SIEMENS

Data sheet

6ES7515-2AM02-0AB0



SIMATIC S7-1500, CPU 1515-2 PN, central processing unit with 500 KB work memory for program and 3 MB for data, 1st interface: PROFINET IRT with 2-port switch, 2nd interface: PROFINET RT, 30 ns bit performance, SIMATIC Memory Card required

General information Product type designation CPU 1515-2 PN HW functional status FS01 Firmware version V2.9 Product function • I&M data • I&M data Yes; I&M0 to I&M3 • Isochronous mode Yes; Distributed and central; with minimum OB 6x cycle of 500 µs	_
HW functional status FS01 Firmware version V2.9 Product function Ves; I&M0 to I&M3 • I&M data Yes; I&M0 to I&M3 • Isochronous mode Yes; Distributed and central; with minimum OB 6x cycle of 500 μs	
Firmware version V2.9 Product function • I&M data Yes; I&M0 to I&M3 • Isochronous mode Yes; Distributed and central; with minimum OB 6x cycle of 500 μs	
Product function • I&M data • Isochronous mode Yes; I&M0 to I&M3 Yes; Distributed and central; with minimum OB 6x cycle of 500 μs	
 I&M data Isochronous mode Yes; I&M0 to I&M3 Yes; Distributed and central; with minimum OB 6x cycle of 500 μs 	
• Isochronous mode Yes; Distributed and central; with minimum OB 6x cycle of 500 µs	
(distributed) and 1 ms (central)	
Engineering with	
• STEP 7 TIA Portal configurable/integrated from version V17 (FW V2.9) / V16 (FW V2.8) or higher; with older TIA Portal version configurable as 6ES7515-2AM01-0AB0	sions
Configuration control	
via dataset Yes	
Display	
Screen diagonal [cm] 6.1 cm	
Control elements	
Number of keys 8	
Mode buttons 2	
Supply voltage	
Rated value (DC) 24 V	
permissible range, lower limit (DC) 19.2 V	
permissible range, upper limit (DC) 28.8 V	
Reverse polarity protection Yes	
Mains buffering	
Mains/voltage failure stored energy time 5 ms	
Repeat rate, min. 1/s	
Input current	
Current consumption (rated value) 0.8 A	
Current consumption, max. 1.1 A	
Inrush current, max. 2.4 A; Rated value	
l²t 0.02 A²·s	
Power	
Infeed power to the backplane bus 12 W	
Power consumption from the backplane bus (balanced) 6.2 W	
Power loss	
Power loss, typ. 6.3 W	
Memory	
Number of slots for SIMATIC memory card 1	
SIMATIC memory card required Yes	
Work memory	

a integrated (for program)	500 khyta
integrated (for program)	500 kbyte
integrated (for data)	3 Mbyte
Load memory	22 Chuta
Plug-in (SIMATIC Memory Card), max. Backup	32 Gbyte
maintenance-free	Yes
CPU processing times	22
for bit operations, typ.	30 ns
for word operations, typ.	36 ns
for fixed point arithmetic, typ.	48 ns
for floating point arithmetic, typ.	192 ns
CPU-blocks	
Number of elements (total)	8 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	3 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	0 05 525
Number range	0 65 535
• Size, max.	500 kbyte
FC	0 05 535
Number range	0 65 535
• Size, max.	500 kbyte
OB	500 lb.t.
• Size, max.	500 kbyte
Number of free cycle OBs	100
Number of time alarm OBs	20
Number of delay alarm OBs	
Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 500 μs
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	2
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	04
per priority class	24
Counters, timers and their retentivity	
S7 counter	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	0.040
• Number	2 048
Retentivity	Ver
— adjustable	Yes
IEC timer	Any (anti-limited by the main many)
Number	Any (only limited by the main memory)
Retentivity	Vee
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	512 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 472 KB
Extended retentive data area (incl. timers, counters, flags),	3 Mbyte; When using PS 6 0W 24/48/60 V DC HF
max.	
Flag	
• Size, max.	16 kbyte

Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	o, o clock memory bit, grouped into one clock memory byte
Retentivity adjustable	Yes
Retentivity preset	No
Local data	
 per priority class, max. 	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192; max. number of modules / submodules
I/O address area	
Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume) — Outputs (volume)	8 kbyte 8 kbyte
per CM/CP	o noyte
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
 Number of subprocess images, max. 	32
Hardware configuration	
Number of distributed IO systems	64; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
• integrated	
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
 Modules per rack, max. 	32; CPU + 31 modules
 Number of lines, max. 	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter Number	16
Clock synchronization	
supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
 on Ethernet via NTP 	Yes
Interfaces	
Number of PROFINET interfaces	2
1. Interface	
Interface types	
RJ 45 (Ethernet)	Yes; X1
Number of ports	2
integrated switch	Yes
Protocols IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes

PROFINET IO Controller	
Services	
— PG/OP communication	Yes
 — Isochronous mode 	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
- Number of connectable IO Devices, max.	256; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 — Of which IO devices with IRT, max. 	64
 — Number of connectable IO Devices for RT, 	256
max.	
— of which in line, max.	256
 — Number of IO Devices that can be 	8; in total across all interfaces
simultaneously activated/deactivated, max.	
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the
	quantity of configured user data
Update time for IRT	
— for send cycle of 250 µs	250 μs to 4 ms; Note: In the case of IRT with isochronous mode, the
for condicide of 500 up	minimum update time of 500 μ s of the isochronous OB is decisive
— for send cycle of 500 μs	500 µs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
- for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 µs: 375 µs, 625 µs 3 875 µs)
Update time for RT	µs 3 673 µs)
— for send cycle of 250 μs	250 µs to 128 ms
— for send cycle of 230 μs	500 µs to 256 ms
	1 ms to 512 ms
— for send cycle of 1 ms	2 ms to 512 ms
— for send cycle of 2 ms	
— for send cycle of 4 ms PROFINET IO Device	4 ms to 512 ms
Services	
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	Yes
	Yes; per user program
— PROFlenergy — Shared device	Yes
 — Shared device — Number of IO Controllers with shared device. 	4
max.	4
 — activation/deactivation of I-devices 	Yes; per user program
— Asset management record	Yes; per user program
2. Interface	
Interface types	Voc: V2
RJ 45 (Ethernet)	Yes; X2 1
Number of ports integrated switch	
integrated switch Protocols	No
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET TO Controller PROFINET TO Device	Yes
SIMATIC communication	Yes
	Yes; Optionally also encrypted
 Open IE communication Web server 	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	No
— Direct data exchange	No
— Direct data exchange — IRT	No
— 11/1	NU

— PROFlenergy	Voc: por usor program
— Prioritized startup	Yes; per user program No
— Number of connectable IO Devices, max.	32; In total, up to 1 000 distributed I/O devices can be connected via
— Number of connectable to Devices, max.	AS-i, PROFIBUS or PROFINET
 — Number of connectable IO Devices for RT, max. 	32
— of which in line, max.	32
— Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	-,
 — Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication
	share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for RT	
— for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	No
— PROFlenergy	Yes; per user program
— Prioritized startup	No
— Shared device	Yes
 — Number of IO Controllers with shared device, 	4
max.	N/
 activation/deactivation of I-devices 	Yes; per user program
— Asset management record	Yes; per user program
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
 Autonegotiation 	Yes
Autocrossing	Yes
 Industrial Ethernet status LED 	Yes
Protocols	
PROFIsafe	No
PROFIsafe Number of connections	
PROFIsafe Number of connections • Number of connections, max.	192; via integrated interfaces of the CPU and connected CPs / CMs
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web	192; via integrated interfaces of the CPU and connected CPs / CMs 10
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths	192; via integrated interfaces of the CPU and connected CPs / CMs 10
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy — Media redundancy	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1)
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy — Media redundancy — MRP	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ.	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
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PROFIsafe Number of connections Number of connections, max. Number of connections reserved for ES/HMI/web Number of connections via integrated interfaces Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ. — Number of stations in the ring, max. SIMATIC communication	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD
PROFIsafe Number of connections • Number of connections, max. • Number of connections reserved for ES/HMI/web • Number of connections via integrated interfaces • Number of S7 routing paths Redundancy mode • H-Sync forwarding Media redundancy - MRP - MRP - MRPD - Switchover time on line break, typ. - Number of stations in the ring, max. SIMATIC communication	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected
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PROFIsafe Number of connections Number of connections, max. Number of connections reserved for ES/HMI/web Number of connections via integrated interfaces Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ. — Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP — Data length, max. — several passive connections per port, supported EISO-on-TCP (RFC1006)	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes See online help (S7 communication, user data size) Yes Yes Yes Yes Yes
PROFIsafe Number of connections Number of connections, max. Number of connections reserved for ES/HMI/web Number of connections via integrated interfaces Number of S7 routing paths Redundancy mode H-Sync forwarding Media redundancy — Media redundancy — MRP — MRP interconnection, supported — MRPD — Switchover time on line break, typ. — Number of stations in the ring, max. SIMATIC communication PG/OP communication S7 routing S7 communication, as server S7 communication, as client User data per job, max. Open IE communication I TCP/IP — Data length, max. — several passive connections per port, supported I ISO-on-TCP (RFC1006) — Data length, max.	192; via integrated interfaces of the CPU and connected CPs / CMs 10 108 16 Yes only via 1st interface (X1) Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client Yes; as MRP ring node according to IEC 62439-2 Edition 3.0 Yes; Requirement: IRT 200 ms; For MRP, bumpless for MRPD 50 Yes; encryption with TLS V1.3 pre-selected Yes Yes<

— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	Yes
• DNS	Yes
SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
 Runtime license required 	Yes; "Medium" license required
OPC UA Client	Yes
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
 — Number of connections, max. 	10
 Number of nodes of the client interfaces, recommended max. 	2 000
 — Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C max. 	300
 — Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
 — Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100
 Number of simultaneous calls of the client instructions for session management, per connection, max. 	1
— Number of simultaneous calls of the client	5
instructions for data access, per connection, max.	
 Number of registerable nodes, max. 	5 000
— Number of registerable method calls of	100
OPC_UA_MethodCall, max. — Number of inputs/outputs when calling OPC_UA_MethodCall, max.	20
• OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address
	space
— Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
— GDS support (certificate management)	Yes
- Number of sessions, max.	48
- Number of accessible variables, max.	100 000
— Number of registerable nodes, max.	20 000
— Number of subscriptions per session, max.	20
— Sampling interval, min.	100 ms
— Publishing interval, min.	200 ms
— Number of server methods, max.	50
 — Number of inputs/outputs per server method, max. 	20
 — Number of monitored items, recommended max. 	2 000; for 1 s sampling interval and 1 s send interval
 Number of server interfaces, max. 	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
 — Number of nodes for user-defined server interfaces, max. 	5 000
 Alarms and Conditions 	Yes
 — Number of program alarms 	200
 — Number of alarms for system diagnostics 	100
Further protocols	
MODBUS	Yes; MODBUS TCP
Isochronous mode	
Equidistance	Yes
S7 message functions	

Number of login stations for message functions, max.	64
Program alarms	Yes
Number of configurable program messages, max.	10 000; Program messages are generated by the "Program_Alarm"
	block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of simultaneously active program alarms	
 Number of program alarms 	800
 Number of alarms for system diagnostics 	200
 Number of alarms for motion technology objects 	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
 Status/control variable 	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
 Number of variables, max. 	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
• Forcing	Yes
 Forcing, variables 	Peripheral inputs/outputs
 Number of variables, max. 	200
Diagnostic buffer	
• present	Yes
 Number of entries, max. 	3 200
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	Yelling a second s
Diagnostics indication LED • RUN/STOP LED	Yes
• ERROR LED	Yes
• ERROR LED	Tes
	Voo
	Yes
STOP ACTIVE LED	Yes
STOP ACTIVE LEDConnection display LINK TX/RX	
STOP ACTIVE LED	Yes Yes
STOP ACTIVE LEDConnection display LINK TX/RX	Yes Yes Yes; Note: The number of technology objects affects the cycle time of
STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for	Yes Yes Yes; Note: The number of technology objects affects the cycle time of
STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	Yes Yes Yes: Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40
STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder 	Yes Yes Yes: Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per oper control axis per external encoder per output cam per cam track 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 40 80 160 80 20 160
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per oper synchronous axis per external encoder per output cam per cam track per probe 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per cam track per probe Positioning axis 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 40 80 160 80 20 160
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 20 160 40 7 14
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 40 80 20 160 40 7 14 Yes; Universal PID controller with integrated optimization
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per output cam per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 40 80 20 160 40 7 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp 	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 40 80 20 160 40 7 14 Yes; Universal PID controller with integrated optimization
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring	Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 40 80 20 160 40 7 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per probe Positioning axis ner probe Positioning axis per probe Positioning axis Pindumber of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter 	Yes Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 7 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter 	Yes Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 7 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
 STOP ACTIVE LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per probe Positioning axis number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring High-speed counter 	Yes Yes Yes Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 7 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature

 horizontal installation, max. 	60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
 vertical installation, min. 	-25 °C; No condensation
vertical installation, max.	40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the
	display is switched off
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
 Installation altitude above sea level, max. 	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
 User program protection/password protection 	Yes
Copy protection	Yes
 Block protection 	Yes
Access protection	
 protection of confidential configuration data 	Yes
 Password for display 	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
 Protection level: Complete protection 	Yes
programming / cycle time monitoring / header	
lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	70 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	830 g
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