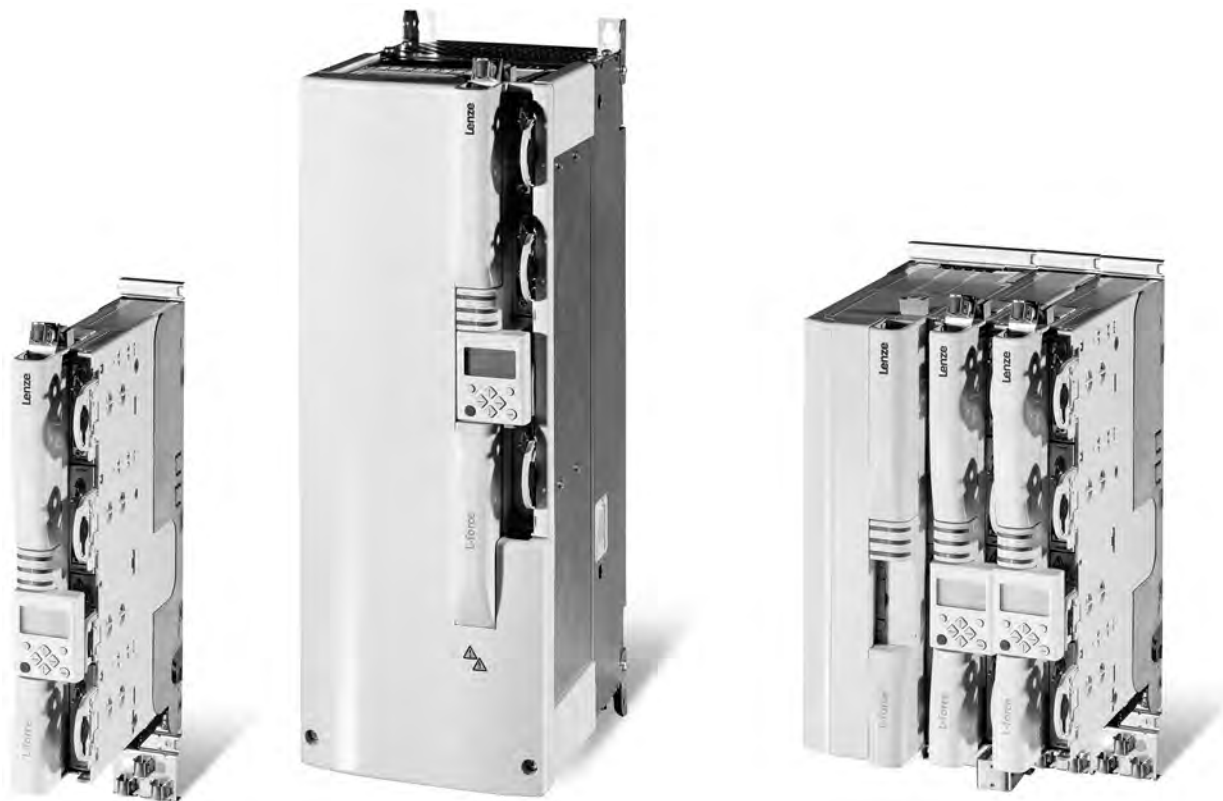
Our single-axis drives combine mains supply, DC bus and inverter in a single device. The filter elements and the brake chopper are integrated into the servo inverter and permit autonomous use in distributed control cabinet installations. Higher interference levels can be achieved without a larger mounting area by using suitable footprint filters (up to 55 kW).

#### Click – the innovative assembly concept

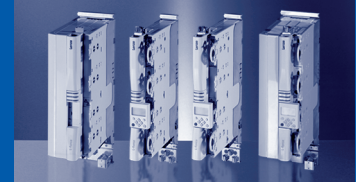
The 9400 Servo Drives have a revolutionary electromechanical assembly concept which wins its users over. Separating the installation backplane from the drive electronics (up to 11 kW) means that the installation, assembly and application procedures are unrivalled in their simplicity.

#### Multi Drive

Our multi-axis drives are particularly suitable for centralised, compact multi-axis installations. The energy exchange via the DC bus reduces the power requirement on the mains side. The axes share the same mains supply, brake chopper and EMC filter. The materials requirements and installation efforts are thus significantly reduced. The integrated DC busbar system provides for compact installations for drives rated up to 11 kW.



9400 Servo Drives Single Drive and 9400 Servo Drives Multi Drive



### 9400 Servo Drives StateLine and HighLine

#### StateLine - for centralised control concepts

The 9400 StateLine Servo Drives use the standardised drive profile DS402 / IEC 61800-7-2 and are ideally suited for centralised topologies. Therefore the StateLine excels with fast commissioning.

Use the implemented operating modes "Homing" for referencing the machine and "Interpolated Position" for fast position following with speed and torque feedforward control. In addition the StateLine features the operating modes "Cyclic Synchronous Velocity" for fast speed following with torque feedforward control and "Cyclic Synchronous Torque" for fast torque following with speed limitation.

The drives communicate with a higher-level motion control or an industrial PC via the CANopen or EtherCAT extension module. The modular concept of the 9400 Servo Drives leaves the system open for future fieldbus systems. One of the highlights of the StateLine is the integrated modular safety engineering concept which makes your machine much safer.

#### HighLine - for decentralised control concepts

The 9400 HighLine Servo Drives feature intelligence in the drive and are therefore designed for decentralised motion control applications as well as for centralised control topologies.

Lenze provides pre-programmed technology applications, e.g. table positioning, electronic gearbox and synchronism with mark registration for solving various applications simply by parameter setting. The function block editor integrated into the L-force Engineer HighLevel (PC setup tool) enables you to adapt the functions in an easy and flexible manner.

The HighLine Servo Drive comes with the CANopen fieldbus, conventional I/Os, diagnostic LEDs, a diagnostic interface, a resolver and a universal encoder input on board.

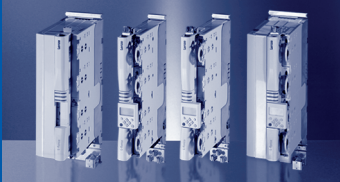
In addition, the HighLine is equipped with two extension slots for communication or extension modules as well as one slot each for a memory module and a safety module, so that the drive can be optimally adapted to your requirements.



9400 StateLine Servo Drives



9400 HighLine Servo Drives



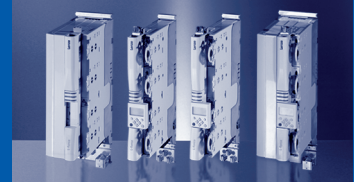
# 9400 Servo Drives

## General information

### Functions and features

Design	9400 StateLine Servo Drives	9400 HighLine Servo Drives
<b>Control modes/motor control</b>	Field-oriented servo control (SC) for synchronous and asynchronous servo motors and standard asynchronous motors	Field-oriented servo control (SC) for synchronous and asynchronous servo motors and standard asynchronous motors Sensorless vector control (SLVC) for standard asynchronous motors (for the drives: E94A□HE0024 to E94A□HE1044) V/f control (VFCplus) for standard and asynchronous servo motors
<b>Basic functions</b>	Motor control Drive monitoring and diagnosing Logbook, oscilloscope function Evaluation of electronic nameplate (ENP) for Lenze servo motors Speed, torque and position control Brake logic, homing	Motor control Drive monitoring and diagnosing Logbook, oscilloscope function Evaluation of electronic nameplate (ENP) for Lenze servo motors Speed, torque and position control Brake logic, homing, manual jog
<b>Technology applications</b>	Drive profile DS402 IEC 61800-7-2: - Homing mode - Interpolated position mode - Cyclic synchronous position - Cyclic synchronous velocity - Cyclic synchronous torque	Speed actuating drive Torque actuating drive Electronic gearbox Synchronism with mark registration Positioning (table positioning, positioning sequence control)
<b>Advanced functions</b>		Function blocks for cam function
<b>Monitoring</b>	Brake chopper Fan Motor phase failure DC-bus voltage	
<b>Monitoring and protective measures</b>	Short circuit Short to earth (protected against short to earth during operation, limited protection against short to earth on mains power-up) Overvoltage Overcurrent Overtemperature Undervoltage Motor stalling, motor overload Motor overtemperature (input for PTC or thermal contact, I <sup>2</sup> x t monitoring)	
<b>Diagnostics</b> Diagnostic interface	Integrated For keypad or USB diagnostic adapter	
Status displays	4 LEDs	6 LEDs
<b>Braking operation</b> Brake chopper Brake resistor	Integrated in Single Drives External	





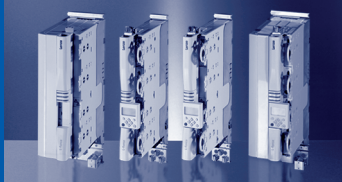
### Control connections

#### Click – the modular structure

The pluggable control connections of the 9400 Servo Drives are located at the front of the device to facilitate access to the control cabinet wiring. The USB diagnostic adapter E94AZCUS, the keypad EZAEBK1001 and the diagnosis terminal EZAEBK2001 are available for the diagnostic interface. For feedback, prefabricated system cables can be used to connect servo motors of the MCS and MCA series. Prefabricated system cables can be supplied in lengths of up to 150 m.



Design	9400 StateLine Servo Drives	9400 HighLine Servo Drives
<b>Inputs/outputs</b>		
Analog inputs	<ul style="list-style-type: none"> <li>▶ Number: 1</li> <li>▶ Resolution: 11 bits + sign</li> <li>▶ Value range: +/-10V</li> <li>▶ 1x switchable value range: +/- 20mA</li> </ul>	<ul style="list-style-type: none"> <li>▶ Number: 2</li> <li>▶ Resolution: 11 bits + sign</li> <li>▶ Value range: +/-10V</li> <li>▶ 1x switchable value range: +/- 20mA</li> </ul>
Analog outputs		<ul style="list-style-type: none"> <li>▶ Number: 2</li> <li>▶ Resolution 10 bits + sign</li> <li>▶ Value range: +/- 10 V</li> <li>▶ Max. 2 mA</li> </ul>
Digital inputs	<ul style="list-style-type: none"> <li>▶ Number: 4</li> <li>▶ Touch-probe capable: 1</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. input current: 8mA</li> </ul>	<ul style="list-style-type: none"> <li>▶ Number: 8</li> <li>▶ Touch-probe capable: 8</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. input current: 8mA</li> </ul>
Digital outputs	<ul style="list-style-type: none"> <li>▶ Number: 1</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. output current: 50mA per output</li> <li>▶ Load &gt; 480 Ω at 24V</li> </ul>	<ul style="list-style-type: none"> <li>▶ Number: 4</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. output current: 50mA per output</li> <li>▶ Load &gt; 480 Ω at 24V</li> </ul>



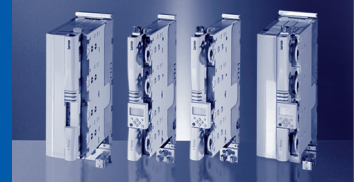
# 9400 Servo Drives

## General information

### Control connections

Design	9400 StateLine Servo Drives	9400 HighLine Servo Drives
<b>Interfaces</b>		
CANopen	▶ Via slot MXI 1: extension	▶ Integrated
Extension modules	▶ Via slot MXI 1: extension ▶ Slot MXI 2: not available	▶ Via slot MXI 1: extension 1 ▶ Via slot MXI 2: extension 2
State bus	▶ Integrated	
Memory module	▶ Slot MMI	
Safety module	▶ Slot MSI	
<b>Drive interface</b>		
Resolver input	▶ Integrated ▶ Sub-D, 9-pin	
Encoder input	▶ Sub-D, 15-pin ▶ Multi-encoder input for: SinCos/TTL incremental encoder, SinCos absolute value encoder single-turn / multi-turn (Hiperface® / Endat V2.1)	
Motor temperature monitoring evaluation	▶ Via feedback: KTY evaluation ▶ Input on the device: PTC evaluation	
Motor brake control	▶ Optional, in the installation backplane up to 23.5 A or in the axis module from 32 A	
<b>Control electronics supply</b>		
Rated voltage	▶ 24V in accordance with IEC 61131-2	
Voltage range	▶ 19.2 ... 28.8V, residual ripple max. ± 5%	
Current consumption	▶ Single Drive: approx. 1.2A during operation, max. 3A starting current for 100ms <sup>1)</sup> ▶ Multi Drive: approx. 2.4A during operation, max. 4A starting current for 100ms	

<sup>1)</sup> The supply voltage for the control electronics comes from the mains voltage. Alternatively, it can be provided by a 24 V supply that is independent of the mains (available as an option).



### Power supply modules for 9400 Servo Drives

#### Power supply modules

The 9400 series power supply modules form the central AC mains connection for a Multi Drive axis grouping. A brake chopper is integrated, as is an outlet to the DC-bus busbar system of the 9400 Multi Drives. Filters and, if necessary, a brake resistor are to be provided by an external source. The combined usage of the mains supply, the brake chopper, the DC-bus busbar system and the filter significantly reduces material and installation costs within a Multi Drive axis grouping.

#### Regenerative power supply modules

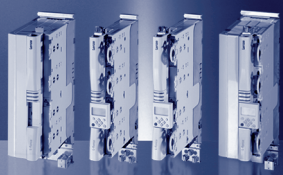
In many applications, the electrical drives used must be accelerated and decelerated repeatedly. If the braking power that occurs is to be fed back into the mains, the power supply/regenerative modules can be used for this. Both of the designs for rated powers of 15 kW and 27 kW fit seamlessly into the power supply and axis module series. The separation of the installation backplane and electronic module also makes installation and mounting very simple. The necessary mains filter is added simply and connected to the installation backplane and the regenerative power supply module via the available connecting cables. The mains filter is available both in a standard design and with increased interference suppression for long motor cables. The regenerative power supply modules can increase their rated power for a short period. This means that they are ideally suited to intermittent drives. If more supply power is required, further uncontrolled rectifiers can be connected in parallel. Therefore, parallel operation with a power supply module is possible.



*Power supply module*



*Regenerative power supply module*

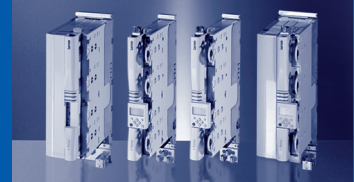


## 9400 Servo Drives

### General information

#### Functions and features

Design	Power supply modules	Regenerative power supply modules
<b>Basic functions</b>	Supply to an axis module or multi-axis system in DC-bus connection	Supply to an axis module or multi-axis system in DC-bus connection Power recovery of the surplus power arising during braking operation into the mains Operation monitoring and diagnostics Logbook, oscilloscope function
<b>Monitoring</b>	Brake chopper Mains voltage Overtemperature	Brake chopper Mains filter Mains voltage, DC-bus voltage Regenerative inverter Overtemperature
<b>Monitoring and protective measures</b>	Short circuit brake chopper	Short circuit brake chopper Mains and mains phase failure detection Overvoltage Device overload Mains filter overload Brake chopper overload Mains inverter overcurrent Undervoltage
<b>Diagnostics</b> Diagnostic interface		Integrated For keypad or USB diagnostic adapter
Status displays	5 LEDs	6 LEDs
<b>Braking operation</b> Power recovery Brake chopper Brake resistor	Integrated External	Via integrated mains inverter



### Control connections

#### Click – the modular structure

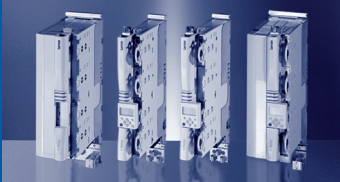
The pluggable control connections of the power supply modules and the regenerative power supply modules are located at the front of the drive to facilitate access to the control cabinet wiring. The USB diagnostic adapter E94AZCUS, the keypad EZAEBK1001 and the diagnosis terminal EZAEBK2001 are available for the diagnostic interface of the regenerative power supply module.



Design	Power supply modules	Regenerative power supply modules
<b>Inputs/outputs</b> Analog inputs  Analog outputs  Digital inputs  Digital outputs	<ul style="list-style-type: none"> <li>▶ Configured</li> <li>▶ Number: 1</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. input current: 8 mA</li> <li>▶ Configured</li> <li>▶ Number: 4</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. output current: 50 mA per output</li> <li>▶ Load &gt; 480 Ω at 24 V</li> </ul>	<ul style="list-style-type: none"> <li>▶ Number: 2</li> <li>▶ Resolution: 11 bits + sign</li> <li>▶ Value range: +/-10V, 1x switchable, 0 ... 20 mA</li> <li>▶ Number: 2</li> <li>▶ Resolution 10 bits + sign</li> <li>▶ Value range: +/- 10 V Max. 2 mA</li> <li>▶ Number: 8</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. input current: 8 mA</li> <li>▶ Number: 4</li> <li>▶ Switching level: PLC (IEC 61131-2)</li> <li>▶ Max. output current: 50 mA per output</li> <li>▶ Load &gt; 480 Ω at 24 V</li> </ul>
<b>Interfaces</b> CANopen Extension modules  State bus Memory module Safety module		<ul style="list-style-type: none"> <li>▶ Integrated</li> <li>▶ Via slot MXI 1: extension 1</li> <li>▶ Via slot MXI 2: extension 2</li> <li>▶ Integrated</li> <li>▶ Slot MMI</li> <li>▶ Slot MSI</li> </ul>
<b>Application interfaces</b> Resolver input Mains synchronisation input  Temperature monitoring input		<ul style="list-style-type: none"> <li>▶ Integrated (no function)</li> <li>▶ Integrated</li> <li>▶ Sub-D, 15-pin</li> <li>▶ Input on the device: PTC evaluation</li> </ul>
<b>Control electronics supply</b> Rated voltage Voltage range Current consumption	<ul style="list-style-type: none"> <li>▶ 24V in accordance with IEC 61131-2</li> <li>▶ 19.2 ... 28.8V, residual ripple max. ± 5%</li> <li>▶ Approx. 1.4A during operation, max. 4A starting current for 100ms</li> </ul>	<ul style="list-style-type: none"> <li>▶ Approx. 1.2A during operation, max. 3A starting current for 100ms<sup>1)</sup></li> </ul>

<sup>1)</sup> The supply to the control electronics comes from the mains voltage. Alternatively, it can be provided by a 24 V supply that is independent of the mains (available as an option).





# 9400 Servo Drives

## General information

### Basic dimensioning of axis modules

Here the most important steps for dimensioning Single Drive and Multi Drive axis modules are listed.

► **Motor power required**

First, the maximum torque required  $M_{max}$ , the maximum speed  $n_{max}$ , the effective torque  $M_{eff}$  and - for geared motors - the transmission ratio  $i$  are determined from the system data.

► **Motor selection**

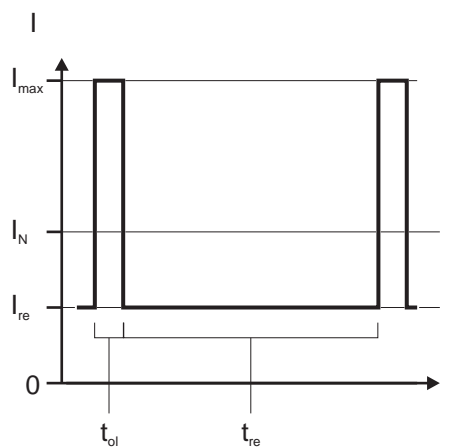
Based on these values, the appropriate servo motor can be selected from the MCS (synchronous motors), MCA or MDFQA (asynchronous motors) ranges.

► **Selecting the axis module**

The axis modules are selected on the basis of the maximum currents and power required.

Depending on the drive, the 9400 Servo Drives and the power supply modules can be operated for overload time  $t_{ol}$  with maximum output current  $I_{max}$ , provided that the drive is then operated for recovery time  $t_{re}$  with a reduced output current.

The switching frequency is automatically adapted to the rate of utilisation.

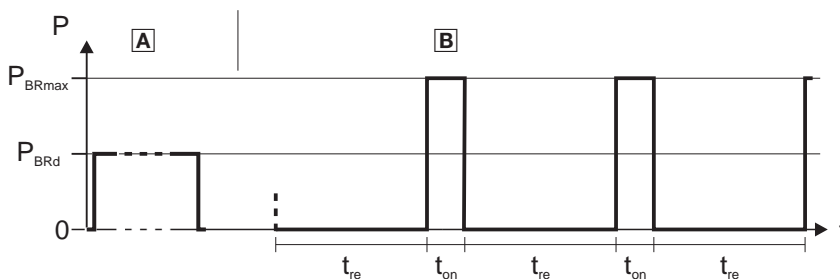


Maximum output current cycle

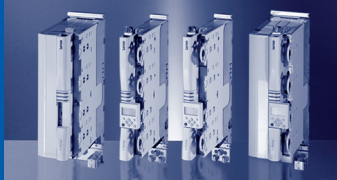
► **Braking operation**

If high moments of inertia are to be braked or if extended operation in generator mode is to be executed, braking energy can be transferred to an external brake resistor or converted into heat with Single Drive axis modules or with power supply modules via the integrated brake chopper.

The brake chopper can dissipate the continuous braking power  $P_{BRd}$  on a continual basis (case A) or the peak braking power  $P_{BRmax}$  for the running time  $t_{on}$  followed by the recovery time  $t_{re}$  (case B).



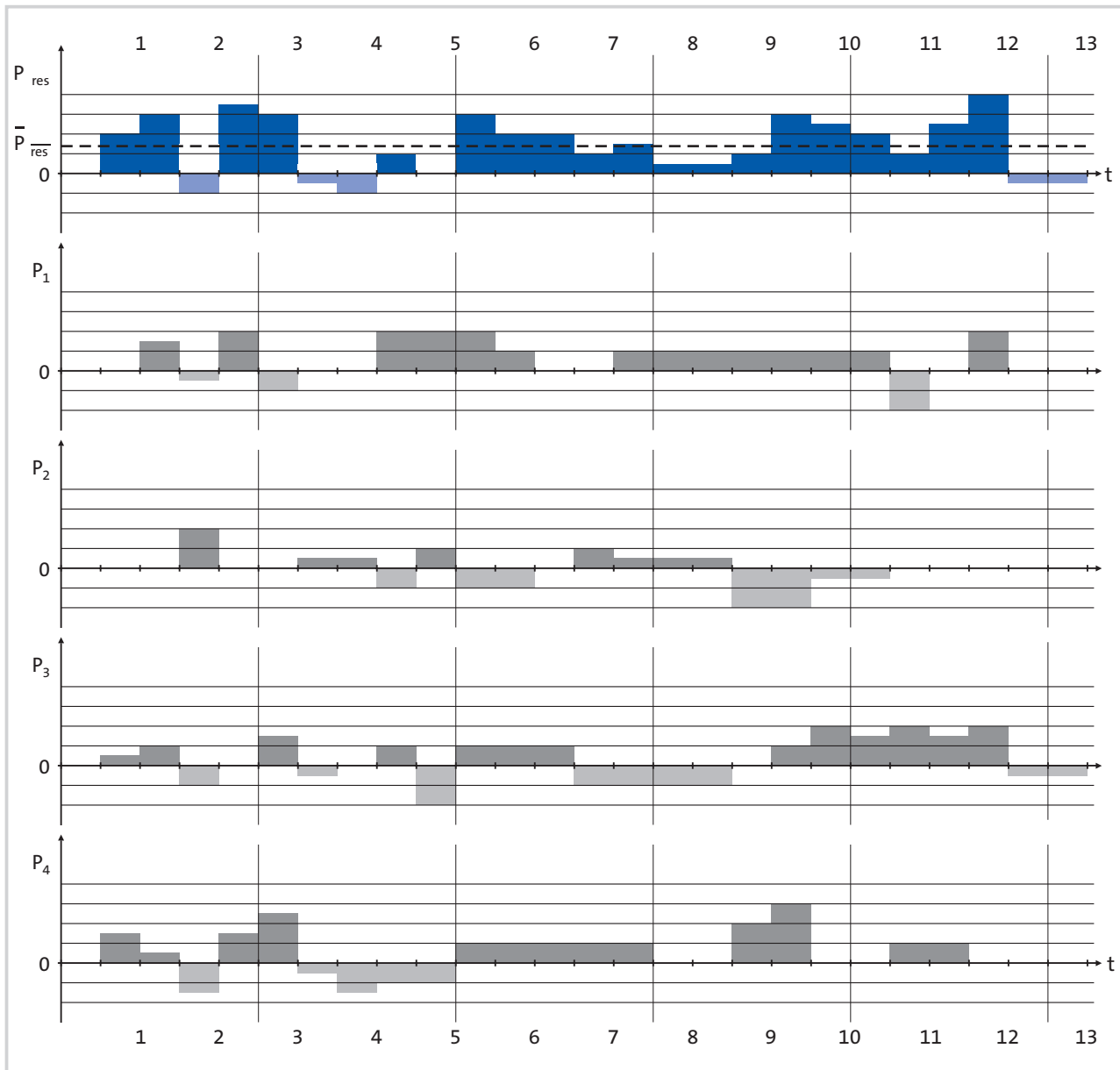
Brake chopper braking power



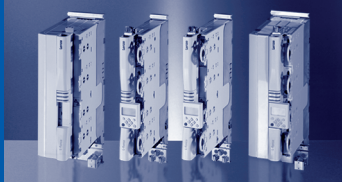
### Dimensioning for DC-bus operation

► **Dimensioning of interconnected multi-axis modules**

The best way to select the ideal power supply module required for a multi-axis application is to use a time/power diagram for the complete machine cycle for all axis modules. The total power required of the power supply module can be calculated by adding the time-based individual axis power ratings. In the same way the braking power required can be determined.



*Time/power diagram of a multi-axis servo system*  
 $P_1 \dots P_4$  = individual power of axis 1...axis 4  
 $P_{res}$  = addition of individual powers  
 $P_{res\ 1-4}$  = mean value of individual powers



# 9400 Servo Drives

## General information

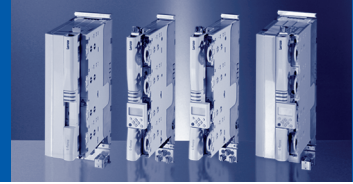
### Standards and operating conditions

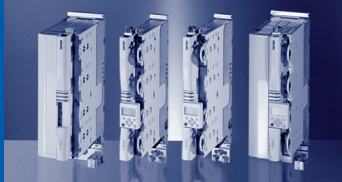
<b>Conformity</b>	CE: Low-Voltage Directive (2006/95/EC)
<b>Approvals</b> UL 508C	Power Conversion Equipment (file no. 132659) <sup>1)</sup>
<b>Enclosure</b> EN 60529 NEMA	IP20 <sup>2)</sup> Protection against contact according to NEMA 250 type 1 <sup>2)</sup>
<b>Climatic conditions</b> Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3) Rated output current derating	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C) Above +45 °C by 2.5%/°C
<b>Permissible installation height</b>  Rated output current derating Overvoltage category at and above 2000 m	0 ... 4000 m amsl Above 1000 m amsl by 5%/1000 m Above 2000 m only for use in overvoltage category II
<b>Vibration resistance</b> Transport EN 60721-3-2 Operation	2M2 Germanischer Lloyd: 5 Hz ≤ f ≤ 13.2 Hz ± 1 mm amplitude 13.2 Hz < f ≤ 100 Hz 0.7 g

<sup>1)</sup> In preparation for products: communication module EtherCAT E94AYCET, regenerative power supply modules E94ARNE□□□4 and the accompanying mains filters E94AZMR□□□4□DB

<sup>2)</sup> Not in the wire range of the on the motor-side terminals

<b>Permissible supply forms</b> Unrestricted use	Systems with earthed star point (TN and TT systems) Systems with high-resistance or isolated star point (IT systems)
<b>Leakage current to PE</b> EN 61800-5-1	> 3.5 mA, fixed installation required, PE must be reinforced
<b>Noise emission</b> EN 61800-3	Conducted disturbance: Max. shielded motor cable lengths for compliance with the C2 EMC protection requirements without external filters E94AS□E0024 to E94AS□E0244: 10 m E94AS□E0324 to E94AS□E1044: 50 m E94AS□E1454 to E94AS□E6954: 150 m
<b>Noise immunity</b> EN 61800-3	Category C3
<b>Insulation resistance</b> EN 61800-5-1	Overvoltage category III, Above 2000 m amsl overvoltage category II
<b>Pollution degree</b> EN 61800-5-1	2
<b>Protective insulation of control circuits</b> EN 61800-5-1	Safe mains isolation through double/reinforced insulation for digital inputs and outputs









# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

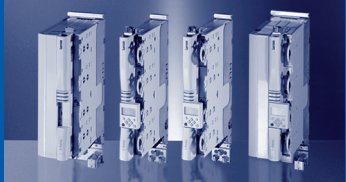
					
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	<b>0.37</b>	<b>0.75</b>	<b>1.5</b>	<b>3</b>
<b>Product key</b> <sup>1)</sup> Single Drive		<b>E94AS□E0024</b>	<b>E94AS□E0034</b>	<b>E94AS□E0044</b>	<b>E94AS□E0074</b>
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 180 V-0% ... 550 V+0%; 45 Hz-0% ... 65 Hz+0%			
<b>Alternative DC supply</b>	$U_{DC}$ [V]	DC 260-0% ... 775 V+0%			
<b>Rated output current</b>					
2 kHz	$I_N$ [A]	1.9 <sup>3)</sup>	3.1 <sup>3)</sup>	5 <sup>3)</sup>	8.8 <sup>3)</sup>
4 kHz	$I_N$ [A]	1.9 <sup>3)</sup>	3.1 <sup>3)</sup>	5 <sup>3)</sup>	8.8 <sup>3)</sup>
8 kHz	$I_N$ [A]	1.5	2.5	4	7
16 kHz	$I_N$ [A]	1.1	1.9	3	5.3
<b>Max. output current cycle (long)</b> <sup>2, 4)</sup>					
Max. output current	$I_{max}$ [A]	2.8	4.7	7.5	13.1
Reduced output current	$I_{re}$ [A]	1.4	2.3	3.8	6.6
Overload time	$t_{ol}$ [s]	60			
Recovery time	$t_{re}$ [s]	120			
<b>Max. output current cycle (short)</b> <sup>2, 4)</sup>					
Max. output current	$I_{max}$ [A]	6	10	16	21
Reduced output current	$I_{re}$ [A]	1.4	2.3	3.8	6.6
Overload time	$t_{ol}$ [s]	0.5			
Recovery time	$t_{re}$ [s]	4.5			

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram

<sup>3)</sup> Mains filter required





<sup>4)</sup> Mains filter required; if no mains filter is installed, the stated values for  $I_{max}$  and  $I_{re}$  decrease





### Rated data for Single Drives

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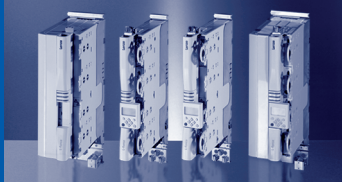
→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

					
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	0.37	0.75	1.5	3
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E0024	E94AS□E0034	E94AS□E0044	E94AS□E0074
<b>Rated mains current</b> With mains choke / mains filter	$I_{Netz}$ [A]	1.5	2.5	3.9	7
Without mains choke / mains filter	$I_{Netz}$ [A]	2.1	3.5	5.5	9.9
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	2.6	4.3	6.7	12.1
<b>Braking unit data</b> <sup>2)</sup> Continuous braking power	$P_{BRd}$ [kW]	1.3	1.9	2.6	
Peak braking power	$P_{BRmax}$ [kW]	6.4	11.2		
Running time	$t_{on}$ [s]	0.7	0.6	0.8	
Recovery time	$t_{re}$ [s]	4.3	4.4	4.2	
Min. brake resistance	$R$ [Ohm]	82	47		
<b>Power loss</b>	$P_V$ [W]	110	130	160	210
<b>Dimensions</b> Height	H [mm]	350 (with 481 installation backplane)			
Width	B [mm]	60		90	
Depth	T [mm]	288			
<b>Mass</b>	m [kg]	4		5.3	
<b>Permissible motor cable length</b> Shielded	l [m]	50		100	

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram






# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

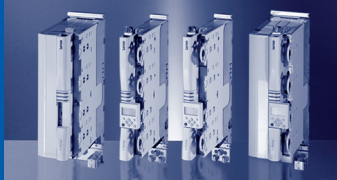
				
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	<b>5.5</b>	<b>7.5</b>	<b>11</b>
<b>Product key</b> <sup>1)</sup> Single Drive		<b>E94AS□E0134</b>	<b>E94AS□E0174</b>	<b>E94AS□E0244</b>
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 180 V-0% ... 550 V+0%; 45 Hz-0% ... 65 Hz+0%		
<b>Alternative DC supply</b>	$U_{DC}$ [V]	DC 260-0% ... 775 V+0%		
<b>Rated output current</b>				
2 kHz	$I_N$ [A]	16.3 <sup>3)</sup>	20.6 <sup>3)</sup>	29.4 <sup>3)</sup>
4 kHz	$I_N$ [A]	16.3 <sup>3)</sup>	20.6 <sup>3)</sup>	29.4 <sup>3)</sup>
8 kHz	$I_N$ [A]	13	16.5	23.5
16 kHz	$I_N$ [A]	9.8	12.4	17.6
<b>Max. output current cycle (long)</b> <sup>2, 4)</sup>				
Max. output current	$I_{max}$ [A]	24.4	30.9	44.1
Reduced output current	$I_{re}$ [A]	12.2	15.5	22.1
Overload time	$t_{ol}$ [s]		60	
Recovery time	$t_{re}$ [s]		120	
<b>Max. output current cycle (short)</b> <sup>2, 4)</sup>				
Max. output current	$I_{max}$ [A]	39	49.5	58.8
Reduced output current	$I_{re}$ [A]	12.2	15.5	22.1
Overload time	$t_{ol}$ [s]		0.5	
Recovery time	$t_{re}$ [s]		4.5	

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram

<sup>3)</sup> Mains filter required


<sup>4)</sup> Mains filter required; if no mains filter is installed, the stated values for  $I_{max}$  and  $I_{re}$  decrease





### Rated data for Single Drives

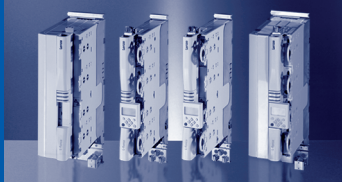
- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

				
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	5.5	7.5	11
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E0134	E94AS□E0174	E94AS□E0244
<b>Rated mains current</b> With mains choke / mains filter	$I_{Netz}$ [A]	11.8	15	20.5
Without mains choke / mains filter	$I_{Netz}$ [A]	16.8	21	29
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	20.6	25.7	35.5
<b>Braking unit data</b> <sup>2)</sup> Continuous braking power	$P_{BRd}$ [kW]	4.7	6.4	9.3
Peak braking power	$P_{BRmax}$ [kW]	19.5	29.2	
Running time	$t_{on}$ [s]	0.8	0.7	1.1
Recovery time	$t_{re}$ [s]	4.2	4.3	3.9
Min. brake resistance	$R$ [Ohm]	27	18	
<b>Power loss</b>	$P_V$ [W]	320	380	500
<b>Dimensions</b> Height	$H$ [mm]	350 (with 481 installation backplane)		
Width	$B$ [mm]	120		
Depth	$T$ [mm]	288		
<b>Mass</b>	$m$ [kg]	8.1		
<b>Permissible motor cable length</b> Shielded	$l$ [m]	100		

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram




# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

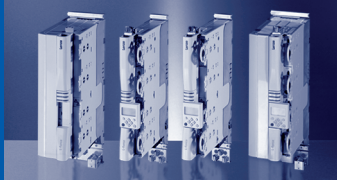
- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
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→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

				
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	<b>15</b>	<b>22</b>	<b>30</b>
<b>Product key</b> <sup>1)</sup> Single Drive		<b>E94AS□E0324</b>	<b>E94AS□E0474</b>	<b>E94AS□E0594</b>
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 180 V-0% ... 550 V+0%; 45 Hz-0% ... 65 Hz+0%		
<b>Alternative DC supply</b>	$U_{DC}$ [V]	DC 260-0% ... 775 V+0%		
<b>Rated output current</b>				
2 kHz	$I_N$ [A]	38.4	47	59
4 kHz	$I_N$ [A]	38.4	47	59
8 kHz	$I_N$ [A]	32		41
16 kHz	$I_N$ [A]	16.8		21.5
<b>Max. output current cycle (long)</b> <sup>2)</sup>				
Max. output current	$I_{max}$ [A]	57.6	70.5	88.5
Reduced output current	$I_{re}$ [A]	28.8	35.3	44.3
Overload time	$t_{ol}$ [s]		60	
Recovery time	$t_{re}$ [s]		120	
<b>Max. output current cycle (short)</b> <sup>2)</sup>				
Max. output current	$I_{max}$ [A]	76.8	94	118
Reduced output current	$I_{re}$ [A]	28.8	35.3	44.3
Overload time	$t_{ol}$ [s]		0.5	
Recovery time	$t_{re}$ [s]		4.5	

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules


<sup>2)</sup> →  24 - See diagram





### Rated data for Single Drives

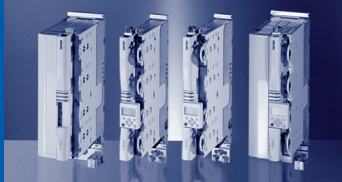
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→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

				
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	15	22	30
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E0324	E94AS□E0474	E94AS□E0594
<b>Rated mains current</b>				
With mains choke / mains filter	$I_{Netz}$ [A]	29	43	54
Without mains choke / mains filter	$I_{Netz}$ [A]	29	43	54
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	36	53	66
<b>Braking unit data</b> <sup>2)</sup>				
Continuous braking power	$P_{BRd}$ [kW]	12.6	18.6	25.3
Peak braking power	$P_{BRmax}$ [kW]	29.2	35	43
Running time	$t_{on}$ [s]	260	320	430
Recovery time	$t_{re}$ [s]	340	280	170
Min. brake resistance	$R$ [Ohm]	18	15	
<b>Power loss</b>	$P_V$ [W]	700	1050	1122
<b>Dimensions</b>				
Height	H [mm]		602	
Width	B [mm]		206	
Depth	T [mm]		294	
<b>Mass</b>	$m$ [kg]		19	
<b>Permissible motor cable length</b> Shielded	$l$ [m]		100	

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram




# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

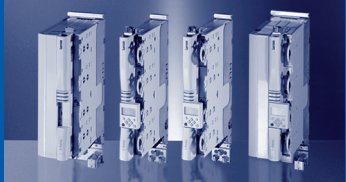
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→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

			
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	<b>45</b>	<b>55</b>
<b>Product key</b> <sup>1)</sup> Single Drive		<b>E94AS□E0864</b>	<b>E94AS□E1044</b>
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 180 V-0% ... 550 V+0%; 45 Hz-0% ... 65 Hz+0%	
<b>Alternative DC supply</b>	$U_{DC}$ [V]	Not possible	
<b>Rated output current</b>			
2 kHz	$I_N$ [A]	86	104
4 kHz	$I_N$ [A]	86	104
8 kHz	$I_N$ [A]	73	78
16 kHz	$I_N$ [A]	38.3	41
<b>Max. output current cycle (long)</b> <sup>2)</sup>			
Max. output current	$I_{max}$ [A]	129	156
Reduced output current	$I_{re}$ [A]	64.5	78
Overload time	$t_{ol}$ [s]	60	
Recovery time	$t_{re}$ [s]	120	
<b>Max. output current cycle (short)</b> <sup>2)</sup>			
Max. output current	$I_{max}$ [A]	172	208
Reduced output current	$I_{re}$ [A]	64.5	78
Overload time	$t_{ol}$ [s]	0.5	
Recovery time	$t_{re}$ [s]	4.5	

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules


<sup>2)</sup> →  24 - See diagram





### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

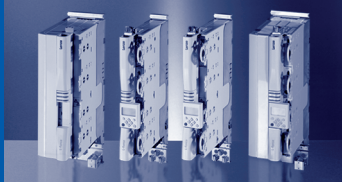
→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

			
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	45	55
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E0864	E94AS□E1044
<b>Rated mains current</b> With mains choke / mains filter	$I_{Netz}$ [A]	79	95
Without mains choke / mains filter	$I_{Netz}$ [A]	79	95
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	96.8	116.4
<b>Braking unit data</b> <sup>2)</sup> Continuous braking power	$P_{BRd}$ [kW]	37.9	46.3
Peak braking power	$P_{BRmax}$ [kW]		70.1
Running time	$t_{on}$ [s]	320	400
Recovery time	$t_{re}$ [s]	280	200
Min. brake resistance	$R$ [Ohm]		7.5
<b>Power loss</b>	$P_V$ [W]	1500	1800
<b>Dimensions</b> Height	$H$ [mm]		702
Width	$B$ [mm]		266
Depth	$T$ [mm]		370
<b>Mass</b>	$m$ [kg]		42
<b>Permissible motor cable length</b> Shielded	$l$ [m]		100

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram







# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

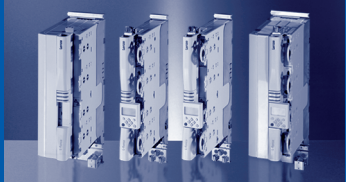
											
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	75	85 <sup>3)</sup>	95 <sup>4)</sup>	90	105 <sup>3)</sup>	110 <sup>4)</sup>	105	125 <sup>3)</sup>	135 <sup>4)</sup>	
<b>Product key<sup>1)</sup></b> Single Drive		E94AS□E1454			E94AS□E1724			E94AS□E2024			
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 342 V-0% ... 550 V+0%; 48 Hz-0% ... 65 Hz+0%									
<b>Alternative DC supply</b>	$U_{DC}$ [V]	Not possible									
<b>Rated output current</b>											
2 kHz	$I_N$ [A]	145	160	177	172	195	212	202	240	260	
4 kHz	$I_N$ [A]	145			172			202			
8 kHz	$I_N$ [A]	102			120			131			
16 kHz	$I_N$ [A]										
<b>Max. output current cycle (long)<sup>2)</sup></b>											
Max. output current	$I_{max}$ [A]	218		195	258		233	303		286	
Reduced output current	$I_{re}$ [A]	109		168	129		201	152		247	
Overload time	$t_{ol}$ [s]					60					
Recovery time	$t_{re}$ [s]					120					
<b>Max. output current cycle (short)<sup>2)</sup></b>											
Max. output current	$I_{max}$ [A]	261	218		310	258		364	303		
Reduced output current	$I_{re}$ [A]	109	145		129	180		152	226		
Overload time	$t_{ol}$ [s]					10					
Recovery time	$t_{re}$ [s]					50					

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram

<sup>3)</sup> The column is valid at an ambient temperature of 40 degrees Celsius and with a fixed switching frequency of 2 kHz.



<sup>4)</sup> The column is valid at an ambient temperature of 40 degrees Celsius, with a fixed switching frequency of 2 kHz and a max. mains voltage of AC 440 V.





### Rated data for Single Drives

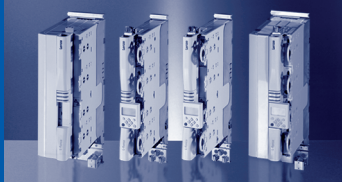
- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

										
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	75	85	95	90	105	110	105	125	135
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E1454			E94AS□E1724			E94AS□E2024		
<b>Rated mains current</b>										
With mains choke / mains filter	$I_{Netz}$ [A]	140			166			195		
Without mains choke / mains filter	$I_{Netz}$ [A]	140			166			195		
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	171			203			239		
<b>Braking unit data</b> <sup>2)</sup>										
Continuous braking power	$P_{BRd}$ [kW]	31.5			36.7			45.1		
Peak braking power	$P_{BRmax}$ [kW]	105.1			122.2			150.2		
Running time	$t_{on}$ [s]				60					
Recovery time	$t_{re}$ [s]				540					
Min. brake resistance	$R$ [Ohm]	5			4.3			3.5		
<b>Power loss</b>	$P_V$ [W]	2100			2200			2600		
<b>Dimensions</b>										
Height	H [mm]	930						1199		
Width	B [mm]				407					
Depth	T [mm]				427					
<b>Mass</b>	m [kg]	54			107			109		
<b>Permissible motor cable length</b> Shielded	l [m]				150					

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram




# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

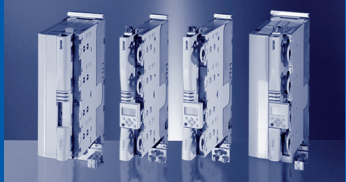
										
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	130	160 <sup>3)</sup>	165 <sup>4)</sup>	150	190 <sup>3)</sup>	210 <sup>4)</sup>	190	235 <sup>3)</sup>	250 <sup>4)</sup>
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E2454			E94AS□E2924			E94AS□E3664		
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 342 V-0% ... 550 V+0%; 48 Hz-0% ... 65 Hz+0%								
<b>Alternative DC supply</b>	$U_{DC}$ [V]	Not possible								
<b>Rated output current</b>										
2 kHz	$I_N$ [A]	245	302	315	292	361	395	366	443	480
4 kHz	$I_N$ [A]	209			250			313		
8 kHz	$I_N$ [A]	160			191			240		
16 kHz	$I_N$ [A]									
<b>Max. output current cycle (long)</b> <sup>2)</sup>										
Max. output current	$I_{max}$ [A]	368		347	438		435	549		528
Reduced output current	$I_{re}$ [A]	184		299	219		375	275		456
Overload time	$t_{ol}$ [s]					60				
Recovery time	$t_{re}$ [s]					120				
<b>Max. output current cycle (short)</b> <sup>2)</sup>										
Max. output current	$I_{max}$ [A]	441	368		526	438		659	549	
Reduced output current	$I_{re}$ [A]	184	275		219	330		275	415	
Overload time	$t_{ol}$ [s]					10				
Recovery time	$t_{re}$ [s]					50				

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram

<sup>3)</sup> The column is valid at an ambient temperature of 40 degrees Celsius and with a fixed switching frequency of 2 kHz.


<sup>4)</sup> The column is valid at an ambient temperature of 40 degrees Celsius, with a fixed switching frequency of 2 kHz and a max. mains voltage of AC 440 V.





### Rated data for Single Drives

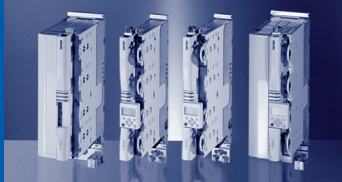
- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

										
Motor power (asynchronous motor, 4-pole)	$P_N$ [kW]	130	160	165	150	190	210	190	235	250
Product key <sup>1)</sup> Single Drive		E94AS□E2454			E94AS□E2924			E94AS□E3664		
Rated mains current										
With mains choke / mains filter	$I_{Netz}$ [A]	237			280			354		
Without mains choke / mains filter	$I_{Netz}$ [A]	237			280			354		
Rated DC-bus current	$I_{DC}$ [A]	290			343			434		
Braking unit data <sup>2)</sup>										
Continuous braking power	$P_{BRd}$ [kW]	56.3			68.6			90.1		
Peak braking power	$P_{BRmax}$ [kW]	187.7			228.5			300.4		
Running time	$t_{on}$ [s]				60					
Recovery time	$t_{re}$ [s]				540					
Min. brake resistance	$R$ [Ohm]	2.8			2.3			1.75		
Power loss	$P_V$ [W]	3300			4100			4900		
Dimensions										
Height	H [mm]				1580					
Width	B [mm]				407					
Depth	T [mm]				427					
Mass	m [kg]				132			161		
Permissible motor cable length Shielded	l [m]				150					

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram




# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

- ▶ The data is valid for operation at 3/PE AC 400 V or DC 565 V.
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→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

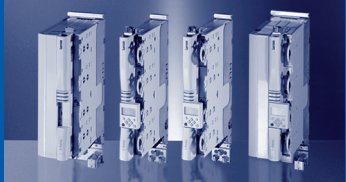
							
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	<b>240</b>	<b>290<sup>3)</sup></b>	<b>315<sup>4)</sup></b>	<b>300</b>	<b>320<sup>3)</sup></b>	<b>345<sup>4)</sup></b>
<b>Product key<sup>1)</sup></b> Single Drive		<b>E94AS□E4604</b>			<b>E94AS□E5724</b>		
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 342 V-0% ... 550 V+0%; 48 Hz-0% ... 65 Hz+0%					
<b>Alternative DC supply</b>	$U_{DC}$ [V]	Not possible					
<b>Rated output current</b>							
2 kHz	$I_N$ [A]	460	550	600	572	610	658
4 kHz	$I_N$ [A]	368			458		
8 kHz	$I_N$ [A]	260			286		
16 kHz	$I_N$ [A]						
<b>Max. output current cycle (long)<sup>2)</sup></b>							
Max. output current	$I_{max}$ [A]	690		660	858		724
Reduced output current	$I_{re}$ [A]	345		570	429		625
Overload time	$t_{ol}$ [s]				60		
Recovery time	$t_{re}$ [s]				120		
<b>Max. output current cycle (short)<sup>2)</sup></b>							
Max. output current	$I_{max}$ [A]	828	690		1030	858	
Reduced output current	$I_{re}$ [A]	345	522		429	550	
Overload time	$t_{ol}$ [s]				10		
Recovery time	$t_{re}$ [s]				50		

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram

<sup>3)</sup> The column is valid at an ambient temperature of 40 degrees Celsius and with a fixed switching frequency of 2 kHz.


<sup>4)</sup> The column is valid at an ambient temperature of 40 degrees Celsius, with a fixed switching frequency of 2 kHz and a max. mains voltage of AC 440 V.





### Rated data for Single Drives

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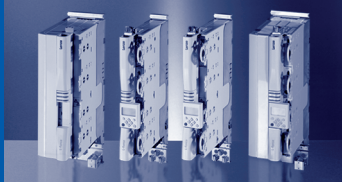
→ Rated data for operation at 3/PE/AC 500 V  
**DS\_9400\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

							
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	240	290	315	300	320	345
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E4604			E94AS□E5724		
<b>Rated mains current</b>							
With mains choke / mains filter	$I_{Netz}$ [A]	444			553		
Without mains choke / mains filter	$I_{Netz}$ [A]	444			553		
<b>Rated DC-bus current</b>							
	$I_{DC}$ [A]	544			677		
<b>Braking unit data</b> <sup>2)</sup>							
Continuous braking power	$P_{BRd}$ [kW]				99		
Peak braking power	$P_{BRmax}$ [kW]	375			438		
Running time	$t_{on}$ [s]	30			28		
Recovery time	$t_{re}$ [s]	270			272		
Min. brake resistance	$R$ [Ohm]	1.4			1.2		
<b>Power loss</b>							
	$P_V$ [W]	6200			7200		
<b>Dimensions</b>							
Height	H [mm]				1559		
Width	B [mm]				568		
Depth	T [mm]				541		
<b>Mass</b>							
	m [kg]	266			278		
<b>Permissible motor cable length</b> Shielded							
	l [m]				150		

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram






# 9400 Servo Drives

## Single Drive


### Rated data for Single Drives

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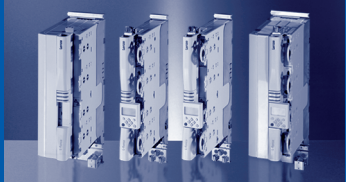
							
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	335	355 <sup>3)</sup>	390 <sup>4)</sup>	370	385 <sup>3)</sup>	420 <sup>4)</sup>
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E6354			E94AS□E6954		
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 342 V-0% ... 550 V+0%; 48 Hz-0% ... 65 Hz+0%					
<b>Alternative DC supply</b>	$U_{DC}$ [V]	Not possible					
<b>Rated output current</b>							
2 kHz	$I_N$ [A]	635	678	745	695	730	800
4 kHz	$I_N$ [A]	508			556		
8 kHz	$I_N$ [A]	318			348		
16 kHz	$I_N$ [A]						
<b>Max. output current cycle (long)</b> <sup>2)</sup>							
Max. output current	$I_{max}$ [A]	953		820	1043		880
Reduced output current	$I_{re}$ [A]	476		708	521		760
Overload time	$t_{ol}$ [s]				60		
Recovery time	$t_{re}$ [s]				120		
<b>Max. output current cycle (short)</b> <sup>2)</sup>							
Max. output current	$I_{max}$ [A]	1143	953		1251	1043	
Reduced output current	$I_{re}$ [A]	476	610		521	653	
Overload time	$t_{ol}$ [s]				10		
Recovery time	$t_{re}$ [s]				50		

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram

<sup>3)</sup> The column is valid at an ambient temperature of 40 degrees Celsius and with a fixed switching frequency of 2 kHz.


<sup>4)</sup> The column is valid at an ambient temperature of 40 degrees Celsius, with a fixed switching frequency of 2 kHz and a max. mains voltage of AC 440 V.





### Rated data for Single Drives

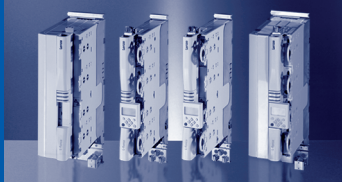
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 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)

							
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	335	355	390	370	385	420
<b>Product key</b> <sup>1)</sup> Single Drive		E94AS□E6354			E94AS□E6954		
<b>Rated mains current</b> With mains choke / mains filter	$I_{Netz}$ [A]	614			672		
Without mains choke / mains filter	$I_{Netz}$ [A]	614			672		
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	752			823		
<b>Braking unit data</b> <sup>2)</sup> Continuous braking power	$P_{BRd}$ [kW]				99		
Peak braking power	$P_{BRmax}$ [kW]				478		
Running time	$t_{on}$ [s]				25		
Recovery time	$t_{re}$ [s]				275		
Min. brake resistance	$R$ [Ohm]				1.1		
<b>Power loss</b>	$P_V$ [W]	7700			8700		
<b>Dimensions</b> Height	H [mm]				1559		
Width	B [mm]				568		
Depth	T [mm]				541		
<b>Mass</b>	m [kg]	300			321		
<b>Permissible motor cable length</b> Shielded	l [m]				150		

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram



## 9400 Servo Drives

### Single Drive accessories

### Installation backplane

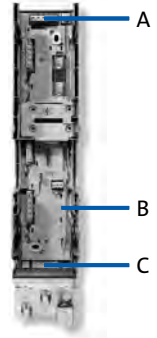
#### Click – the innovative concept

Up to a rated current of 23.5 A the 9400 Servo Drives consist of an axis module and an installation backplane. The backplane can be mounted without the axis module in the control cabinet, thus simplifying installation.

This offers additional advantages in terms of reduced spare part stocking and time savings in the event of drive replacements.

Further features of the installation backplane:

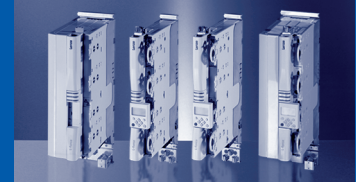
- ▶ A brake module for a 24 V DC 2.5 A brake can optionally be installed
- ▶ Connection options for shieldings of power and control connections



*Installation backplane for Single Drive:  
A: mains connection  
B: brake module (optional)  
C: motor connection*

### Assignment of Single Drive axes and backplanes

Motor power (asynchronous motor, 4-pole)	Mains voltage	Product key		Installation backplane data
		Single Drive	Installation backplane	Design
$P_N$ [kW]	$U_{\text{Netz}}$ [V]			
0.37	3 AC 180 - 550	E94AS□E0024	E94AZPS0034N	Without brake module
			E94AZPS0034HX0051	With brake module
E94AS□E0034		E94AZPS0034N	Without brake module	
		E94AZPS0034HX0051	With brake module	
1.5		E94AS□E0044	E94AZPS0074N	Without brake module
			E94AZPS0074HX0051	With brake module
3		E94AS□E0074	E94AZPS0074N	Without brake module
			E94AZPS0074HX0051	With brake module
5.5		E94AS□E0134	E94AZPS0244N	Without brake module
			E94AZPS0244HX0051	With brake module
7.5		E94AS□E0174	E94AZPS0244N	Without brake module
			E94AZPS0244HX0051	With brake module
11		E94AS□E0244	E94AZPS0244N	Without brake module
			E94AZPS0244HX0051	With brake module



### DC busbar set for Single Drive installation backplane

If the Single Drive axis module is to be run in a DC-bus connection (multi-axis application), this requires retrofitting of the DC busbar system and DC fuses.

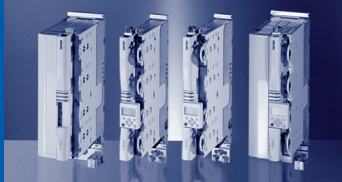
Mechanical coupling is possible via the following components:

- ▶ Power supply module
- ▶ DC input module
- ▶ Single Drive axis modules
- ▶ Multi Drive axis modules

For retrofitting the DC busbar set and the DC fuse have to be installed in the axis module's installation backplane which is provided with the appropriate fixtures.

The DC fuse required is part of the DC busbar set. Spare fuses are not contained in the scope of supply. We recommend the use of the SIBA fuses listed here in the table.

Product key		
Installation backplane	DC busbar system	DC FUSE
E94AZPS0034N	E94AZJA003	SIBA
E94AZPS0034HX0051		5020106.16A
E94AZPS0074N	E94AZJA007	SIBA
E94AZPS0074HX0051		5020106.40A
E94AZPS0244N	E94AZJA024	SIBA
E94AZPS0244HX0051		2028221.100A



## 9400 Servo Drives

### Single Drive accessories





#### Brake modules

An intelligent motor brake logic system is included as standard in the axis modules' software in the form of a function block. The brake modules are available in numerous designs. The optionally integrable brake modules enable a DC 24 V, DC 180 V or DC 205 V brake to be easily connected and this logic to be used.



- ▶ For axis modules up to 23.5 A, the brake module is integrated into the installation backplane.
- ▶ For axis modules above 32 A, the brake module is integrated into the axis modules.

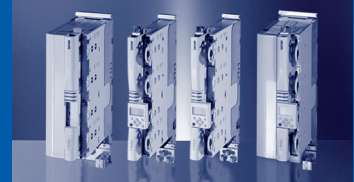


*Brake module, can be integrated into installation backplane*

Design		Features	Product key
<b>Integrable</b>		<b>Brake module</b>	
<b>Brake module DC 24V / 0.3 ... 2.5A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage DC 24V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the installation backplanes, up to 23.5 A</li> </ul>	E94AZHX0051
<b>Brake module DC 24V / 1.0 ... 5.0A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage DC 24V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the axis modules, from 32 A</li> </ul>	E94AZHY0101
<b>Brake module DC 180V / 0.1 ... 0.61A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage AC 400V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the axis modules, from 32 A</li> </ul>	E94AZHY0026
<b>Brake module DC 205V / 0.1 ... 0.75A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage AC 230V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the axis modules, from 32 A</li> </ul>	E94AZHY0025

The external brake modules are provided for DIN rail installation and can be used if axis modules up to 23.5 A require brake voltages of DC 180 V and DC 205 V.

Design		Features	Product key
<b>External</b>		<b>Brake module</b>	
<b>Brake module DC 180V / 0.1 ... 0.75A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage AC 400V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Preconfigured for DIN rail mounting</li> </ul>	E94AZHN0026
<b>Brake module DC 205V / 0.1 ... 0.75A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage AC 230V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Preconfigured for DIN rail mounting</li> </ul>	E94AZHN0025



### Brake resistors

The brake resistor/Single Drive axis module assignment is listed in the following table.



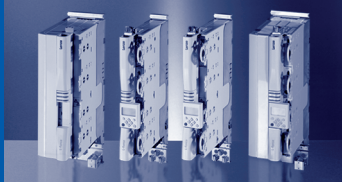
82 ohm brake resistor

Motor power (asynchronous motor, 4-pole)	Mains voltage	Product key		Brake resistor data					
		Single Drive	Brake resistor	Resistance	Continuous power	Thermal capacity	Dimensions	Mass	
$P_N$ [kW]	$U_{Netz}$ [V]			R [Ohm]	P [W]	WK [kWs]	H x B x T [mm]	m [kg]	
0.37	3 AC 180 - 550 1)	E94AS□E0024	ERBP082R200W	82	200	30	320 x 41 x 122	1	
0.75		E94AS□E0034							
1.5		E94AS□E0044		ERBP047R200W	47	400	60 90	400 x 110 x 105	2.3
				ERBS047R400W					
				ERBS047R800W					
3		E94AS□E0074		ERBP047R200W	47	200	30	320 x 41 x 122	1
				ERBS047R400W					
				ERBS047R800W					
5.5		E94AS□E0134		ERBP027R200W	27	200	30	320 x 41 x 122	1
				ERBS027R600W					
				ERBS027R01K2					
7.5		E94AS□E0174		ERBP018R300W	18	300	30	240 x 41 x 122	1.4
				ERBS018R800W					
				ERBS018R02K8					
11		E94AS□E0244		ERBP018R300W	18	300	30	240 x 41 x 122	1.4
				ERBS018R01K2					
				ERBS018R02K8					
15		E94AS□E0324		ERBS018R800W	18	800	120	710 x 110 x 105	4
				ERBS018R01K4					
				ERBG018R04K3					
22	E94AS□E0474		ERBS015R800W	15	800	1500	380 x 736 x 302	4	
			ERBS015R02K4						
			ERBG015R06K2						
30	E94AS□E0594		ERBS015R01K2	15	1200	180	1020 x 110 x 105	5.6	
			ERBG015R03K3						
			ERBG015R10K0						

1) For 230 V mains voltage a different brake resistor assignment applies.

→ Data sheet on brake resistors  
**DS\_9400\_0002**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)





## 9400 Servo Drives

### Single Drive accessories

### Brake resistors

The brake resistor/Single Drive axis module assignment is listed in the following table.



3.5 ohm brake resistor

Motor power (asynchronous motor, 4-pole)	Mains voltage	Product key		Brake resistor data				
		Single Drive	Brake resistor	Resistance	Continuous power	Thermal capacity	Dimensions	Mass
$P_N$ [kW]	$U_{\text{Netz}}$ [V]			R [Ohm]	P [W]	WK [kWs]	H x B x T [mm]	m [kg]
45	3 AC 180 - 550 <sup>1)</sup>	E94AS□E0864	ERBG075D01K9	7.5	1900	285	486 x 236 x 302	9.5
55		E94AS□E1044						
75	3 AC 342-550	E94AS□E1454	ERBG005R02K6	5	2600	390	486 x 326 x 302	12.6
90		E94AS□E1724	ERBG043D03K0	4.3	3000	450		11.8
105		E94AS□E2024	ERBG035D03K3	3.5	3300	495		12.6
130		E94AS□E2454	ERBG028D04K1	2.8	4100	615	486 x 426 x 302	12.8
150		E94AS□E2924	ERBG023D05K6	2.3	5600	840		15.9
190		E94AS□E3664	ERBG035D03K3 <sup>2)</sup>	3.5	3300	495	486 x 326 x 302	12.6
240		E94AS□E4604	ERBG028D04K1 <sup>2)</sup>	2.8	4100	615	486 x 426 x 302	12.8
300		E94AS□E5724						
335		E94AS□E6354	ERBG023D05K6 <sup>2)</sup>	2.3	5600	840		15.9
370		E94AS□E6954						

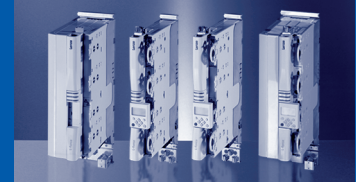
<sup>1)</sup> For 230 V mains voltage a different brake resistor assignment applies.

<sup>2)</sup> Two resistors must be connected in parallel.

→ Data sheet on brake resistors

**DS\_9400\_0002**

Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



### RFI and mains filters

RFI filters and mains filters enable compliance with the interference voltage categories of the European standard EN 61800-3. There a distinction is drawn between category C1 and category C2.

**Category C1** describes the use on public supply networks.

**Category C2** describes the use of drives which are intended to be used for industrial purposes in areas also comprising residential areas.



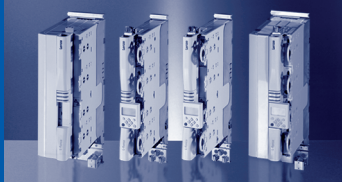
*RFI filter, can be mounted beside or below the axis module*

### RFI filter

RFI filters are capacitive accessory components which can be connected directly upstream of the axis modules. This measure enables compliance with the corresponding conducted noise emission requirements according to EN61800-3.

Motor power (asynchronous motor, 4-pole)	Mains voltage	Product key		RFI filter data					
		Single Drive	RFI filter	Rated current	Power loss	Max. cable length C1	Max. cable length C2	Dimensions	Mass
$P_N$ [kW]	$U_{\text{Netz}}$ [V]			$I_N$ [A]	$P_V$ [W]	$l$ [m]	$l$ [m]	H x B x T [mm]	m [kg]
0.37	3 AC 180 - 550	E94AS□E0024	E94AZRS0044	3.5	4	0	50	522 x 60 x 60	1.8
0.75		E94AS□E0034							
1.5		E94AS□E0044	E94AZRS0104	10	8				
3		E94AS□E0074							
5.5		E94AS□E0134	E94AZRS0294	29	22			522 x 120 x 60	3.6
7.5		E94AS□E0174							
11		E94AS□E0244							
15		E94AS□E0324	E94AZRS0544	54	50	50	100	670 x 201 x 60	9
22		E94AS□E0474							
30		E94AS□E0594							
45		E94AS□E0864	E94AZRS0954	95	70	780 x 261 x 60	13		
55		E94AS□E1044							

→ Data sheet on RFI filters  
**DS\_9400\_0003**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



## 9400 Servo Drives

### Single Drive accessories

### Mains filter

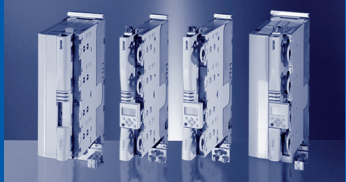
A mains filter is a combination of mains choke and RFI filter in one housing. It reduces line-bound noise emission into the mains, thus ensuring that the line-bound interference voltage is reduced to a permissible level according to EN61800-3.



*Mains filter, can be mounted beside or below the axis module*

Motor power	Mains voltage	Product key		Mains filter data					
(asynchronous motor, 4-pole)		Single Drive	Mains filter	Rated current	Voltage drop	Max. cable length C1	Max. cable length C2	Dimensions	Mass
$P_N$ [kW]	$U_{\text{Netz}}$ [V]			I [A]	U [V]	l [m]	l [m]	H x B x T [mm]	m [kg]
0.37	3 AC 180 - 550	E94AS□E0024	E94AZMS0034	3.2	10	25	50	522 x 60 x 60	3.2
0.75		E94AS□E0034							
1.5		E94AS□E0044	E94AZMS0094	9	7.4	100	522 x 90 x 60	5.2	
3		E94AS□E0074							
5.5		E94AS□E0134							
7.5		E94AS□E0174	E94AZMS0184	18	7.4			522 x 120 x 60	8.4
11		E94AS□E0244	E94AZMS0314	31	7.3				8.8

→ Data sheet on mains filters  
**DS\_9400\_0004**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



### Sinusoidal filter

A sinusoidal filter in the motor cable limits the rate of rise of voltage and the capacitive charge/discharge currents that occur during inverter operation. In combination with a line filter, the EMC requirements of the limit class C2 for conducted noise emissions are still met, even if longer shielded or even unshielded motor cables are used.

Application range:

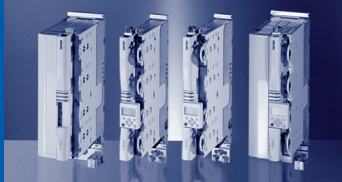
- ▶ Only use a sinusoidal filter with 0 to 550 V standard asynchronous motors
- ▶ Only operate with V/f or V/f<sup>2</sup>-characteristic control
- ▶ Fix the switching frequency to the stated value
- ▶ Limit the output frequency of the 9400 Servo Drive to a maximum of 150 Hz



*Sinusoidal filter*

Motor power	Mains voltage	Product key				Data for sinusoidal filters				
(asynchronous motor, 4-pole)		Single Drive	RFI filter	Mains filter	Sinusoidal filter	Rated current	In-ductance	Switching frequency	Max. cable length C2, shielded	Max. cable length C2, unshielded
P <sub>N</sub> [kW]	U <sub>Netz</sub> [V]					I <sub>N</sub> [A]	L [mH]	f <sub>ch</sub> [kHz]	l [m]	l [m]
0.37	3 AC 180 - 550	E94AS□E0024		E94AZMS0034	EZS3-004A200	4	11	4; 8	100	300
0.75		E94AS□E0034								
1.5		E94AS□E0044								
3		E94AS□E0074								
5.5		E94AS□E0134								
7.5		E94AS□E0174								
11		E94AS□E0244	E94AZMS0314	EZS3-037A200	37	1.7				
15		E94AS□E0324								
22		E94AS□E0474	E94AZRS0544		EZS3-048A200	48	1.2		150	
30		E94AS□E0594								
45		E94AS□E0864	E94AZRS0954		EZS3-061A200	61	1			
55		E94AS□E1044								
					EZS3-072A200	72	0.95			
					EZS3-115A200	115	0.7			
					EZS3-150A200	150	0.5	2; 4		





→ Data sheet on sinusoidal filters  
**DS\_ZB\_EZS3\_0001**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)





## 9400 Servo Drives Multi Drive

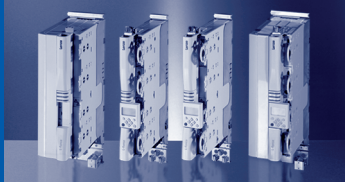
### Rated data for Multi Drives

- ▶ The data is valid for operation at DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

					
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	<b>0.37</b>	<b>0.75</b>	<b>1.5</b>	<b>3</b>
<b>Product key</b> <sup>1)</sup> Multi Drive		<b>E94AM□E0024</b>	<b>E94AM□E0034</b>	<b>E94AM□E0044</b>	<b>E94AM□E0074</b>
<b>DC supply</b>	$U_{DC}$ [V]	DC 260 - 0% ... 775 V + 0%			
<b>Rated output current</b>					
2 kHz	$I_N$ [A]	1.9	3.1	5	8.8
4 kHz	$I_N$ [A]	1.9	3.1	5	8.8
8 kHz	$I_N$ [A]	1.5	2.5	4	7
16 kHz	$I_N$ [A]	1.1	1.9	3	5.3
<b>Max. output current cycle (long)</b> <sup>2)</sup>					
Max. output current	$I_{max}$ [A]	2.8	4.7	7.5	13.1
Reduced output current	$I_{re}$ [A]	1.4	2.3	3.8	6.6
Overload time	$t_{ol}$ [s]	60			
Recovery time	$t_{re}$ [s]	120			
<b>Max. output current cycle (short)</b> <sup>2)</sup>					
Max. output current	$I_{max}$ [A]	6	10	16	21
Reduced output current	$I_{re}$ [A]	1.4	2.3	3.8	6.6
Overload time	$t_{ol}$ [s]	0.5			
Recovery time	$t_{re}$ [s]	4.5			





<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules


<sup>2)</sup> →  24 - See diagram

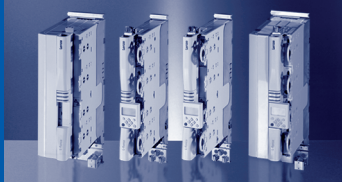


### Rated data for Multi Drives

- ▶ The data is valid for operation at DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

					
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	0.37	0.75	1.5	3
<b>Product key</b> <sup>1)</sup> Multi Drive		E94AM□E0024	E94AM□E0034	E94AM□E0044	E94AM□E0074
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	2.6	4.3	6.7	12.1
<b>Power loss</b>	$P_V$ [W]	100	120	150	190
<b>Dimensions</b>		350 (with 481 installation backplane)			
Height	H [mm]	350 (with 481 installation backplane)			
Width	B [mm]	60			90
Depth	T [mm]	288			
<b>Mass</b>	m [kg]	4			5.3
<b>Permissible motor cable length</b> Shielded	l [m]	50			100

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules


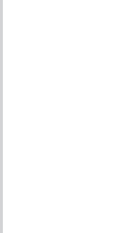





# 9400 Servo Drives


## Multi Drive

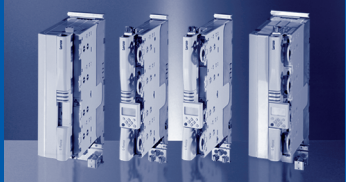
### Rated data for Multi Drives

- ▶ The data is valid for operation at DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

					
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	<b>4</b>	<b>5.5</b>	<b>7.5</b>	<b>11</b>
<b>Product key</b> <sup>1)</sup> Multi Drive		<b>E94AM□E0094</b>	<b>E94AM□E0134</b>	<b>E94AM□E0174</b>	<b>E94AM□E0244</b>
<b>DC supply</b>	$U_{DC}$ [V]	DC 260 - 0% ... 775 V + 0%			
<b>Rated output current</b>					
2 kHz	$I_N$ [A]	11.7	16.3	20.6	29.4
4 kHz	$I_N$ [A]	11.7	16.3	20.6	29.4
8 kHz	$I_N$ [A]	9.3	13	16.5	23.5
16 kHz	$I_N$ [A]	7	9.8	12.4	17.6
<b>Max. output current cycle (long)</b> <sup>2)</sup>					
Max. output current	$I_{max}$ [A]	17.5	24.4	30.9	44.1
Reduced output current	$I_{re}$ [A]	8.8	12.2	15.5	22.1
Overload time	$t_{ol}$ [s]	60			
Recovery time	$t_{re}$ [s]	120			
<b>Max. output current cycle (short)</b> <sup>2)</sup>					
Max. output current	$I_{max}$ [A]	28	39	49.5	70.5
Reduced output current	$I_{re}$ [A]	8.8	12.2	15.5	22.1
Overload time	$t_{ol}$ [s]	0.5			
Recovery time	$t_{re}$ [s]	4.5			





<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules


<sup>2)</sup> →  24 - See diagram



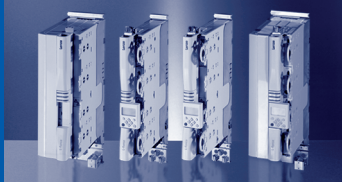
## Rated data for Multi Drives

- ▶ The data is valid for operation at DC 565 V.
- ▶ Unless otherwise specified, the data refers to the default setting.

					
<b>Motor power</b> (asynchronous motor, 4-pole)	$P_N$ [kW]	4	5.5	7.5	11
<b>Product key</b> <sup>1)</sup> Multi Drive		E94AM□E0094	E94AM□E0134	E94AM□E0174	E94AM□E0244
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	15.4	20.6	25.7	35.5
<b>Power loss</b>	$P_V$ [W]	230	280	320	420
<b>Dimensions</b>			350 (with 481 installation backplane)		
Height	H [mm]				
Width	B [mm]	90		120	
Depth	T [mm]			288	
<b>Mass</b>	m [kg]	5.3		8.1	
<b>Permissible motor cable length</b> Shielded	l [m]			100	

<sup>1)</sup> →  10 - see product key – illustration shows accessories / modules










## 9400 Servo Drives Multi Drive

### Rated data for power supply modules

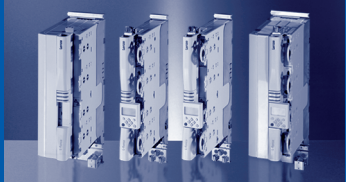
► The data is valid for operation at 3/PE AC 400 V.

					
Product key <sup>1)</sup> Power supply modules		E94APNE0104	E94APNE0364	E94APNE1004	E94APNE2454
<b>Rated power</b>					
With mains filter	$P_{NDC}$ [kW]	4.9	17.5	48.6	119
Without mains filter	$P_{NDC}$ [kW]	3.6	13	36.2	88.6
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 180 V-0% ... 550 V+0%; 45 Hz-0% ... 65 Hz+0%			
<b>Rated mains current</b>	$I_{Nnetz}$ [A]	8	29	82	200
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	10	36	100	245
<b>Max. DC-bus current cycle (long)<sup>2)</sup></b>					
Max. DC-bus current	$I_{DCmax}$ [A]	15	54	150	368
Reduced DC-bus current	$I_{DCre}$ [A]	7.5	27	75	183.5
Overload time	$t_{ol}$ [s]			60	
Recovery time	$t_{re}$ [s]			120	
<b>Max. output power (long)<sup>3)</sup></b>	$P_{DCmax}$ [kW]	7.35	26.25	72.9	179
<b>Max. DC-bus current cycle (short)<sup>2)</sup></b>					
Max. DC-bus current	$I_{DCmax}$ [A]	40	108	200	368
Reduced DC-bus current	$I_{DCre}$ [A]	7.5	27	75	183.5
Overload time	$t_{ol}$ [s]			0.5	
Recovery time	$t_{re}$ [s]			4.5	
<b>Max. output power (short)<sup>3)</sup></b>	$P_{DCmax}$ [kW]	19.6	52.5	146	357
<b>Braking unit data<sup>2)</sup></b>					
Continuous braking power	$P_{BRd}$ [kW]	2.6	8.7	17	30.3
Peak braking power	$P_{BRmax}$ [kW]	19.5	43.8	105.1	187.7
Running time	$t_{on}$ [s]			0.5	
Recovery time	$t_{re}$ [s]	3.8	2.5		3.1
Min. brake resistance	$R$ [Ohm]	27	12	5	2.8
<b>Power loss</b>	$P_V$ [W]	55	110	230	550
<b>Dimensions</b>					
Height	H [mm]	350 (with 461.5 backplane)			510
Width	B [mm]	60	120	210	390
Depth	T [mm]	288			
<b>Mass</b>	m [kg]	2.6	5.3	13.5	28.5

<sup>1)</sup> →  12 - see product key – illustration shows accessories / modules

<sup>2)</sup> →  24 - See diagram

<sup>3)</sup> Mains filter required; if no mains filter is installed, the stated values for  $P_{DCmax}$  decrease



### Rated data for regenerative power supply modules

▶ The data is valid for operation at 3/PE AC 400 V.

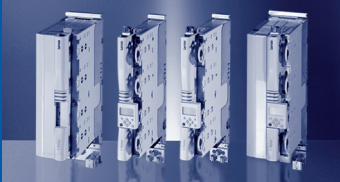
▶ Mains filter required, see "mains filter" accessory page



		E94ARNE0134		E94ARNE0244	
		Supply	Power recovery	Supply	Power recovery
<b>Product key</b> <sup>1)</sup> Regenerative power supply modules					
<b>Operating mode</b>					
<b>Rated power</b> With mains filter	$P_{NDC}$ [kW]	15	7.5	27	13.5
<b>Mains voltage range</b>	$U_{Netz}$ [V]	3/PE AC 180 V-0% ... 550 V+0%; 45 Hz-0% ... 65 Hz+0%			
<b>Rated mains current</b>	$I_{Netz}$ [A]	26	13	47	23.5
<b>Rated DC-bus current</b>	$I_{DC}$ [A]	32	16	57	29
<b>Max. DC-bus current cycle (long)</b> <sup>2)</sup>					
Max. DC-bus current	$I_{DCmax}$ [A]	48	24	86	44
Reduced DC-bus current	$I_{DCre}$ [A]	20	9.8	35	18
Overload time	$t_{ol}$ [s]			60	
Recovery time	$t_{re}$ [s]			120	
<b>Max. output power (long)</b>	$P_{DCmax}$ [kW]	22.4	11.2	40.5	20.2
<b>Max. DC-bus current cycle (short)</b> <sup>2)</sup>					
Max. DC-bus current	$I_{DCmax}$ [A]	96	48	171	87
Reduced DC-bus current	$I_{DCre}$ [A]	20	9.8	35	18
Overload time	$t_{ol}$ [s]			0.5	
Recovery time	$t_{re}$ [s]			4.5	
<b>Max. output power (short)</b>	$P_{DCmax}$ [kW]	44.9	22.4	81.1	40.5
<b>Braking unit data</b> <sup>2)</sup>					
Continuous braking power	$P_{BRd}$ [kW]	4.7		9.3	
Peak braking power	$P_{BRmax}$ [kW]	19.5		29.2	
Running time	$t_{on}$ [s]	0.8		1.1	
Recovery time	$t_{re}$ [s]	4.2		3.9	
Min. brake resistance	$R_{BRmin}$ [Ohm]	27		18	
<b>Power loss</b>	$P_V$ [W]	150	110	230	170
<b>Dimensions</b>					
Height	H [mm]	350 (with 481 installation backplane)			
Width	B [mm]	120			
Depth	T [mm]	288			
<b>Mass</b>	m [kg]	5.3			

<sup>1)</sup> → 12 - see product key – illustration shows accessories / modules

<sup>2)</sup> → 24 - See diagram



## 9400 Servo Drives

### Multi Drive accessories

### Installation backplane

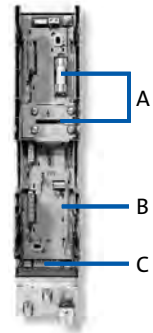
#### Click – the innovative concept

Up to a rated current of 23.5 A the 9400 Servo Drives consist of an axis module and an installation backplane. The backplane can be mounted without the axis module in the control cabinet, thus simplifying installation.

This offers additional advantages in terms of reduced spare part stocking and time savings in the event of drive replacements.

Further features of the installation backplane:

- ▶ A brake module for a 24 V DC 2.5 A brake can optionally be installed
- ▶ Connection options for shieldings of power and control connections



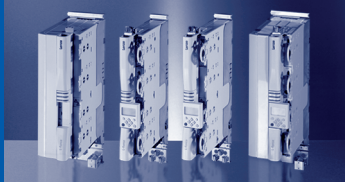
*Multi Drive installation backplane:  
A: DC fuse and DC busbar  
B: brake module (optional)  
C: motor connection*

### Assignment of Multi Drive axes and backplanes

Motor power (asynchronous motor, 4-pole)	Mains voltage	Product key		Installation backplane data
$P_N$ [kW]	$U_{\text{Netz}}$ [V]	Multi Drive	Installation backplane	Design
0.37	3 AC 180 - 550	E94AM□E0024	E94AZPM0044N	Without brake module
			E94AZPM0044HX0051	With brake module
E94AM□E0034		E94AZPM0044N	Without brake module	
		E94AZPM0044HX0051	With brake module	
1.5		E94AM□E0044	E94AZPM0044N	Without brake module
			E94AZPM0044HX0051	With brake module
3		E94AM□E0074	E94AZPM0094N	Without brake module
			E94AZPM0094HX0051	With brake module
4		E94AM□E0094	E94AZPM0094N	Without brake module
			E94AZPM0094HX0051	With brake module
5.5		E94AM□E0134	E94AZPM0244N	Without brake module
			E94AZPM0244HX0051	With brake module
7.5		E94AM□E0174	E94AZPM0244N	Without brake module
			E94AZPM0244HX0051	With brake module
11	E94AM□E0244	E94AZPM0244N	Without brake module	
		E94AZPM0244HX0051	With brake module	

### Assignment of power supply modules and regenerative power supply modules and backplanes

Rated power	Mains voltage	Product key		
With mains filter		Power supply modules	Regenerative power supply modules	Installation backplane
$P_{\text{NDC}}$ [kW]	$U_{\text{Netz}}$ [V]			
4.9	3 AC 180 - 550	E94APNE0104		E94AZPP0104
17.5		E94APNE0364		E94AZPP0364
15			E94ARNE0134	
27			E94ARNE0244	



## Brake modules

An intelligent motor brake logic system is included as standard in the axis modules' device software in the form of a function block.


The brake modules are available in numerous designs.

The optionally integrable brake module enables a DC 24 V brake to be easily connected and this logic to be used.



- ▶ For axis modules up to 23.5 A, the DC 24 V brake module is integrated into the installation backplane.

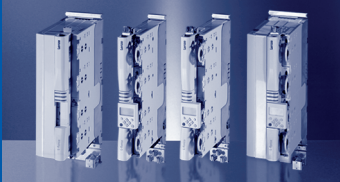


*Brake module, can be integrated into installation backplane*

Design		Features	Product key
<b>Integrable</b>		<b>Brake module</b>	
<b>Brake module DC 24V / 0.3 ... 2.5A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage DC 24V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Can be integrated into the installation backplanes, up to 23.5 A</li> </ul>	E94AZHX0051

The external brake modules are provided for DIN rail installation and can be used if axis modules up to 23.5 A require brake voltages of DC 180 V and DC 205 V.

Design		Features	Product key
<b>External</b>		<b>Brake module</b>	
<b>Brake module DC 180V / 0.1 ... 0.75A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage AC 400V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Preconfigured for DIN rail mounting</li> </ul>	E94AZHN0026
<b>Brake module DC 205V / 0.1 ... 0.75A</b>		<ul style="list-style-type: none"> <li>▶ External supply of supply voltage AC 230V</li> <li>▶ Monitoring of power supply and brake cable for open circuit and short circuit</li> <li>▶ Polarity reversal protection of supply voltage</li> <li>▶ Preconfigured for DIN rail mounting</li> </ul>	E94AZHN0025



# 9400 Servo Drives

## Multi Drive accessories

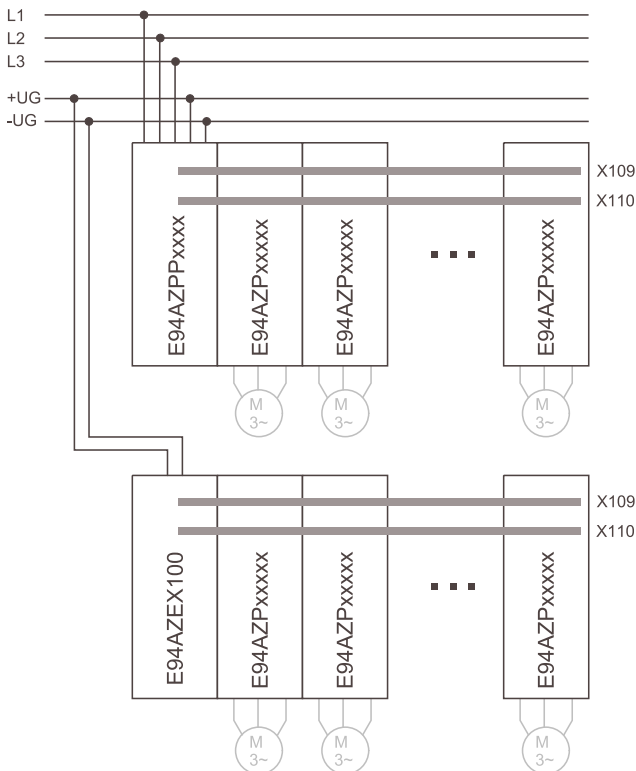
### DC input module

Via a DC input module, an axis module interconnection can be supplied with power from a central DC source (power supply module, Single Drive axis modules, Multi Drive axis modules). This is, for instance, required if a drive system with a multi-level structure installed in a control cabinet is to be supplied via a central DC power supply unit. The rated current of the DC input module is defined to be 100 A (DC). The DC input module can be connected at the top or bottom offering great flexibility when integrating it into the system wiring. Especially for multi-row axis module mounting, optimum connection is thus possible.

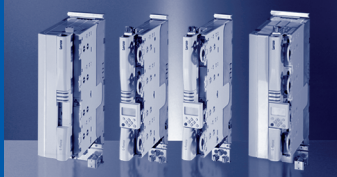


DC input module  
100 A

Design	Product key	Dimensions	Mass
	Input module		
		H x B x T [mm]	m [kg]
DC input module 100 A	E94AZEX100	422 x 60 x 95	0.9



Wiring example for multi-row mounting of axis modules



### Brake resistors

The assignment of brake resistances to the supply and regenerative power supply modules is shown in the following tables.



27 ohm brake resistor

### Brake resistors for power supply modules

Rated power	Mains voltage	Product key		Brake resistor data				
With mains filter		Power supply modules	Brake resistor	Resistance	Continuous power	Thermal capacity	Dimensions	Mass
$P_{NDC}$ [kW]	$U_{Netz}$ [V]			R [Ohm]	P [W]	WK [kWs]	H x B x T [mm]	m [kg]
4.9	3 AC 180 - 550 <sup>1)</sup>	E94APNE0104	ERBP027R200W	27	200	30	320 x 41 x 122	1
			ERBS027R600W		600	90	550 x 110 x 105	3.1
			ERBS027R01K2		1200	180	1020 x 110 x 105	5.6
17.5		E94APNE0364	ERBG012R01K9	12	1900	285	486 x 236 x 302	9.5
			ERBG012R05K2		5200	780	486 x 426 x 302	15.1
48.6		E94APNE1004	ERBG005R02K6	5	2600	390	486 x 326 x 302	12.6
119	E94APNE2454	ERBG028D04K1	2.8	4100	615	486 x 426 x 302	12.8	

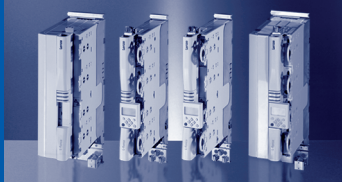
<sup>1)</sup> For 230 V mains voltage a different brake resistor assignment applies.

### Brake resistances for regenerative power supply modules

Rated power	Mains voltage	Product key		Brake resistor data				
		Regenerative power supply modules	Brake resistor	Resistance	Continuous power	Thermal capacity	Dimensions	Mass
$P_{NDC}$ [kW]	$U_{Netz}$ [V]			R [Ohm]	P [W]	WK [kWs]	H x B x T [mm]	m [kg]
15	3 AC 180 - 550 <sup>2)</sup>	E94ARNE0134	ERBP027R200W	27	200	30	320 x 41 x 122	1
			ERBS027R600W		600	90	550 x 110 x 105	3.1
			ERBS027R01K2		1200	180	1020 x 110 x 105	5.6
27		E94ARNE0244	ERBP018R300W	18	300	30	240 x 41 x 122	1.4
			ERBS018R01K2		1200	180	1020 x 110 x 105	5.6
			ERBS018R02K8		2800	420	1110 x 200 x 105	12

<sup>2)</sup> For 230 V mains voltage a different brake resistor assignment applies.

→ Data sheet on brake resistors  
**DS\_9400\_0002**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



## 9400 Servo Drives

### Multi Drive accessories

### RFI and mains filters

RFI filters and mains filters enable compliance with the interference voltage categories of the European standard EN 61800-3. There a distinction is drawn between category C1 and category C2.

**Category C1** describes the use on public supply networks.

**Category C2** describes the use of drives which are intended to be used for industrial purposes in areas also comprising residential areas.

For Multi Drives external filters must be used to comply with the EMC Directive.



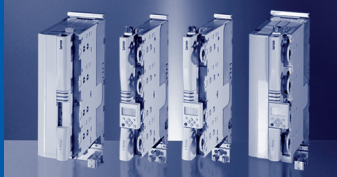
*RFI filter, can be mounted beside the power supply module*

### RFI filter

RFI filters are capacitive accessory components which can be connected directly upstream of the power supply modules. This measure enables compliance with the corresponding conducted noise emission requirements according to EN 61800-3

Rated power	Mains voltage	Product key		RFI filter data				
		Power supply modules	RFI filter	Rated current	Power loss	Max. cable length Reference group C2	Dimensions	Mass
$P_{NDC}$ [kW]	$U_{Netz}$ [V]			$I_N$ [A]	$P_V$ [W]		H x B x T [mm]	m [kg]
3.6	3 AC 180 - 550	E94APNE0104	E94AZRP0084	8	20	6 axes of 10 m each	485 x 60 x 261	4.2
13		E94APNE0364	E94AZRP0294	29	50			4.5
36.2		E94APNE1004	E94AZRP0824	82	80		490 x 209 x 272	18.5
88.6		E94APNE2454	E94AZRP2004	200	150			21

→ Data sheet on RFI filters  
**DS\_9400\_0003**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)



### Mains filter

A mains filter is a combination of mains choke and RFI filter in one housing. It reduces line-bound noise emission into the mains, thus ensuring that the line-bound interference voltage is reduced to a permissible level according to EN61800-3.



*Mains filter, can be mounted beside the power supply module*

### Mains filters for power supply modules

Rated power	Mains voltage	Product key		Mains filter data				
With mains filter		Power supply modules	Mains filter	Rated current	Voltage drop	Max. cable length Reference group C2	Dimensions	Mass
$P_{NDC}$ [kW]	$U_{Netz}$ [V]			I [A]	U [V]		H x B x T [mm]	m [kg]
4.9	3 AC 180 - 550	E94APNE0104	E94AZMP0084	8	10	10 axes of 50 m each	485 x 90 x 261	8.6
17.5		E94APNE0364	E94AZMP0294	29	7.3		485 x 120 x 261	16
48.6		E94APNE1004	E94AZMP0824	82	6.4		490 x 270 x 272	29
119		E94APNE2454	E94AZMP2004	200	6.3		490 x 330 x 272	51.5



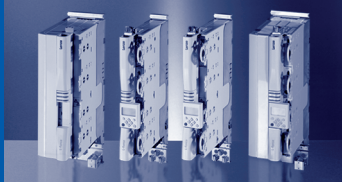
*Mains filter, can be mounted beside the regenerative power supply module*

### Mains filters for regenerative power supply modules

Rated power	Mains voltage	Product key		Mains filter data				
With mains filter		Regenerative power supply modules	Mains filter	Rated current	Voltage drop	Max. cable length Reference group C2	Dimensions	Mass
$P_{NDC}$ [kW]	$U_{Netz}$ [V]			I [A]	U [V]		H x B x T [mm]	m [kg]
15	3 AC 180 - 550	E94ARNE0134	E94AZMR0264SDB	26	6.3	6 axes of 10 m each	485 x 149 x 272	25
			E94AZMR0264LDB			10 axes of 50 m each		26
27		E94ARNE0244	E94AZMR0474SDB	47	6.2	6 axes of 10 m each	485 x 209 x 272	36
			E94AZMR0474LDB			10 axes of 50 m each		37

→ Data sheet on mains filters  
**DS\_9400\_0004**  
 Available for download at [www.lenze.de/dsc](http://www.lenze.de/dsc)





### 24 V power supply units

Multi-axis applications with Multi Drive axis modules require an external power supply unit to feed the control electronics. Depending on the number of axis modules, power supply units with a rated current of 5, 10 or 20 A at a voltage supply of 1 x AC 230 V or 3 x AC 400 V can be selected here. Single Drive axis modules generally do not require the use of the power supply unit. If, however, a separate power supply of control electronics and power section is needed for a single-axis application, the same power supply units can be used.



24 V power supply unit

### Rated data

Product key		EZV1200-000	EZV2400-000	EZV4800-000	EZV1200-001	EZV2400-001	EZV4800-001
Mains voltage	$U_{\text{Netz}}$ [V]	1 AC 230			3 AC 400		
Rated mains current	$I_{\text{Netz}}$ [A]	0.84	1.2	2.3	0.34	0.57	1
Output voltage	$U_{\text{DC}}$ [V]	DC 22.5 ... 28.5					
Rated output current	$I_{\text{N}}$ [A]	5	10	20	5	10	20
Dimensions							
Height	H [mm]	130					
Width	B [mm]	55	85	157	73	85	160
Depth	T [mm]	125					
Mass	m [kg]	0.8	1.24	2.48	0.95	1.1	1.93

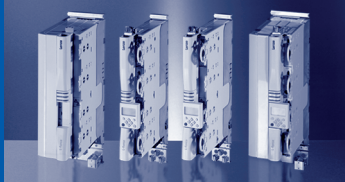
### CAN bus connector

The connector is used to connect the CAN to those Lenze drives which are provided with a Sub-D connection for the CAN bus. An integrated CAN terminating resistor can be switched on/off. Internal spring terminals make the use of special mounting tools superfluous. The switch setting can be read from two sides.

Design	Product key
CAN bus connector "switch"	EWZ0046



CAN bus connector



### USB diagnostic adapter


Diagnostics can be performed via a PC by using the USB diagnostic adapter. A connecting cable, which can be connected to the PC's USB interface, is supplied together with the adapter.

Connecting cables for connecting the USB diagnostic adapter to the axis module can be ordered separately. These are available in lengths of 2.5 m, 5 m or 10 m.

The software drivers for the adapter are automatically installed together with the Lenze software (e.g. L-force Engineer).

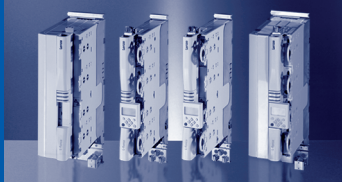


*USB diagnostic adapter with cable to connect to the PC*

Design	Features	Slot	Product key
	<b>USB diagnostic adapter</b>		
USB diagnostic adapter	 <ul style="list-style-type: none"> <li>▶ Input-side voltage supply via USB connection on PC</li> <li>▶ Output-side voltage supply via diagnostic interface of the inverter</li> <li>▶ Diagnostic LED</li> <li>▶ Electrical isolation of PC and inverter</li> <li>▶ Hot-pluggable</li> <li>▶ Can also be used for 8400 Inverter Drives</li> <li>▶ Supported operating systems: Microsoft® Windows® 2000/XP</li> </ul>	DIAG	E94AZCUS

### Accessories for the USB diagnostic adapter

Design	Features	Product key
	<b>Connecting cable for USB diagnostic adapter</b>	
Connection cable	▶ Length: 2.5 m	EWL0070
	▶ Length: 5 m	EWL0071
	▶ Length: 10 m	EWL0072




## 9400 Servo Drives Accessories

### Keypad X400


Local parameter setting and diagnostics can be performed very easily with the keypad. Data available in the device can be accessed quickly via structured menus and a plain text display. The language selection feature means that the keypad can be used around the world. The keypad is attached to the front of the axis module.

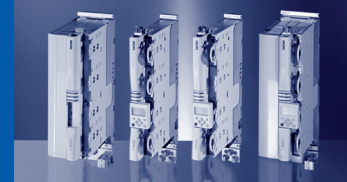


Keypad X400

Design	Features	Slot	Product key
	<b>Keypad</b>		
Keypad X400	 <ul style="list-style-type: none"> <li>▶ Menu-driven diagnostics and parameter setting</li> <li>▶ Graphics display with background lightning for clear presentation of information</li> <li>▶ 4 navigation keys, 2 context-sensitive keys</li> <li>▶ Adjustable RUN/STOP function</li> <li>▶ Hot-pluggable</li> <li>▶ Can also be used for 8400 Inverter Drives</li> </ul>	DIAG	EZAEBK1001

### Diagnosis terminal X400

Design	Features	Slot	Product key
	<b>Diagnosis terminal X400</b>		
Diagnosis terminal X400	 <ul style="list-style-type: none"> <li>▶ X400 keypad in a robust housing</li> <li>▶ Also suitable for installation in the control cabinet door</li> <li>▶ Menu navigation</li> <li>▶ Graphics display with background lightning for clear presentation of information</li> <li>▶ 4 navigation keys, 2 context-sensitive keys</li> <li>▶ Adjustable RUN/STOP function</li> <li>▶ Hot-pluggable</li> <li>▶ Incl. 2.5 m cable</li> <li>▶ IP20 enclosure, IP65 for control cabinet installation on front face</li> <li>▶ Can also be used for 8400 Inverter Drives</li> </ul>	DIAG	EZAEBK2001



### Shield mounting kits for motor cable

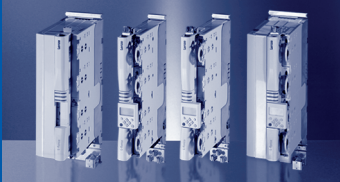
The motor cable shielding can be connected to the shield plates of the installation backplanes or axis modules. To simplify the wiring, additional shield supports can be fitted to the shield plates. The shield support can easily be attached to a fixture on the shield plate and the connection cable just has to be passed through. For larger axis modules the shield support is part of the shield plate.

Product key		Shield mounting
Single Drive	Multi Drive	
	E94AM□E0024	E94AZJS003
E94AS□E0024		
	E94AM□E0034	
E94AS□E0034		E94AZJS007
	E94AM□E0044	
E94AS□E0044		
	E94AM□E0074	E94AZJS024
E94AS□E0074		
	E94AM□E0094	
	E94AM□E0134	E94AZJS024
E94AS□E0134		
	E94AM□E0174	
E94AS□E0174		
	E94AM□E0244	
E94AS□E0244		

### Further accessories

By way of supplementing the 9400 Servo Drives, Lenze offers a wide range of additional automation components. These components are not listed in this product catalogue, but in Lenze's PC-based Automation catalogue. Specifically, this includes the following components:

- ▶ Remote maintenance components
- ▶ I/O systems
- ▶ Human machine interfaces
- ▶ System bus adapters



# 9400 Servo Drives Moduls

## Overview of modules

So that they can be adjusted to meet machine requirements, the 9400 Servo Drives and the regenerative power supply modules can be aligned with up to four different modules.

The following modules are available:





- ▶ Memory modules (module slot MMI) required for operation,
- ▶ safety modules (module slot MSI) required for operation
- ▶ extension modules (module slot MXI 1 and/or MXI 2)

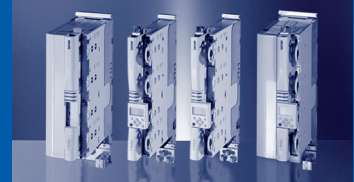
The following tables show the modules available for the 9400 Servo Drives and the regenerative power supply modules.







*Axis module with module slots MXI, MMI and MSI*

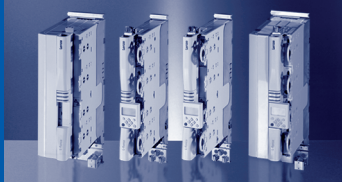
## Memory module

Module		Product key	Design		
Module slot	Module designation		StateLine	HighLine	Regenerative power supply module
MMI	 Memory module MM110	E94AYM11	Standard		
MMI	 Memory module MM220	E94AYM22		Standard	Standard
MMI	 Memory module MM330	E94AYM33		Option	
MMI	 Memory module MM430	E94AYM43		Option	













## Safety module

Module		Product key	Design			
Module slot		Module designation		StateLine	HighLine	Regenerative power supply module
MSI		Safety module SM0	E94AYAA	Standard	Standard	Standard
MSI		Safety module SM100	E94AYAB	Option	Option	
MSI		Safety module SM300	E94AYAD		Option	
MSI		Safety module SM301	E94AYAE	Option	Option	



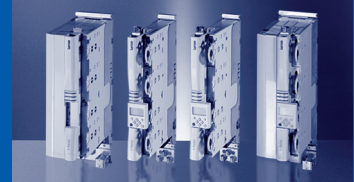
# 9400 Servo Drives Moduls

## Extension modules

Module slot	Module		Product key	Design		
		Module designation		StateLine <sup>1)</sup>	HighLine <sup>2)</sup>	Regenerative power supply module <sup>2)</sup>
MXI		Extension module Digital frequency	E94AYFLF		Option	
MXI		Communication module CANopen	E94AYCCA	Option	Option	Option
MXI		Communication module DeviceNet	E94AYCDN		Option	
MXI		Communication module EtherCAT	E94AYCET	Option	Option	
MXI		Communication module Ethernet	E94AYCEN		Option	Option
MXI		Communication module ETHERNET Powerlink MN/CN	E94AYCEP		Option	
MXI		Communication module ETHERNET Powerlink CN	E94AYCEC		Option	
MXI		Communication module PROFIBUS	E94AYCPM		Option	Option
MXI		Communication module PROFINET	E94AYCER		Option	

<sup>1)</sup> Number of available extension module slots: 1

<sup>2)</sup> Number of available extension module slots: 2



## Assignment of extension modules and module slots (HighLine)

Two module slots on the 9400 HighLine Servo Drives are included for extensions. The following table lists the possible combinations.

MXI 1	E94AYFLF	E94AYCCA	E94AYCDN	E94AYCET	E94AYCEN	E94AYCEP	E94AYCEC	E94AYCPM	E94AYCER
<b>MXI 2</b>									
E94AYFLF		•	•	•	•	•	•	•	•
E94AYCCA	•			•	•	•	•	•	•
E94AYCDN	•				•	•	•	•	•
E94AYCET	•	•			•				•
E94AYCEN	•	•	•	•		•	•	•	•
E94AYCEP	•	•	•		•			•	•
E94AYCEC	•	•	•		•				
E94AYCPM <sup>1)</sup>	•	•	•		•	•			•
E94AYCER <sup>1)</sup>	•	•	•	•	•	•		•	

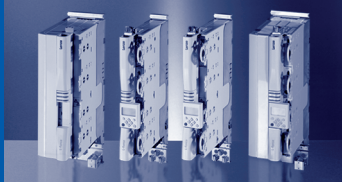
<sup>1)</sup> Module slot MXI 1 must be used for PROFI-safe.

## Assignment of extension modules and the module slot for the regenerative power supply module

Two module slots on the regenerative power supply modules are included for extensions. The following table lists the possible combinations.

MXI 1	E94AYCCA	E94AYCEN	E94AYCPM
<b>MXI 2</b>			
E94AYCCA		•	•
E94AYCEN	•		•
E94AYCPM	•	•	





# 9400 Servo Drives Moduls

## Memory module

### Click – the pluggable memory module

Different memory modules are available for the 9400 Servo Drives:



- ▶ Motion Control StateLevel (MM110)
- ▶ Motion Control HighLevel (MM220)
- ▶ Motion Control TopLevel (MM330 and MM430).

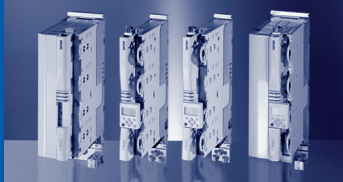
These modules activate the functional ranges described below. The activated functions can be loaded into the drive with the L-force Engineer.

In addition to the different functional ranges of the runtime software versions, depending on the memory module used, different storage capacities and a real-time function (battery-buffered) are also available.





Memory module MM330

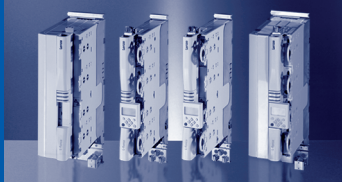
Memory module	Features	Slot	Product key
<b>Motion Control StateLevel MM110</b> 	<ul style="list-style-type: none"> <li>▶ Application and parameter storage</li> <li>▶ Functional range for Motion Control StateLevel device profile DS402 / IEC 61800-7-2 in connection with 9400 Servo Drives StateLine:               <ul style="list-style-type: none"> <li>- Homing mode</li> <li>- Interpolated position mode</li> <li>- Cyclic synchronous position</li> <li>- Cyclic synchronous velocity</li> <li>- Cyclic synchronous torque</li> </ul> </li> </ul>	MMI	E94AYM11
<b>Motion Control HighLevel MM220</b> 	<ul style="list-style-type: none"> <li>▶ Application and parameter storage</li> <li>▶ Functional range for Motion Control HighLevel in connection with 9400 Servo Drives HighLine:               <ul style="list-style-type: none"> <li>- Speed actuating drive</li> <li>- Torque actuating drive</li> <li>- Electronic gearbox</li> <li>- Synchronism with mark synchronisation</li> <li>- Table positioning</li> <li>- Extension/adjustment via function block editor</li> </ul> </li> <li>In connection with regenerative power supply module:               <ul style="list-style-type: none"> <li>- Operation of the regenerative power supply module</li> </ul> </li> <li>▶ Address switch and baud rate setting for onboard system bus CANopen</li> </ul>		E94AYM22



## Memory module

Memory module		Features	Slot	Product key
<b>Motion Control TopLevel MM330</b>		<ul style="list-style-type: none"> <li>▶ Application and parameter storage</li> <li>▶ Functional range for Motion Control TopLevel in connection with 9400 Servo Drives HighLine:                             <ul style="list-style-type: none"> <li>- Speed actuating drive</li> <li>- Torque actuating drive</li> <li>- Electronic gearbox</li> <li>- Synchronism with mark synchronisation</li> <li>- Table positioning</li> <li>- Positioning sequence control (graphical sequence chain)</li> <li>- Extension/adjustment via function block editor</li> <li>- Function blocks with cam functionality</li> </ul> </li> <li>▶ Address switch and baud rate setting for onboard system bus CANopen</li> </ul>	MMI	E94AYM33
<b>Motion Control TopLevel MM430</b>		<ul style="list-style-type: none"> <li>▶ Application and parameter storage</li> <li>▶ Functional range for Motion Control TopLevel in connection with 9400 Servo Drives HighLine:                             <ul style="list-style-type: none"> <li>- Speed actuating drive</li> <li>- Torque actuating drive</li> <li>- Electronic gearbox</li> <li>- Synchronism with mark synchronisation</li> <li>- Table positioning</li> <li>- Positioning sequence control (graphical sequence chain)</li> <li>- Extension/adjustment via function block editor</li> <li>- Function blocks with cam functionality</li> </ul> </li> <li>▶ Address switch and baud rate setting for onboard system bus CANopen</li> <li>▶ Real-time function (battery-buffered)</li> </ul>		E94AYM43

Product key		E94AYM11	E94AYM22	E94AYM33	E94AYM43
<b>Memory module</b>		<b>Motion Control StateLevel MM110</b>	<b>Motion Control HighLevel MM220</b>	<b>Motion Control TopLevel MM330</b>	<b>Motion Control TopLevel MM430</b>
<b>Storage medium</b> Flash memory	[MB]	1	2	4	8
<b>Additional functions</b> Real-time function (battery-buffered)			No		Yes
System bus address switch (CAN)		No		Yes	



## 9400 Servo Drives Moduls

### Safety module

#### Click – integrated safety

Today one of the main tasks in plant engineering and construction is the integration of extensive safety engineering for almost all applications. Often this is only possible by means of time-consuming and expensive wiring. The drive-based safety solutions which can be integrated into the 9400 Servo Drives allow safety to be implemented via the axis modules. The optionally integrable safety engineering has a modular design. The scalable functionality starts with safe torque off (previously called safe standstill) and ends with the integration of safety bus systems. The modular approach of drive-based safety also guarantees it will be fit for the future and maintains flexibility. The following modules are available:

- ▶ SM0 (required as a cover for slot MSI when no safety functions are needed)
- ▶ SM100
- ▶ SM300
- ▶ SM301

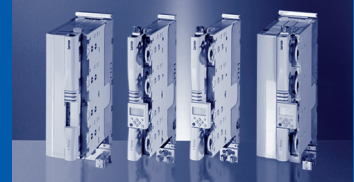


Safety module SM301

Safety module	Features	Slot	Product key
SM0	<ul style="list-style-type: none"> <li>▶ No safety functions</li> </ul>	MSI	E94AYAA
SM100	<ul style="list-style-type: none"> <li>▶ 1 safe input for active sensors, 1 monitor (1-channel output)</li> <li>▶ Safe torque off (STO)</li> <li>▶ Control category 4 to EN 954-1, PLe to EN ISO 13849-1</li> </ul>		E94AYAB
SM300	<ul style="list-style-type: none"> <li>▶ Connection of active and passive sensors</li> <li>▶ Safe torque off (STO)</li> <li>▶ Safe stop 1 (SS1)</li> <li>▶ PROFIsafe safety bus via PROFIBUS (required)</li> <li>▶ Control category 3 to EN 954-1</li> </ul>		E94AYAD
SM301	<ul style="list-style-type: none"> <li>▶ 4 safe inputs, for active or passive sensors</li> <li>▶ 1 safe output, parameterisable</li> <li>▶ Safe torque off (STO)</li> <li>▶ Safe stop 1 (SS1)</li> <li>▶ Safe stop 2 (SS2), safe operating stop (SOS)<sup>1, 2)</sup></li> <li>▶ Safely limited speed (SLS)<sup>1)</sup></li> <li>▶ Safe maximum speed (SMS)<sup>1)</sup></li> <li>▶ Operation mode selector (OMS) with confirmation (ES)</li> <li>▶ Safe speed monitor (SSM)<sup>1)</sup></li> <li>▶ PROFIsafe safety bus via PROFIBUS DP and PROFINET IO (optional)</li> <li>▶ Control category 3 to EN 954-1, PLe to EN ISO 13849-1</li> </ul>		E94AYAE

<sup>1)</sup> Speed-dependent functions only in conjunction with MCS motors and SRS50 or SRM50 SinCos encoders

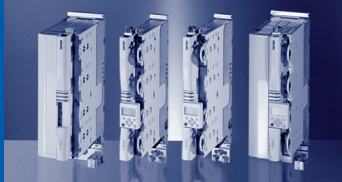
<sup>2)</sup> Safety function following IEC 61800-5-2. SOS is performed with speed monitoring.



## Safety module

Product key		E94AYAA	E94AYAB	E94AYAD	E94AYAE
Safety module		SMO	SM100	SM300	SM301
Certified to EN 954-1 EN ISO 13849-1			Category 4 PLe	Category 3	Category 3 PLe
Fail-safe state			Safe torque off	Safe torque off	Safe torque off
<b>Safe inputs/outputs</b>					
Number of connectable active safety sensors			1	1	4 choice between active or passive
Number of connectable passive safety sensors				2	4 choice between active or passive
Monitor (1-channel output) Safe speed monitor (2-channel output)			1		1 (2-channel output)
<b>Safety bus</b> PROFIsafe <sup>1)</sup>				Communication module PROFIBUS DP (required)	Communication module PROFIBUS DP, PROFINET IO (optional)
<b>Diagnostics</b> Status displays			2 LEDs	5 LEDs	6 LEDs
<b>DC supply voltage</b>	U <sub>DC</sub> [V]		24	24	24

<sup>1)</sup> Module slot MXI 1 must be used for PROFIsafe.



## 9400 Servo Drives Moduls

### Extension module for digital frequency

Some applications require several axes to be operated in synchronism. What was formerly implemented by means of the line shaft, can now be achieved in the 9400 HighLine Servo Drives with the digital frequency extension module. The extension module provides a digital frequency input and output. The signals of the different axes can thus be looped through and simulated.

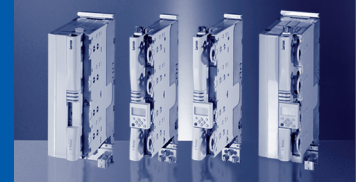


Extension module for digital frequency

Design	Features	Slot	Product key
Extension module			
Digital frequency	<ul style="list-style-type: none"> <li>▶ Digital frequency 0 - 500 kHz</li> <li>▶ Up to three slave drives connectable</li> <li>▶ Sub-D connection for LFin and Lfout</li> </ul>	MXI	E94AYFLF

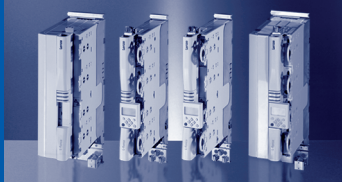
### Standards and operating conditions

Product key	E94AYFLF
Design Extension module	Digital frequency
Enclosure EN 60529	IP20
Vibration resistance	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd
Permissible installation height	0 ... 4000 m amsl
Climatic conditions Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)
Insulation voltage to reference earth/PE EN 61800-5-1	AC 50 V



## Extension module for digital frequency

<b>Product key</b>		<b>E94AYFLF</b>
<b>Medium</b>		System cables, type: EYD
<b>Digital frequency</b>		
Input		0 to 500 kHz (TTL)
Output		0 to 500 kHz (TTL)
<b>Incremental encoder</b>		TTL encoder 2 signals of 5 V offset by 90°
<b>Slave drives</b>		
Parallel connection		3 drives
Series connection		For 250 kHz 20 drives For 500 kHz 10 drives
<b>Max. cable length</b> between two nodes	[m]	50
<b>DC supply voltage</b>	$U_{DC}$ [V]	Internal via mains connection of the inverter



## 9400 Servo Drives Moduls


### Communication module CANopen

The 9400 HighLine Servo Drives and the regenerative power supply modules are equipped with an on board CANopen interface as standard. This interface enables communication between the axis modules and to other system bus components (e.g. I/O systems or HMIs).

If the 9400 StateLine Servo Drive is used or the system network requires a second CANopen interface, the CANopen communication module can be used for this purpose. CANopen is a communication protocol based on CAN technology. It is specified by the CiA user group (CAN in Automation) and can be configured for compatibility with the Lenze system bus (CAN).

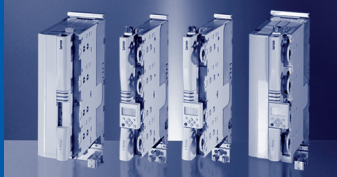


Communication module CANopen

Design	Features	Slot	Product key
Communication module			
CANopen 	<ul style="list-style-type: none"> <li>▶ Automatic baud rate detection</li> <li>▶ CANopen profile DS301, V4.02 Lenze system bus</li> <li>▶ 2 LEDs for communication status display</li> <li>▶ DIP switch for selecting baud rate and address</li> <li>▶ Sub-D connection</li> </ul>	MXI	E94AYCCA

### Standards and operating conditions

Product key	E94AYCCA
Design Communication module	CANopen
Enclosure EN 60529	IP20
Vibration resistance	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd
Permissible installation height	0 ... 4000 m amsl
Climatic conditions Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)
Insulation voltage to reference earth/PE EN 61800-5-1	AC 50 V

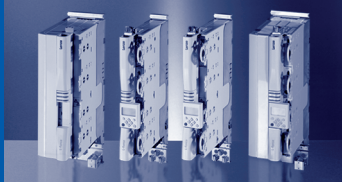


## Communication module CANopen

<b>Product key</b>		<b>E94AYCCA</b>
<b>Communication Medium</b>		DIN ISO 11898
<b>Communication profile</b>		CANopen, DS301 V4.02, or Lenze system bus
<b>Drive profile</b>		DS402 in combination with 9400 StateLine Servo Drives
<b>Baud rate</b>	[kBit/s]	10 20 50 125 250 500 800 1000
<b>Node</b>		Multi-master or slave
<b>Network topology</b>		Line with terminating resistors (120 ohm) at both ends
<b>Number of logical process data channels</b>		4 (each with 1 - 8 bytes)
<b>Number of logic parameter data channels</b>		5
<b>Number of nodes</b>		127 110 (no repeaters)
<b>Max. distance between 2 nodes</b>	[m]	Unlimited, determined by max. bus length
<b>Max. cable length per bus segment<sup>1)</sup></b>	[m]	17 for 1000 kbps 40 for 800 kbps 110 for 500 kbps 290 for 250 kbps 630 for 125 kbps 1500 for 50 kbps 3900 for 20 kbps 8000 for 10 kbps
<b>DC supply voltage</b>	U <sub>DC</sub> [V]	Internal via mains connection of the inverter

<sup>1)</sup> Max. bus cable lengths also depend on the number of nodes and the cable cross-section used.





## 9400 Servo Drives Moduls

### Communication module DeviceNet

The American automation specialist Allan Bradley developed the DeviceNet fieldbus based on the CAN controller. This communication profile was published by the ODVA (Open DeviceNet Vendor Association) user organisation. A large number of sensors and actuators are available. Similar to CANopen, a DeviceNet master is used to control the DeviceNet.

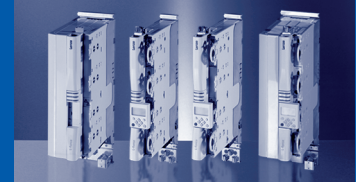


Communication module DeviceNet

Design	Features	Slot	Product key
Communication module			
DeviceNet	<ul style="list-style-type: none"> <li>▶ "Group 2 Only Server" functionality (slave)</li> <li>▶ 1 LED for communication status display</li> <li>▶ DIP switch for selecting baud rate and address</li> <li>▶ Plug connector with screw connection, 5-pole</li> </ul>	MXI	E94AYCDN

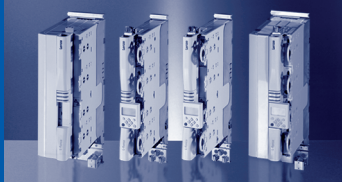
### Standards and operating conditions

Product key	E94AYCDN
Design Communication module	DeviceNet
Enclosure EN 60529	IP20
Vibration resistance	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd
Permissible installation height	0 ... 4000 m amsl
Climatic conditions Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)
Insulation voltage to reference earth/PE EN 61800-5-1	AC 50 V



## Communication module DeviceNet

<b>Product key</b>		<b>E94AYCDN</b>	
<b>Communication Medium</b>		DIN ISO 11898	
<b>Communication profile</b>		DeviceNet	
<b>Baud rate</b>	[kBit/s]	125 250 500	
<b>Node</b>		Slave	
<b>Network topology</b>		Line with terminating resistors (120 ohm) at both ends	
<b>Process data words (PCD)</b> 16 bits	[Wörter]	32	
<b>Number of nodes</b>		Max. 64	
<b>Max. cable length per bus segment</b>	[m]	Thick cable 100 for 500 kbps 250 for 250 kbps 500 for 125 kbps	Thin cable 100 for 125 kbps 100 for 250 kbps 100 for 500 kbps
<b>DC supply voltage</b>	$U_{DC}$ [V]	External 24 via the DeviceNet cable to the 5-pole plug connector	



## 9400 Servo Drives Moduls

### Communication module EtherCAT

Physically speaking, EtherCAT is a ring system that uses a one-total-frame protocol, where the device manipulates the data during the cycle. It is found in the E-bus and Ethernet physical variants. E-bus is merely suitable for short distances within a device; only the Ethernet version offers the benefits of an Ethernet system.

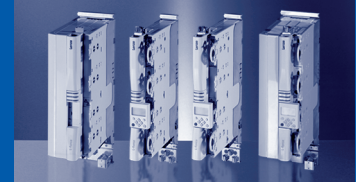


Communication module EtherCAT

Design	Features	Slot	Product key
Communication module			
EtherCAT	<ul style="list-style-type: none"> <li>▶ CANopen over EtherCAT (CoE)</li> <li>▶ Distributed clock</li> <li>▶ 2 RJ45 connections with LED for link/activity</li> <li>▶ 2 LEDs for communication status display</li> <li>▶ External voltage supply possible</li> </ul>	MXI	E94AYCET

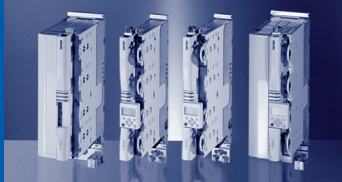
### Standards and operating conditions

Product key	E94AYCET
Design Communication module	EtherCAT
Enclosure EN 60529	IP20
Vibration resistance	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd
Permissible installation height	0 ... 4000 m amsl
Climatic conditions Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)
Insulation voltage to reference earth/PE EN 61800-5-1	AC 50 V



## Communication module EtherCAT

<b>Product key</b>		<b>E94AYCET</b>
<b>Communication Medium</b>		CAT5e S/FTP according to ISO/ICE11801 (2002)
<b>Communication profile</b>		CoE (CANopen over EtherCAT)
<b>Baud rate</b>	[Mbit/s]	100
<b>Node</b>		Slave
<b>Network topology</b>		Line (internal ring)
<b>Number of logical process data channels</b>		1
<b>Process data words (PCD)</b> 16 bits	[Wörter]	32
<b>Number of nodes</b>		65535
<b>Max. distance between 2 nodes</b>	[m]	100
<b>DC supply voltage</b>	$U_{DC}$ [V]	External 24 V connection Internal via mains connection of the inverter



## 9400 Servo Drives Moduls

### Communication module Ethernet

Initially the Ethernet network was reserved for the office, but today this communication system is also often used for system parameterisation. The 9400 Servo Drives can be expanded for this purpose using an Ethernet module.

The Ethernet module can be integrated into general IT infrastructures (e.g. control centres, production data acquisition) and is suitable for remote maintenance applications. It is intended for parameter setting, but not for real-time transmission of process data.

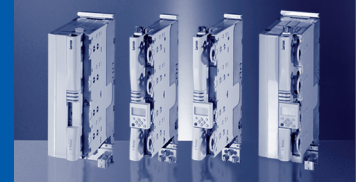


Communication module Ethernet

Design	Features	Slot	Product key
Communication module			
Ethernet	<ul style="list-style-type: none"> <li>▶ Automatic setting of baud rate and transmission mode</li> <li>▶ Automatic detection of wiring errors and polarity reversal</li> <li>▶ Automatic switching between transmit and receive paths (autocrossing)</li> <li>▶ 1 LED for communication status display</li> <li>▶ Electrically isolated from the bus</li> </ul>	MXI	E94AYCEN

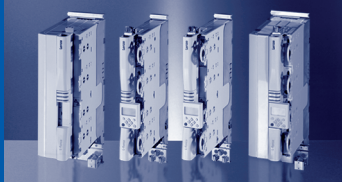
### Standards and operating conditions

Product key	E94AYCEN
Design Communication module	Ethernet
Enclosure EN 60529	IP20
Vibration resistance	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd
Permissible installation height	0 ... 4000 m amsl
Climatic conditions Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)
Insulation voltage to reference earth/PE EN 61800-5-1	AC 50 V



## Communication module Ethernet

<b>Product key</b>		<b>E94AYCEN</b>
<b>Communication Medium</b> Communication profile		Twisted Pair, CAT 5e to IEEE802.3 GCI, based on TCP/IP
<b>Baud rate</b> Ethernet	[MBit/s]	10/100
<b>Signalling</b> Ethernet		Link and activity
<b>Max. cable length</b> between two nodes	[m]	100
<b>Network topology</b>		Star; use of hubs/switches
<b>Transmission Mode</b>		Half duplex/full duplex
<b>Port</b>		1200 and 9400
<b>DC supply voltage</b>	$U_{DC}$ [V]	Internal via mains connection of the inverter



# 9400 Servo Drives Moduls

## Communication module ETHERNET Powerlink

ETHERNET Powerlink (EPL) is an Ethernet-based bus system which also makes use of the tried-and-tested CANopen standards. Any CANopen drive profile can be transferred directly to the EPL context without the need for any adaptations. ETHERNET Powerlink is suitable for control/inverter networking, for pure PLC functionality and for motion control systems. The managing node (MN) takes care of the bus master functionality and the slaves are referred to as controlled nodes (CN).

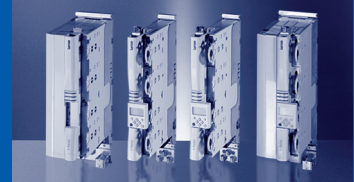


Communication module ETHERNET Powerlink

Design	Features	Slot	Product key
<b>Communication module</b>			
<b>POWERLINK MN/CN</b>	<ul style="list-style-type: none"> <li>▶ Managing node (MN) or controlled node (CN)</li> <li>▶ 2 RJ45 connections with LED for link/activity</li> <li>▶ Integrated hub</li> <li>▶ 2 LEDs for communication status display</li> <li>▶ External voltage supply possible</li> </ul>	MXI	E94AYCEP
<b>POWERLINK CN</b>	<ul style="list-style-type: none"> <li>▶ 2 RJ45 connections with LED for link/activity</li> <li>▶ Integrated hub</li> <li>▶ Controlled node (CN)</li> <li>▶ 2 LEDs for communication status display</li> <li>▶ External voltage supply possible</li> </ul>		E94AYCEC

## Standards and operating conditions

Product key	E94AYCEP	E94AYCEC
<b>Design</b> Communication module	<b>POWERLINK MN/CN</b>	<b>POWERLINK CN</b>
<b>Enclosure</b> EN 60529	IP20	
<b>Vibration resistance</b>	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd	
<b>Permissible installation height</b>	0 ... 4000 m amsl	
<b>Climatic conditions</b> Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)	
<b>Insulation voltage to reference earth/PE</b> EN 61800-5-1	AC 50 V	



## Communication module ETHERNET Powerlink

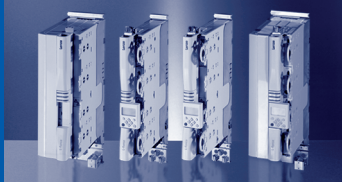
Product key		E94AYCEP	E94AYCEC
Communication Medium		CAT5e S/FTP according to ISO/ICE11801 (2002)	
Communication profile		EPL2.0	
Baud rate	[Mbit/s]	100	
Node		Managing node (MN) Controlled node (CN)	Controlled node (CN)
Network topology		Star when external hubs are used, line when internal hubs are used	
Number of nodes		240	
Max. cable length between two nodes	[m]	100	
DC supply voltage	$U_{DC}$ [V]	External 24 V connection Internal via mains connection of the inverter	

## ETHERNET Powerlink hub

Lenze offers an external 8-fold hub supplementing the 2-fold hub integrated in the ETHERNET Powerlink interface module. This infrastructure component corresponds to a class-II repeater according to IEEE802.3u. It automatically detects the network baud rate (10 or 100 Mbps). The hubs can be cascaded via a special uplink port.

Design	Features	Product key
Communication module		
Powerlink Hub	 <ul style="list-style-type: none"> <li>▶ DC 24V</li> <li>▶ 8-fold hub in industrial design</li> <li>▶ Automatic baud rate detection (10/100 Mbps)</li> <li>▶ Cascadable</li> </ul>	E94AZCEH





## 9400 Servo Drives Moduls

### Communication module PROFIBUS

One of the communication channels most commonly used in industry is PROFIBUS. The 9400 Servo Drives series is provided with the corresponding interface module required for this type of communication.

The PROFIBUS module is a slave connection module with the PROFIBUS-DP communication profile. It is used for networking between the control and the inverter at high processing speeds. It provides a user-friendly way of integrating the inverter into the overall system network.

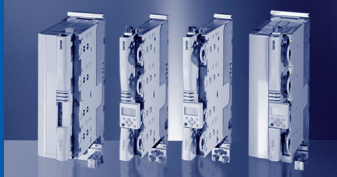


Communication module PROFIBUS

Design	Features	Slot	Product key
Communication module			
PROFIBUS	<ul style="list-style-type: none"> <li>▶ 2 LEDs for communication status display</li> <li>▶ Address can be set by means of a DIP switch</li> <li>▶ Electrically isolated from the bus</li> <li>▶ Compatibility switch for communication module EMF2133 IB</li> </ul>	MXI	E94AYCPM

### Standards and operating conditions

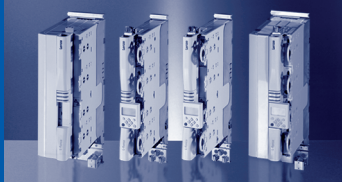
Product key	E94AYCPM
Design Communication module	PROFIBUS
Enclosure EN 60529	IP20
Vibration resistance	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd
Permissible installation height	0 ... 4000 m amsl
Climatic conditions Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)
Insulation voltage to reference earth/PE EN 61800-5-1	AC 50 V



## Communication module PROFIBUS

Product key		E94AYCPM
Communication Medium		RS 485, shielded twisted pair
Communication profile		PROFIBUS-DP-V0 PROFIBUS-DP-V1 PROFIsafe in combination with SM300 and SM301
Drive profile		Drivecom profile "Drive technology 20" <sup>1)</sup> Lenze drive control PROFIDrive, version 4 <sup>1)</sup>
Baud rate	[kBit/s]	9.6 ... 12000 (automatic detection)
Node		Slave
Network topology		With repeater: line or tree Without repeater: line
Process data words (PCD) 16 bits	[Wörter]	1 ... 32
DP user data length		Optional parameter channel (4 words) + process data words
Number of nodes		31 slaves + 1 master per bus segment With repeaters: 125
Max. cable length per bus segment	[m]	1200 (depends on baud rate and cable type used)
DC supply voltage	U <sub>DC</sub> [V]	External 24 V connection Internal via mains connection of the inverter

<sup>1)</sup> In preparation.



# 9400 Servo Drives Moduls

## Communication module PROFINET

The PROFINET bus system based on Ethernet is often used as the successor of PROFIBUS. There are several variants of the PROFINET which differ regarding the deterministics and thus the cycle times possible. The most frequent variant of the PROFINET I/O is the RT variant which can be used for control/inverter networking but not for motion control applications.

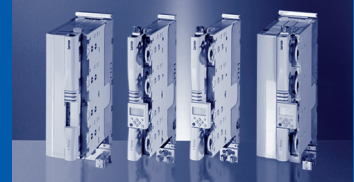


Communication module PROFINET

Design	Features	Slot	Product key
Communication module			
PROFINET	<ul style="list-style-type: none"> <li>▶ 1 RJ45 connection with LED for link/activity</li> <li>▶ PROFINET I/O device</li> <li>▶ Soft real time (RT)</li> <li>▶ 2 LEDs for communication status display</li> <li>▶ External voltage supply possible</li> </ul>	MXI	E94AYCER

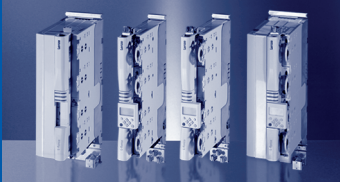
## Standards and operating conditions

Product key	E94AYCER
Design Communication module	PROFINET
Enclosure EN 60529	IP20
Vibration resistance	Sinusoidal oscillation; Amplitude/acceleration (10 Hz ≤ f ≤ 57 Hz 0.075 mm, 57 Hz ≤ f ≤ 150 Hz 1 g), acceleration resistant up to 0.7 g acc. to Germanischer Lloyd
Permissible installation height	0 ... 4000 m amsl
Climatic conditions Storage (EN 60721-3-1) Transport (EN 60721-3-2) Operation (EN 60721-3-3)	1K3 (temperature: -25 °C ... +60 °C) 2K3 (temperature: -25 °C ... +70 °C) 3K3 (temperature: -10 °C ... +55 °C)
Insulation voltage to reference earth/PE EN 61800-5-1	AC 50 V



## Communication module PROFINET

<b>Product key</b>		<b>E94AYCER</b>
<b>Communication Medium</b> Communication profile Drive profile		CAT5e S/FTP according to ISO/ICE11801 (2002) PROFINET I/O (RT) PROFIsafe in combination with SM301
<b>Baud rate</b>	[kBit/s]	100
<b>Node</b>		PROFINET I/O device
<b>Network topology</b>		Star; use of switches
<b>Process data words (PCD)</b> 16 bits	[Wörter]	1 ... 32
<b>Max. cable length</b> between two nodes	[m]	100
<b>DC supply voltage</b>	$U_{DC}$ [V]	External 24 V connection Internal via mains connection of the inverter



# 9400 Servo Drives

## Notes



### General information

The L-force Engineer is the engineering tool for commissioning and diagnosing the 9400 Servo Drives. The user interface is intuitive and easy to use. The clearly structured dialogs of the L-force Engineer are specially adapted to the requirements of users.

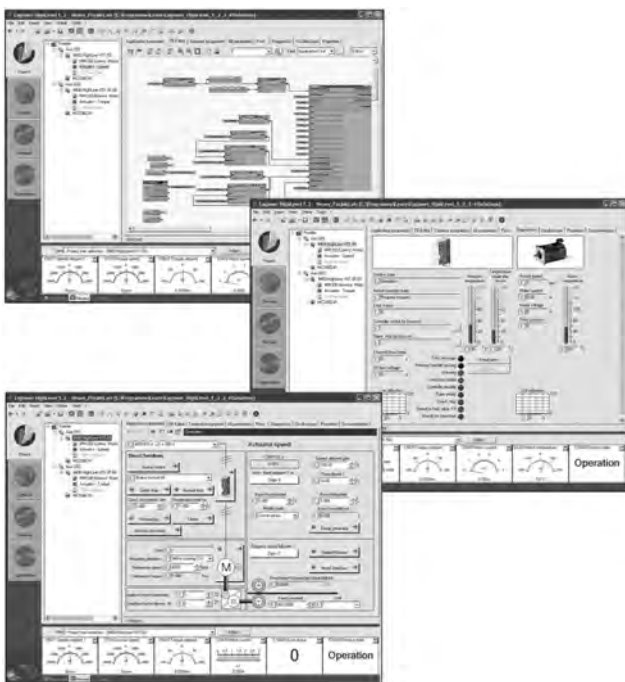
The various phases of a project are used as the primary navigation aid, as a result of which the key functions are sorted and presented in a clear manner. Numerous graphical interfaces are used in addition to simplify the configuration and parameter setting processes for the devices. As a result, in many cases more complicated programming processes can be replaced with a simpler configuration step.

Multi drive engineering comes naturally with the L-force Engineer. A large number of functions enable your machine to be optimally configured, commissioned and diagnosed.

The following versions are available:

- ▶ **Engineer StateLevel (can be downloaded free of charge)**  
Featuring all necessary diagnostic functions, this product is absolutely ideal for service engineers and commissioners. It is optimised for commissioning 9400 Servo Drives and can also be used to implement smaller projects with up to 5 target systems. The CD also includes the GDC easy parameter setting program as well as the L-Force Loader tool so that you can commission further target systems.

- ▶ **Engineer HighLevel**  
In addition to the functions provided by the Engineer StateLevel software, the Engineer HighLevel version offers essential functions for large projects, such as establishing networks, connecting communication stations and editing function blocks. You can even integrate your own documentation into the Engineer project, so that everything remains available centrally at all times - long searches are a thing of the past. The GDC easy parameter setting program and other programs included on this CD can be used for configuring and commissioning further target systems. This full version is available as a single user, multiple user or buyout licence type.



*User interfaces of L-force Engineer HighLevel*



### Functions and features

The following table describes the functions and properties of the engineering software for 9400 Servo Drives.

Since not all functions can be accessed by every drive, the engineering software appears differently, depending on the selected drive.

Product key Short form	ESPEVEHNNN□□1	
Design	L-force Engineer StateLevel	L-force Engineer HighLevel
<b>Drives and components</b>		
9400 Servo Drives	•	•
I/O system IP20	•	•
Lenze motors	•	•
Application motors	•	•
<b>Project creation</b>		
Limitation to 5 target systems	Yes	No
<b>Project documentation</b>		
Stored in project		•
<b>Parameterisation</b>		
Graphics-based	•	•
Parameter list	•	•
<b>Networks and communication</b>		
System bus (CAN) network configuration		•
Network configuration - ETHERNET Powerlink		•
Communication interconnection		•
Port editor (communication interface)		•
Creation of machine application		•
<b>CONFIGURATION</b>		
Function block editor		•
<b>Diagnostics</b>		
Terminal display/diagnostics overview	•	•
Monitor window	•	•
Logbook of all error messages	•	•
Online values in graphics-based parameterisation	•	•
Online values in function block editor		•
Network diagnostics		•
Online/offline comparison	•	•
Oscilloscope	2-channel	8-channel
<b>Safety</b>		
Safe configuration of SM301	•	•



### Functions and features

The following table describes the functions and properties of the engineering software for 9400 Servo Drives.

Since not all functions can be accessed by every drive, the engineering software appears differently, depending on the selected drive.

Product key Short form		ESPEVEHNNN□□1
Design	L-force Engineer StateLevel	L-force Engineer HighLevel
<b>Cams</b>		
Cam Editor		•
Import, graphical entry		•
Straight line, 5th order polynomial and sloped sine line		•
Automatic addition of profiles with integrated export system		with Cam Designer
<b>Technology applications</b>		
Electronic gearbox	•	•
Synchronism with mark registration	•	•
Positioning sequence control	•	•
Torque actuating drive	•	•
Speed actuating drive	•	•
Table positioning	•	•

### System requirements for L-force Engineer StateLevel / HighLevel V2.7

To be able to use the L-force Engineer, the following minimum hardware and software requirements must be met:

- ▶ Microsoft® Windows® 2000 SP2 or higher / XP
- ▶ IBM-compatible PC with Intel® Pentium® processor 1.4 GHz or higher (projects up to max. 5 axes from 750 MHz)
- ▶ At least 512 MB of RAM (projects up to max. 5 axes at least 256 MB)
- ▶ At least 950 MB free hard disk space
- ▶ At least 1024 x 768 pixels screen resolution with 256 colours
- ▶ Mouse
- ▶ CD-ROM drive
- ▶ Free slots / interfaces in accordance with the requirements of the different fieldbus interface modules.





### Overview of licences

#### Single user licence

Single user licences are always supplied with the software product on CD-ROM. The purchaser is entitled to install the software product on his/her PC. Multiple installations on different PCs are not permitted.

#### Multiple user licence

Some software products can be supplied with multiple user licences. When you purchase a multiple user licence, you acquire the right to install a specific software product (CD-ROM with single user licence) on the number of machines for which licences have been purchased. A legally valid single user licence must be held before multiple user licences can be purchased.

#### Corporate licence

Software products with corporate licences need only be purchased once. These products may be installed on multiple machines within a company on a single site. In such cases, additional multiple user licences are not required.

#### Buyout licence

A buyout licence permits multiple installations of the software within a company on a single site. Purchasers of buyout licences are also entitled to issue sublicences for machines in which Lenze devices are installed.

### Selection and order data

Design	Features	Product key
L-force Engineer StateLevel, freeware	<ul style="list-style-type: none"> <li>▶ Order free of charge</li> <li>▶ Download via the Internet</li> <li>▶ Includes GDC easy and L-force Loader</li> <li>▶ Languages: German/English/French</li> </ul>	Download free of charge
L-force Loader	<ul style="list-style-type: none"> <li>▶ Order free of charge</li> <li>▶ Download via the Internet</li> <li>▶ Languages: German/English/French</li> </ul>	
L-force Engineer HighLevel, single user licence	<ul style="list-style-type: none"> <li>▶ CD-ROM included in scope of supply</li> <li>▶ Installation on one PC</li> <li>▶ Includes GDC, L-force Loader and GD Oscilloscope</li> <li>▶ Languages: German/English/French</li> </ul>	ESPEVEHXAOEC1
L-force Engineer HighLevel, multiple user licence	<ul style="list-style-type: none"> <li>▶ CD-ROM not included in scope of supply</li> <li>▶ Multiple installations on the number of machines for which licences have been purchased</li> <li>▶ The basis is a single user licence</li> </ul>	ESPEVEHNNNML1
L-force Engineer HighLevel, corporate licence	<ul style="list-style-type: none"> <li>▶ CD-ROM not included in scope of supply</li> <li>▶ Multiple installations within a company at one location</li> <li>▶ The basis is a single user licence</li> </ul>	ESPEVEHNNNFL1
L-force Engineer HighLevel, buyout licence	<ul style="list-style-type: none"> <li>▶ CD-ROM not included in scope of supply</li> <li>▶ Multiple installations within a company at one location</li> <li>▶ Issuing of sublicences in conjunction with Lenze drives installed in a machine</li> <li>▶ The basis is a single user licence</li> </ul>	ESPEVEHNNNB1
Cam Designer, single user licence	<ul style="list-style-type: none"> <li>▶ CD-ROM included in scope of supply</li> <li>▶ Installation on one PC</li> <li>▶ Languages: German/English/French</li> </ul>	ESP-CAM1-P
Cam Designer V 2.3 upgrade to Cam Designer V 3.x	<ul style="list-style-type: none"> <li>▶ Upgrade to Cam Designer V 3.0</li> <li>▶ Multiple user licence</li> </ul>	ESP-CAM1-PU2



## Data access/communication

The following table describes the communication paths of the engineering software to the connected drives. Some drives do not support all communication paths, so that some communication paths may not be possible.

Communication	
System bus (CAN)	<ul style="list-style-type: none"><li>▶ USB connection with USB system bus adapter EMF 21771B</li><li>▶ Parallel interface with system bus adapter EMF 21731B</li></ul>
Ethernet	<ul style="list-style-type: none"><li>▶ Network connection (10/100 Mbps Ethernet) switch or hub recommended</li></ul>
Diagnostic interface	<ul style="list-style-type: none"><li>▶ USB connection with diagnostic adapter E94AZCUS</li></ul>

## L-force Loader

The L-force Loader makes standard set-up much easier to perform. Finished L-force projects can be transferred from the PC to the device directly. The L-force Loader cannot be used to make any changes to these projects. You can obtain the L-force Loader free of charge from the Internet at [www.Lenze.de](http://www.Lenze.de).

## Cam Designer

You can use the Cam Designer to create and optimise motion profiles and cam groups for electronic cams quickly and intuitively. Whether you are importing data, using CAD or entering the profiles directly, the Cam Designer will support you from the very first step. Motion profiles can be entered really easily using the mouse and a graphical user interface.

### Features:

- ▶ Fast entry of the relevant parts of the motion profile
- ▶ Clear overview of all motion profiles of other tools
- ▶ Complex motion tasks divided into several simple indexing movements
- ▶ The Cam Manager program is integrated for simple management of all drives, curves and cams



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