

Data sheet for SINAMICS G120C

Article No.: 6SL3210-1KE14-3AF2

Client order no. : Order no. : Offer no. : Remarks :





Figure similar

Rated data			
In	Input		
	Number of phases	3 AC	
	Line voltage	380 480 V +10 %	6 -20 %
	Line frequency	47 63 Hz	
	Rated current (LO)	5.50 A	
	Rated current (HO)	4.50 A	
Output			
	Number of phases	3 AC	
	Rated voltage	400V IEC	480V NEC 1)
	Rated power (LO)	1.50 kW	2.00 hp
	Rated power (HO)	1.10 kW	1.50 hp
	Rated current (LO)	4.10 A	
	Rated current (HO)	3.10 A	
	Rated current (IN)	4.30 A	
	Max. output current	6.20 A	
	Pulse frequency	4 kHz	
	Output frequency for vector control	0 240 Hz	
	Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

 $150\,\%$ base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

Communication

200~% base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications			
Power factor λ	0.70 0.85		
Offset factor $\cos\phi$	0.95		
Efficiency η	0.97		
Sound pressure level (1m)	49 dB		
Power loss 61.9 W			
Filter class (integrated) Class A			
Communication			

PROFINET, EtherNet/IP

Inputs / outputs		
Standard digital inputs		
Number	6	
Switching level: 0→1	11 V	
Switching level: 1→0	5 V	
Max. inrush current	15 mA	
Fail-safe digital inputs		
Number	1	
Digital outputs		
Number as relay changeover contact	1	
Output (resistive load)	DC 30 V, 0.5 A	
Number as transistor	1	
Output (resistive load)	DC 30 V, 0.5 A	
Analog / digital inputs		
Number	1 (Differential input)	
Resolution	10 bit	
Switching threshold as digital input		
0→1	4 V	
1→0	1.6 V	
Analog outputs		
Number	1 (Non-isolated output)	

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5\,^{\circ}\text{C}$

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Aml	oient conditions	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.005 m ³ /s (0.177 ft ³ /s)	
Installation altitude	1,000 m (3,280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
	Connections	
Signal cable		
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Line side		
Version	Plug-in screw terminals	
Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14)	
Motor end		
	Diversity and the second	
Version	Plug-in screw terminals	

Conductor cross-section		
DC link (for braking resistor)		

Version	Plug-in screw terminals
Conductor cross-section	1.00 2.50 mm ² (AWG 18 AWG 14)
Line length, max.	15 m (49.21 ft)
PE connection	On housing with M4 screw

1.00 ... 2.50 mm²

(AWG 18 ... AWG 14)

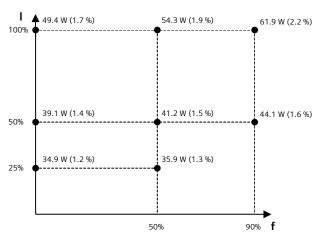
Max. motor cable length

Shielded	50 m (164.04 ft)
Unshielded	100 m (328.08 ft)

Mechanical data			
Degree of protection	IP20 / UL open type		
Frame size	FSAA		
Net weight	1.40 kg (3.09 lb)		
Dimensions			
Width	73 mm (2.87 in)		
Height	173 mm (6.81 in)		
Depth	178 mm (7.01 in)		

Standards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC

Converter losses to IEC61800-9-2*		
Efficiency class	IE2	
Comparison with the reference converter (90% / 100%)	30.3 %	



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

^{*}converted values

 $^{^{1)}}$ The output current and HP ratings are valid for the voltage range 440V-480V