

Specifications:

- 1. Motor type: 8 pole, 3 phase, wye winding, permanent magnet rotor, totally enclosed, non-ventilated.
- 2. Operating speed: 5000 RPM max.
- 3. Continuous stall torque: 2.94 Nm (26 lb-in) max at 125C winding temperature in a 40C ambient, when mounted on a 12 inch sq x 1/2 inch thick aluminum heatsink.
- 4. Peak stall torque: 7.1 Nm (63 lb-in) max.
- 5. Continuous output rating: 0.86 kW (1.15 hp) max at continuous rated operating point: 4575 RPM, 1.81 Nm (16 lb-in), 6.8 Amps 0 to peak max.
- 6. Operating voltage: 230 VAC RMS Ref. (Not for direct connection to AC line).
- 7. Continuous stall current: 10 Amps 0 to peak max.
- 8. Peak stall current: 24.8 Amps 0 to peak max.
- 9. Insulation class: 155C (Class F).
- 10. Housing temperature: 110C (230F) max.
- 11. Ke: 37.8 to 46.2 (42 nom) V/kRPM 0 to peak, phase to phase at 20C to 30C.
- 12. Kt: (sine) 0.347 Nm/Amp 0 to peak (3.07 lb-in/Amp 0 to peak) Ref at 20C to 30C.
- 13. Winding resistance: 0.801 to 0.979 Ohms, phase to phase at 20C to 30C.
- 14. Winding inductance: 5.1 mH, phase to phase Ref.
- 15. Dielectric rating of motor power connections (U,V,W) to ground: 1800 VAC RMS 50/60 Hz for 1 second.
- 16. Rotor inertia: 0.00011 kg-m² (0.00096 lb-in-sec²) Ref.
- 17. Rotor balancing: Quality grade G-6.3.
- 18. Friction torque: 0.025 Nm (0.22 lb-in) Ref.
- 19. Friction torque with shaft seal option installed: 0.053 Nm (0.47 lb-in) Ref.
- 20. Cogging torque: 0.015 Nm (0.13 lb-in) peak to peak Ref.
- 21. Damping: 0.014 Nm/kRPM (0.12 lb-in/kRPM) Ref.
- 22. Thermal resistance, winding to ambient: 1.1 degrees C/watt Ref.
- 23. Thermal time constant, winding to ambient: 15 minutes Ref.
- 24. Product weight: 2.6 kg (5.7 lb) Ref.
- 25. Shipping weight: 2.9 kg (6.4 lb) Ref.
- 26. Operating ambient temperature: 0C to 40C (32F to 104F).
- 27. Storage ambient temperature: -10C to 85C (14F to 185F).
- 28. Relative humidity: 20% to 85% non-condensing.
- 29. Liquid / dust protection: IP65 when optional shaft seal is installed, excluding flying lead connectors (connectors rating: IP30).
- 30. Shock: 20 g peak max, 6 msec duration (18 occurances tested).
- 31. Vibration: 2.5 g peak max, 30 to 2000 Hz.
- 32. Bearing arrangement: Outer diameter of rear bearing is trapped axially.
- 33. Shaft material: Steel, grade S45C.
- Notes: "Ref" denotes untoleranced specifications, provided for reference only.

Speed, torque and current specifications are for motor operation with Allen Bradley drives.

Г	02	TITLE							
REV TL-A2540P-BJ32AA, ESE									
			PART NO.						
	Alle	n-Bradley	TLA2540PBJ32AAESE						
			A SIZE		SHEET	2	OF	4	

Feedback Specifications:

Encoder Function:

- 1. 17 bit single turn absolute position data is provided, via serial output, with or without an external battery connected.
- 2. 16 bit multi-turn absolute position data is provided, along with the 17 bit single turn absolute position data, via serial output, when an external battery is connected.

Electrical Hardware:

- 1. SD+, SD- (serial data) output / input: RS 485 differential line driver / receiver.
- 2. EPWR (encoder power) voltage input: 4.75 to 5.25 VDC.
- 3. EPWR current input: 60 mADC nominal, 110 mADC max continuous. 1.3 ADC max inrush.
- 4. BAT+ (battery) voltage input: 3.6 VDC nominal.
- 5. BAT+ current input, with +5VDC applied to EPWR input: 3.6 uA nominal.
- 6. BAT+ current input, with no EPWR input applied: 110 uA max.
- 7. Battery alarm fault (battery change required) voltage level: 3.1 VDC Ref.
- 8. Battery error fault (absolute multi-turn position not saved at power loss) voltage level: 2.5 VDC Ref.

Serial Communication:

- 1. SD+, SD- serial data rate: 2.5 Mbps, asynchronous.
- 2. Communication hierarchy: Encoder is slave, communication is externally initiated.
- 3. Single turn absolute position value range: 0 to 131,071 (17 bit).
- 4. Multi-turn absolute shaft revolution value range: 0 to 65,535 revolutions (16 bit).
- 5. Absolute position data: Binary, value increases with CCW shaft rotation viewing motor mounting face.
- 6. Memory storage capacity: 80 bytes, EEPROM.

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