Shock Absorber

RB Series

Absorbing impact and noise

Dampening to meet the high speed requirements of the modern world.

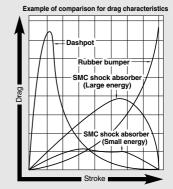
Shock absorber: RB series Coolant resistant type: RBL series

Usable without a stopper nut
The strong body can be positioned directly.

Shock absorber

Automatic adjustment to the most appropriate absorption performance

Specially designed orifice can absorb energy comprehensively and most appropriately in many different applications. This ranges from high speed low loads, to load speed high loads; without requiring additional adjustment of the shock absorber.



* Drag waveform will vary depending on the operating conditions.

Short type: RBQ series

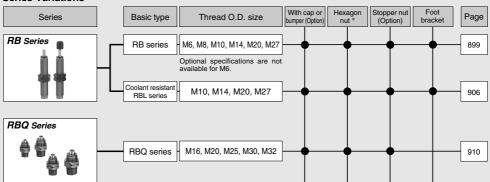
A compact type that has been shortened lengthwise

Allowable eccentric angle is 5° Suitable for absorption of rotation energy.

Usable without a stopper nutThe strong body can be positioned directly.



Series Variations



*2 Hexagon nuts are attached for the RB series and standard models RBQ.



RJ



Model Selection

Model Selection Step Selection Example 1. Type of impact Cylinder stroke at load (Horizontal) Cylinder stroke at load (Horizontal) Shock absorber 1. Cylinder stroke at load (Downward) υ Type □ Cylinder stroke at load (Upward) Conveyor stroke at load (Horizontal) of impact l nad 鄱 m ☐ Free horizontal impact ☐ Free dropping impact □ Rotating impact (With torque) Collision speed (1) 1) 2. Enumeration of operating conditions Kinetic energy ·m•1)² Εı Symbol Operating condition Impacting object mass Thrust energy kg F₁.S E٥ Collision speed m / sec υ Absorbed energy h Dropping height m E1 + E2 E Angle speed stance between axis or plinder and impact poin ω rad/sec Corresponding (2) R 2 1)2 ·E m impacting object d Bore size mm Cylinder operating pressure MPa p Thrust **m** = 1 kg m = 50 kgN Torque N · m v = 0.5 m/s $v = 0.3 \, \text{m/s}$ т d = 10 mmd = 40 mmn Operation cycle cycle / min Operating Operating **p** = 0.5 MPa **p** = 0.5 MPa Ambient temperature °C t conditions conditions n = 30 cycle/min n = 20 cycle/min ш Friction coefficient t = 25 °C t = 25 °C Specifications and operational instructions 3. Confirmation of specifications Confirmation of specifications Ensure that the collision speed, thrust, operation cycle, the ambient temperature ... 0.3 < 5 (max.) ... -10 (min.) < 25 < 80 (max.) ... F1 ...628 < 1961 (max.) υ ··· 0.5 < 1.0 (max.) Specifications Specifications · –10 (min.) < 25 · **F1** ··· 39.3 < < 80 (max.) and atmosphere fall within the specifications. and operational and operational *Be aware of the min. installation radius in the case of rotating impacts. instructions YES instructions YES Calculation of kinetic energy E₁ Kinetic energy E₁ Kinetic energy E₁ Using the equation suitable for the classification of impact. Use Formula to calculate E1. Use Formula to calculate E1. Calculation Calculation Subs titute 1.0 for m and 0.5 for v Substitute 50 for m and 0.3 for v of kinetic of kinetic In the case of cylinder stroke at load and free horizontal impact, E₁ ≅ 2.3 J E₁ ≅ 0.125 energy E1 energy E1 substitute respective figures for Data A in order to calculate E1. 5. Calculation of thrust energy E2 Thrust energy E2 Thrust energy E2 Provisionally select a model RB0604 and make the use of Data B at left. According to d = Select any shock absorber as a provisional Provisionally select a model RB2015 and make the use of Data B. According to d = 40, E2 Calculation Calculation of thrust of thrust In the case of thrust energy of cylinder E1, E2 is obtained. energy E₂ energy E₂ substitute respective figures for Data B or Data C. $E_2\cong 9.4\ J$ E₂ ≅ 0.157 6. Calculation of corresponding mass of impacting object Me Corresponding mass Corresponding mass Absorbed energy E = E1 + E2 of impacting object Me of impacting object Me Calculation of Calculation of Corresponding mass of impacting object $\mathbf{Me} = \frac{2}{2\sqrt{2}} \cdot \mathbf{E}$ the Formula "Absorbed Use the formula "Absorbed energy corresponding corresponding energy E = E1 + E2 = 0.282" to calculate Me. Substitute 0.282 for $E = E_1 + E_2 = 2.3 + 9.4 = 11.7$ mass of mass of to calculate Me. Substitute 11.7.1 Substitute both absorbed energy E and collision E and 0.5 for v. for E and 0.3 for to impacting impacting speed v for Data A in order to calculate the corobject Me Me ≅ 2.3 object Me Me ≅ 260 kg responding mass of the impacting object Me. 7. Selection of applicable model Selection of applicable Selection of RB0604 model Taking into consideration the corresponding RB0604 satisfies Me = 2.3 < 3 kg mass of the impacting object Me, calculated using Data D and collision speed v, check provisional model compatibility with the condition of application. If this is satisfactory, then the said provisional model will be the (Max. corresponding mass of im-According to Data D, the tentativepacting object). Ultimately, it will ly selected RB2015 satisfies Me result in an operating frequency 260 kg < 400 kg at υ = 0.3. Selection Selection of of 30 < 80, without causing a Ultimately, it will result in an of RB0604 applicable problem. operating frequency of n...20 < 25. applicable one model without causing a problem. Caution on Selection YES In order for the shock absorbers to operate accurately for long hours, it is necessary to select a model that is well-suited to your

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operating conditions. If the impact energy is smaller than 5% of the maximum energy absorption, select a model that is one class

Select RB2015

1. Type of Impact

i. Type of fillp	Jaci				
	Cylinder stroke at load (Downward)	Cylinder stroke at load (Upward)	Conveyor stroke at load (Horizontal)	Free dropping impact	Rotating impact (With torque)
Type of impact	Fi Cylinder Load ↓ v	v Load m Cylinder	μ Load d	Load du v	(3)
Collision speed (1)	υ	υ	υ	√2gh	ω · R
Kinetic energy E ₁	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	m · g · h	$\frac{1}{2} \cdot \mathbf{m} \cdot \omega^2$
Thrust energy E2	F ₁ ·S+m·g·S	$F_1 \cdot S + m \cdot g \cdot S$	m·g·μ·S	m · g · S	T · S
Absorbed energy E	E ₁ + E ₂	E ₁ + E ₂	E ₁ + E ₂	E ₁ + E ₂	E1 + E2
Corresponding (2) mass of impacting object Me	<u>2</u> .⊨	<u>2</u> √2 • E	<u>2</u> ⋅E	<u>2</u> ∵E	<u>2</u> √2•E

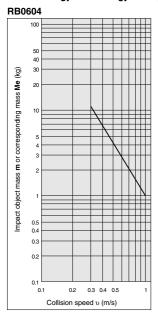
Note 1) Collision speed is momentary velocity at which object is impacting against shock absorber. The collision speed is $v = 2\overline{v}$ when the speed (average speed \overline{v}) is calculated from the air cylinder's stroke time.

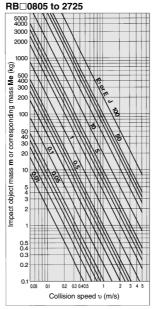
Note 2) An "Impact body equivalent mass" is the mass of an impact object without involving thrust, into which an object's total energy has been converted. Hence, E = $\frac{1}{2}$ -Me· \mathbb{U}^2

Note 3) R: The distance between rotational center and impact point. Set R at the minimum installation radius (page 904) or higher.

Data A

Kinetic Energy E₁ or Energy Absorption E





Symbol

Syllin	JUI	
Symbol	Specifications	Unit
d	Bore size	mm
E	Absorbed energy	J
E ₁	Kinetic energy	J
E ₂	Thrust energy	J
F ₁	Cylinder thrust	N
g	Acceleration of gravity (9.8)	m / s ²
h	Dropping height	m
I (4)	Moment of inertia around the center of gravity	kg · m²
n	Operating frequency	cycle / min
р	Cylinder operating pressure	MPa
R	Distance between axis of cylinder and impact point	m
S	Shock absorber stroke	m
Т	Torque	N · m
t	Ambient temperature	°C
υ	Collision speed	m/s
m	Impact object mass	kg
Ме	Corresponding mass of impact object	kg
ω	Angle speed	rad / s
μ	Friction coefficient	_

Note 4) For the formula of moment of inertia I (kg·m²), refer to the catalog of rotary actuator.



RJ



RB Series

Data B

Thrust Energy of Cylinder F1-S

(Operating pressure 0.5 MPa) (J)

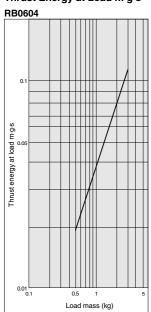
М	odel	RB0604	RB□0805	RB□0806	RB□1007	RB□1411	RB□1412	RB□2015	RB□2725
		1150004	115=0000	RB□1006	11551007	11001411	11001412	IID	IID E I I
	absorption nm)	4	5	6	7	11	12	15	25
	6	0.057	0.071	0.085	0.099	0.156	0.170	0.212	0.353
	10	0.157	0.196	0.236	0.274	0.432	0.471	0.589	0.982
	15	0.353	0.442	0.530	0.619	0.972	1.06	1.33	2.21
	20	0.628	0.785	0.942	1.10	1.73	1.88	2.36	3.93
	25	0.981	1.23	1.47	1.72	2.70	2.95	3.68	6.14
	32	_	2.01	2.41	2.81	4.42	4.83	6.03	10.1
Ē	40	_	3.14	3.77	4.40	6.91	7.54	9.42	15.7
(mm)	50	_	4.91	5.89	6.87	10.8	11.8	14.7	24.5
0	63	_	7.79	9.35	10.9	17.1	18.7	23.4	39.0
size d	80	_	12.6	15.1	17.6	27.6	30.2	37.7	62.8
Bore	100	_	19.6	23.6	27.5	43.2	47.1	58.9	98.2
ď	125	_	30.7	36.8	43.0	67.5	73.6	92.0	153
	140	_	38.5	46.2	53.9	84.7	92.4	115	192
	160	_	50.3	60.3	70.4	111	121	151	251
	180	_	63.6	76.3	89.1	140	153	191	318
	200	_	78.5	94.2	110	173	188	236	393
	250	_	123	147	172	270	295	368	614
	300	_	177	212	247	389	424	530	884

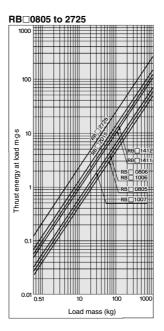
■ Operating pressure other than 0.5 MPa: Multiply by the following coefficient.

Operating pressure (MPa)	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
Coefficient	0.2	0.4	0.6	0.8	1.0	12	14	16	1.8

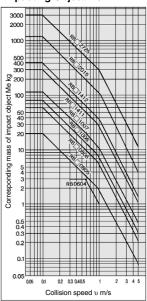
Data C

Thrust Energy at Load m.g.s





Data D Corresponding Mass of Impacting Object Me



The graph of corresponding mass of impacting object: At room temperature (20 to 25°C)

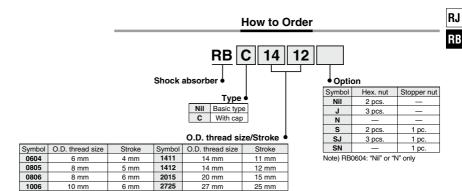
Shock Absorber RB Series



Specifications

	Model	Basic type	RB0604	RB0805	RB0806	RB1006	RB1007	RB1411	RB1412	RB2015	RB2725	
	Specifications	With cap	-	RBC0805	RBC0806	RBC1006	RBC1007	RBC1411	RBC1412	RBC2015	RBC2725	
	Max. energy absorp	otion (J) Note)	0.5	0.98	2.94	3.92	5.88	14.7	19.6	58.8	147	
	Thread O.D. siz	ze	M6 x 0.75	M8 >	(1.0	M10	x 1.0	M14	x 1.5	M20 x 1.5	M27 x 1.5	
	Stroke (mm)		4	5	6	6	7	11	12	15	25	
	Collision speed (m/s)		0.3 to 1.0		0.05 to 5.0							
	Max. operating frequency (cycle/min)		80	80	80	70	70	45	45	25	10	
8	Max. allowable	thrust (N)	150	245	245	422	422	814	814	1961	2942	
	Ambient temperatur	e range (°C)				-10 to 8	0 (No fre	ezing)				
	Spring force	Extended	3.05	1.96	1.96	4.22	4.22	6.86	6.86	8.34	8.83	
	(N)	Retracted	5.59	3.83	4.22	6.18	6.86	15.30	15.98	20.50	20.01	
	14/-1	Basic type	5.5	15	15	23	23	65	65	150	350	
	Weight (g)	With cap	_	16	16	25	25	70	70	165	400	

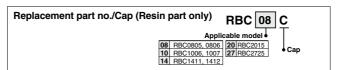
Note) The maximum energy absorption, the maximum corresponding mass of impacting object and maximum operating frequency are measured at room temperature (20 to 25°C).



10 mm Note) RB0604: With cap type is not available.

7 mm

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Cap cannot be mounted for basic type. Please place an order with cap type from the beginning.

D-□ -X□

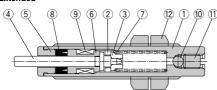
SMC

RB Series

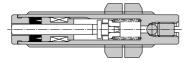
Construction

RB0604

Extended



Compressed

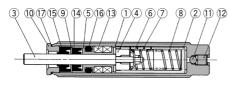


Component Parts

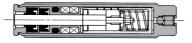
Ī	No.	Description	Material	Treatment
	1	Outer tube	Free-cutting steel	Nitriding
	2	Piston	Copper alloy	_
	3	Spring guide	Stainless steel	_
	4	Piston rod	Carbon steel	Nitriding
Ì	5	Stopper	Stainless steel	_
	6	Bearing	Copper alloy	_
	7	Return spring	Piano wire	Zinc trivalent chromated
	8	Rod seal	NBR	_
	9	Accumulator	NBR	Foam rubber
	10	Steel ball	Bearing steel	_
Ì	11	Hexagon socket head cap screw	Special steel	Nickel plated
	12	Hexagon nut	Carbon steel	Nickel plated

RB□0805 to 2725

Extended



Compressed

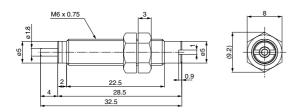


Component Parts

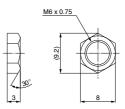
No.	Description	Material	Treatment
1	Outer tube	Rolled steel	Gray coated
2	Inner tube	Special steel	Heat treated
3	Piston rod	Special steel	Electroless nickel plated
4	Piston	Special steel	Heat treated
5	Bearing	Special bearing material	
6	Spring guide	Carbon steel	Zinc chromated
7	Lock ring	Copper	
8	Return spring	Piano wire	Zinc chromated
9	Seal holder	Copper alloy	
10	Stopper	Carbon steel	Zinc chromated
11	Steel ball	Bearing steel	
12	Set screw	Special steel	
13	Accumulator	NBR	Foam rubber
14	Rod seal	NBR	
15	Scraper	NBR	
16	Gasket	NBR	
17	Gasket	NBR	Only RB(C)2015, 2725

Dimensions

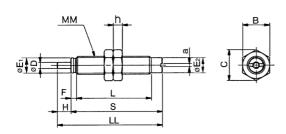
RB0604



Hexagon Nut (2 pcs. standard equipment)

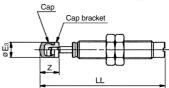


Basic type: RB0805, RB0806, RB1006, RB1007



With cap: RBC0805, RBC0806 RBC1006, RBC1007

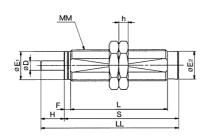
* Other dimensions are the same as the basic type.

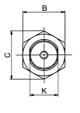


RJ RB

Mo	odel		Basic type dimensions						With cap *			Hexagon nut					
Basic type	With cap	D	E ₁	E ₂	F	Н	а	L	LL	MM	S	E₃	LL	Z	В	С	h
RB0805	RBC0805	2.8	6.8	6.6	2.4	5	1.4	33.4	45.8	M8 x 1.0	40.8	6.8	54.3	8.5	12	13.9	4
RB0806	RBC0806	2.8	6.8	6.6	2.4	6	1.4	33.4	46.8	M8 x 1.0	40.8	6.8	55.3	8.5	12	13.9	4
RB1006	RBC1006	3	8.8	8.6	2.7	6	1.4	39	52.7	M10 x 1.0	46.7	8.7	62.7	10	14	16.2	4
RB1007	RBC1007	3	8.8	8.6	2.7	7	1.4	39	53.7	M10 x 1.0	46.7	8.7	63.7	10	14	16.2	4

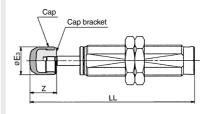
Basic type: RB1411, RB1412, RB2015, RB2725





With cap: RBC1411, RBC1412 RBC2015, RBC2725

* Other dimensions are the same as the basic type.



Mo	odel		Basic type dimensions							With cap *			Hexagon nut				
Basic type	With cap	D	E ₁	E ₂	F	Н	K	L	LL	MM	S	Eз	LL	Z	В	၁	h
RB1411	RBC1411	5	12.2	12	3.5	11	12	58.8	78.3	M14 x 1.5	67.3	12	91.8	13.5	19	21.9	6
RB1412	RBC1412	5	12.2	12	3.5	12	12	58.8	79.3	M14 x 1.5	67.3	12	92.8	13.5	19	21.9	6
RB2015	RBC2015	6	18.2	18	4	15	18	62.2	88.2	M20 x 1.5	73.2	18	105.2	17	27	31.2	6
RB2725	RBC2725	8	25.2	25	5	25	25	86	124	M27 x 1.5	99	25	147	23	36	41.6	6

D-□

RB Series

Hexagon Nut

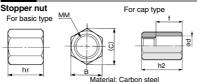
(2 pcs. standard equipment)



Material: Special steel Treatment: Zinc trivalent chromated

Part no.	D	imensi	ons	
raitiio.	MM	h	В	С
RB06J	M6 x 0.75	3	8	9.2
RB08J	M8 x 1.0	4	12	13.9
RB10J	M10 x 1.0	4	14	16.2
RB14J	M14 x 1.5	6	19	21.9
RB20J	M20 x 1.5	6	27	31.2
RB27J	M27 x 1.5	6	36	41.6

Option



Material: Carbon steel
Treatment: Zinc trivalent chromated

Par	t no.	Dimensions										
Basic type	With cap	В	С	h1	h2	MM	d	f				
RB08S	RBC08S	12	13.9	6.5	23	M8 x 1.0	9	15				
RB10S	RBC10S	14	16.2	8	23	M10 x 1.0	11	15				
RB14S	RBC14S	19	21.9	11	31	M14 x 1.5	15	20				
RB20S	RBC20S	27	31.2	16	40	M20 x 1.5	23	25				
RB27S	RBC27S	36	41.6	22	51	M27 x 1.5	32	33				

Replacement Parts

Cap



These are the replacement part for the cap type. Not available for the basic type.

Material: Polyui

	Materiai: Polyurethane									
Part no.	Dimensions									
raitiio.	Α	В	SR							
RBC08C	6.5	6.8	6							
RBC10C	9	8.7	7.5							
RBC14C	12.5	12	10							
RBC20C	16	18	20							
RBC27C	21	25	25							

Foot Bracket for Shock Absorber

Available for the foot mounting bracket of the RB series.

 Part no.
 Material: Aluminum alloy Treatment: Black hard anodized

 Part no.
 Applicable absorber

 RB08-X331
 RB□0805, 0806

 RB10-X331
 RB□1006, 1007

 RB14-X331
 RB□1411, 1412

 RB20-X331
 RB□2015

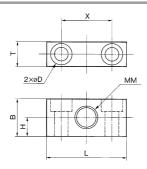
RB □2725



^{*} Order foot brackets separately.

RB27-X331

Dimensions



Part no.	В	D	Н	L	MM	Т	Х	Mounting bolt
RB08-X331	15	4.5 drill, 8 counterbore depth 4.4	7.5	32	M8 x 1.0	10	20	M4
RB10-X331	19	5.5 drill, 9.5 counterbore depth 5.4	9.5	40	M10 x 1.0	12	25	M5
RB14-X331	25	9 drill, 14 counterbore depth 8.6	12.5	54	M14 x 1.5	16	34	M8
RB20-X331	38	11 drill, 17.5 counterbore depth 10.8	19	70	M20 x 1.5	22	44	M10
RB27-X331	50	13.5 drill, 20 counterbore depth 13	25	80	M27 x 1.5	34	52	M12



RB Series Specific Product Precautions 1

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions.

Selection

\land Danger

1. Energy absorption

Select a model so that the aggregated energy of impact object should not exceed the maximum absorption energy. Otherwise, it could cause changes in properties or result in damaging the shock absorber.

2. Corresponding mass of impacting object

Make a model selection, so that the corresponding mass of impacting object does not exceed the allowable range. Pulsation will occur in buffer and deceleration force, thus making it difficult to absorb shock smoothly.

3. Collision speed

Use it in the conditions that collision speed is within the specified range. It could cause the changes in buffer characteristics or lead to damage a shock absorber.

⚠ Warning

1. Static load

Design the system, so that any other forces than the buffer capacity or impacts should not be applied to the piston rod which is stopped at the retracted state.

⚠ Caution

1. Maximum operating frequency

Design the system in the conditions under which it is not used at the frequency exceeding the specified maximum operating frequency.

2. Stroke

The maximum absorption energy in the specifications cannot be exerted unless the full stroke is used for both RB and RBL Series.

3. Work surface of an impact object

The contact surface of the impact object with which the piston rod comes into contact must be highly rigid.

In the case without a cap, a high surface compression load is applied to the contact surface of the impact body with which the piston rod comes into contact. Therefore, the contact surface must be highly rigid (hardness of HRC35 or more).

4. Be aware of the return force of the impact object.

If used in a conveyor drive, after the shock absorber has absorbed energy, it could be pushed back by the spring that is built-in. For the spring force in the specifications, refer to the column (page 899).

5. Selection of size

As the number of operation proceeds, the maximum absorption energy of shock absorbers will be decreased by the following reasons such as abrasion, or deterioration, etc. of the internal working fluid. Taking this into consideration, selecting a size which is 20 to 40% affordable against the amount of absorption energy is recommended.

6. Drag characteristics

In general, the values of drag (reactive force generated during operation) generated by the operating speed will vary in hydraulic shock absorber. And then, by adopting "Porous orifice construction", the RB series can adapt to such this fast/slow speed and can absorb shock smoothly in a wide range of speed.

But, the speed reduction (speed reduction G) would be larger around the stroke terminal, depending upon the operating conditions. Please note that it might be encountered that stroke time is long, motion is not smooth, etc. If this would be a problem, we recommend that stroke amount should be restricted by using our optional component like "Stopper nut", etc.

7 Parallel usane

When using multiple shock absorbers in parallel, energy will not be divided evenly because of differences in product dimensions and devices. For this reason, select the following options.

F = Fa/N/0 6

E : Energy used per shock absorber

Ea: All energies

N: The number of shock absorbers used in parallel

Operating Environment

1. Operation in an environment which requires explosion-proof

- When mounting in places where static electricity is accumulated, implement a distribution of electrical energy by grounding.
- Do not use the materials for buffer face which might cause to spark by collision.

🛕 Warning

Pressure

Do not use it in the vacuum state, which is substantially different from the atmospheric pressure (above sea level) and in the atmosphere under being pressurized.

2. Using inside a clean room

Do not use the shock absorber in a clean room, as it could contaminate the clean room.

⚠ Caution

1. Temperature range

Do not use it, exceeding the specified allowable temperature range. Seal could be softened or hardened or worn out, or leading to leak a working fluid, deterioration, or impact characteristic changes.

2. Deterioration by atmosphere

Do not use the product in an environment where the product may be damaged by salt or air which contains organic solvent, phosphoester operating oil, sulfurous acid gas, chlorine gas or other acids. It may deteriorate seals or corrode metals.

3. Deterioration by ozone

Do not use it under the direct sunlight on the beach, or by the mercury lamp, or the ozone generator, because the rubber material will be deteriorated by ozone.

4. Cutting oil, water, blown dust

Do not use the product under the condition, where the liquid such as cutting oil, water, solvent, etc. is exposed either directly or in atomized form to the piston rod, or where blown dust could be adhered around the piston rod. This could cause malfunction.

D-□

RJ

RR







RB Series Specific Product Precautions 2

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions.

Operating Environment

⚠ Caution

5. Vibration

When vibrations are applied on impact objects, implement a secure quide on impact objects.

Mounting

🗥 Warning

- Before performing installation, removal, or stroke adjustment, make sure to cut the power supply to the equipment and verify that the equipment has stopped.
- 2. Installation of protective cover

We recommend the protective cover should be installed in the case workers might be getting close during the operation.

3. The rigidity of the mounting frame

The mounting frame must have sufficient rigidity.

Load on mounting plate can be calculated as follows.

Load on mounting plate
$$N \cong 2 \frac{E \text{ (Absorbed energy : J)}}{S \text{ (Stroke : m)}}$$

Depending on the impact conditions, a load applied to the mounting frame may exceed the calculated value.

When setting the rigidity of the mounting frame, the sufficient safety ration must be taken into account in the calculated value.

1. Tightening torque of mounting nut should be as follows.

When threading on a mounting frame in order to mount a shock absorber directly, prepared hole dimensions are referred to the table below.

For tightening torque of a nut for shock absorber, kindly abide by the table below.

If the tightening torque that is applied to the nut exceeds the value given below, the shock absorber itself could become damaged.

Model	RB0604	RB(C)0805 RB(C)0806	RB(C)1006 RB(C)1007	RB(C)1411 RB(C)1412
O.D. thread (mm)	M6 x 0.75	M8 x 1.0	M10 x 1.0	M14 x 1.5
Thread prepared bore (mm)	ø5.3 ^{+0.1}	ø7.1 ^{+0.1}	ø9.1 ^{+0.1}	ø12.7 +0.1
Tightening torque (N · m)	0.85	1.67	3.14	10.8

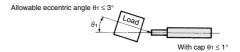
Model	RB(C)2015	RB(C)2725
O.D. thread (mm)	M20 x 1.5	M27 x 1.5
Thread prepared bore (mm)	ø18.7 ^{+0.1}	ø25.7 ^{+0.1}
Tightening torque (N · m)	23.5	62.8

Mounting

∧ Caution

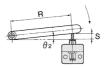
2. Deviation of impact

The installation must be designed so that the impact body is perpendicular to the shock absorber's axial center. An angle of deviation that exceeds 3° will place an excessive load on the bearings, leading to oil leaks within a short period of operation.



3. Rotating angle

If rotating impacts are involved, the installation must be designed so that the direction in which the load is applied is perpendicular to the shock absorber's axial center. The allowable rotating angle until the stroke end must be $\theta \epsilon < 3^{\circ}$.



Allowable rotating eccentric angle $\theta_2 \le 3^\circ$

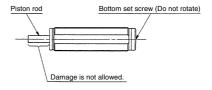
Installation Conditions for Rotating Impact (mm										
Model	S	θ2	R (Min. insta	lation radius)						
iviodei	(Stroke)	(Allowable rotating angle)	Basic type	With cap						
RB0604	4		76	_						
RB□□0805	5		96	258						
RB□□0806	6		115	277						
RB□□1006	6		115	306						
RB□□1007	7	3°	134	325						
RB□□1411	11		210	468						
RB□□1412	12		229	487						
RB□□2015	15		287	611						
RB□□2725	25		478	916						

Do not scratch the sliding portion of the piston rod or the outside threads of the outer tube.

Failure to observe this precaution could scratch or gouge the sliding potion of the piston rod, or damage the seals, which could lead to oil leakage and malfunction. Furthermore, damage to outside threaded portion of the outer tube could prevent the shock absorber from being mounted onto the frame, or its internal components could deform, leading to a malfunction.

5. Never turn the screw on the bottom of the body.

This is not an adjusting screw. Turning it could result in oil leakage.





RB Series **Specific Product Precautions 3**

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions.

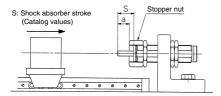
Mounting

⚠ Caution

6. Adjust the stopping time through the use of the stopper nut, as

Control the stopping time of the impact object by turning the stopper nut in or out (thus changing length "a"). After establishing the stopper nut position, use a hexagon nut to secure the stopper nut in place.

Capacity of shock absorbers deteriorate in accordance with usage. When crashing sounds or vibrations are generated during the operation. adjust the stopper nut and make the effective stroke (a) longer, or give the stroke enough leeway beforehand



Maintenance

1. Check the mounting nut is not loosen.

The shock absorber could become damaged if it is used in a loose

2. Pay attention to any abnormal impact sounds or vibrations.

If the impact sounds or vibrations have become abnormally high, the shock absorber may have reached the end of its service life. If this is the case, replace the shock absorber. If use is continued in this state, it could lead to equipment damage

3. Confirm that abnormality, oil leakage, etc. in the outward surface.

When a large amount of oil is leaking, replace the product, because it is believed to be happening something wrong with it. If it keeps on using, it may cause to break the equipment which is mounted by this product.

4. Inspect the cap for any cracks or wear.

If the shock absorber comes with a cap, the cap could wear first. To prevent damage to the impact object, replace the cap often.

Storage

Caution

1. Piston rod position while stored

If a piston rod is stored as pushed in for a long period of time (over 30 days), absorption capacity may decrease.

Avoid storing like this for a long time.

Service Life and Replacement Period of Shock Absorber

∕∖∖ Caution

1. Allowable operating cycle under the specifications set in this catalog is shown below.

1.2 million cycles RB0604, RB08□□ 2 million cycles RB10□□ to RB2725 RBADDDD, RBLDDDD 1 million cycles

Note) Specified service life (suitable replacement period) is the value at room temperature (20 to 25°C). The period may vary depending on the temperature and other conditions. In some cases the absorber may need to be replaced before the allowable operating cycle above.

RJ

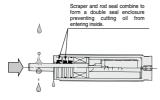




Shock Absorber: Coolant Resistant Type

RBL Series

Can be operated in an environments exposed to non-water soluble cutting oil. (Mainly JIS Class 1 equivalent)



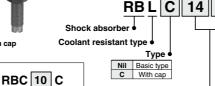


Specifications

Mode	Basic type	RBL1006	RBL1007	RBL1411	RBL1412	RBL2015	RBL2725	
Specifications	With cap	RBLC1006	RBLC1007	RBLC1411	RBLC1412	RBLC2015	RBLC2725	
Max. energy absor	ption (J) Note)	3.92	5.88	14.7	19.6	58.8	147	
Thread O.D. siz	ze	M10	x 1.0	M14	x 1.5	M20 x 1.5	M27 x 1.5	
Stroke absorpt	ion (mm)	6	7	11	12	15	25	
Collision speed	d (m/s)			0.05 to 5				
Max. operating freq (cycle/min)	uency	70	70 70		45	25	10	
Max. allowable	thrust (N)	422	422	814 814		1961	2942	
Ambient temperatur	re range (°C)			-101	to 80			
Effective atmos	sphere		١	lon-water sol	uble cutting o	il		
Spring force	Extended	4.22	4.22	8.73	8.73	11.57	22.16	
(N)	Retracted	6.18	6.86	14.12	14.61	17.65	38.05	
Weight (g)	Basic type	26	26	70	70	150	365	
weight (g)	With cap	28	28	75	75	165	410	

Note) The maximum energy absorption and maximum operating frequency are measured at room temperature (20 to 25°C).

How to Order



• Optio	● Option									
Symbol	Hex. nut	Stopper nut								
Nil	2 pcs.	_								
J	3 pcs.	_								
N	_	_								
S	2 pcs.	1 pc.								
SJ	3 pcs.	1 pc.								
SN		1 nc								

- O.D.	thread	size/Str	oke

	Symbol	O.D. thread size	Stroke	Symbol	O.D. thread size	Stroke
	1006	10 mm	6 mm	1412	14 mm	12 mm
'	1007	10 mm	7 mm	2015	20 mm	15 mm
	1411	14 mm	11 mm	2725	27 mm	25 mm

| 10| RBLC1006, 1007 | 20| RBLC2015 | 27| RBLC2725 | Cap cannot be mounted for basic type

With cap

Applicable model

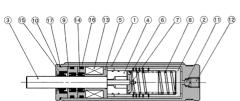
Cap cannot be mounted for basic type. Please place an order with cap type from the beginning.

Construction

Basic type

Replacement part no./

Cap (Resin part only)

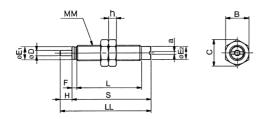


Com	ponent	Parts

No.	Description	Material	Treatment
1	Outer tube	Rolled steel	Gray coated
2	Inner tube	Special steel	Heat treated
3	Piston rod	Special steel	Electroless nickel plated
4	Piston	Special steel	Heat treated
5	Bearing	Special bearing material	
6	Spring guide	Carbon steel	Zinc chromated
7	Lock ring	Copper	
8	Return spring	Piano wire	Zinc chromated
9	Seal holder	Copper alloy	
10	Stopper	Carbon steel	Zinc chromated
11	Steel ball	Bearing steel	
12	Set screw	Special steel	
13	Accumulator	NBR	Foam rubber
14	Rod seal	NBR	
15	Scraper	NBR	
16	Gasket	NBR	
17	Gasket	NBR	Only RBL(C)2015, 2725

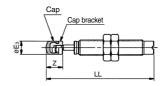
Dimensions

Basic type: RBL1006, RBL1007



With cap: RBLC1006, RBLC1007

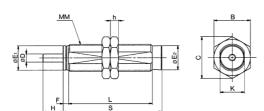
* Other dimensions are the same as the basic type.



Mo		Basic type dimensions						W	ith cap	*	He	exagon	nut				
Basic type	With cap	D	Εı	E ₂	F	Н	а	L	LL	MM	S	Eз	LL	Z	В	С	h
RBL1006	RBLC1006	3	8.8	8.6	2.7	6	1.4	43.8	57.5	M10 x 1.0	51.5	8.7	67.5	10	14	16.2	4
RBL1007	RBLC1007	3	8.8	8.6	2.7	7	1.4	43.8	58.5	M10 x 1.0	51.5	8.7	68.5	10	14	16.2	4

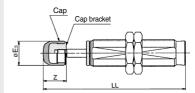
Note) L, LL and S dimensions of RBL(C)1007/1006 are different from those of RB(C)1007/1006.

Basic type: RBL1411·RBL1412·RBL2015·RBL2725



With cap: RBLC1411.RBLC1412 RBLC2015-RBLC2725

* Other dimensions are the same as the basic type.



	R	J
ĺ	R	R

Mo	del		Basic type dimensions					With cap*			Hexagon nut						
Basic type	With cap	D	E ₁	E ₂	F	Н	K	L	LL	MM	S	E ₃	LL	Z	В	C	h
RBL1411	RBLC1411	5	12.2	12	3.5	11	12	63.6	83.1	M14 x 1.5	72.1	12	96.6	13.5	19	21.9	6
RBL1412	RBLC1412	5	12.2	12	3.5	12	12	63.6	84.1	M14 x 1.5	72.1	12	97.6	13.5	19	21.9	6
RBL2015	RBLC2015	6	18.2	18	4	15	18	62.2	88.2	M20 x 1.5	73.2	18	105.2	17	27	31.2	6
RBL2725	RBLC2725	8	25.2	25	5	25	25	91.5	129.5	M27 x 1.5	104.5	25	152.5	23	36	41.6	6

Note) L, LL and S dimensions are different from those of RB(C) (except RBL(C)2015).

Hexagon Nut

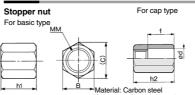
(2 pcs. standard equipment)



Material: Special steel
Treatment: Zinc trivalent chromated

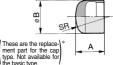
Part no.	Dimensions						
raitiio.	MM	h	В	С			
RB10J	M10 x 1.0	4	14	16.2			
RB14J	M14 x 1.5	6	19	21.9			
RB20J	M20 x 1.5	6	27	31.2			
RB27J	M27 x 1.5	6	36	41.6			

Option



	rreatment. Zinc trivalent chromated							mateu
Par	t no.	Dimensions						
Basic type	With cap	В	С	h1	h2	MM	d	f
RB10S	RBC10S	14	16.2	8	23	M10 x 1.0	11	15
RB14S	RBC14S	19	21.9	11	31	M14 x 1.5	15	20
RB20S	RBC20S	27	31.2	16	40	M20 x 1.5	23	25
RB27S	RBC27S	36	41.6	22	51	M27 x 1.5	32	33

Replacement Parts



e basic type. Material: Polyurethane

Part no.	Dimensions					
raitiio.	Α	В	SR			
RBC10C	9	8.7	7.5			
RBC14C	12.5	12	10			
RBC20C	16	18	20			
RBC27C	21	25	25			

D-□ -X□





Foot Bracket for Shock Absorber

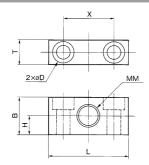
Available for the foot mounting bracket of the RBL series.

Material: Aluminum alloy

Part no.	Treatm	ent: Black hard ánodized
Part no.		Applicable absorber
RB10-X3	31	RB□1006, 1007
RB14-X3	31	RB□1411, 1412
RB20-X3	31	RB□2015
RB27-X3	31	RB□2725

^{*} Order foot brackets separately.

Dimensions

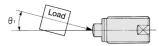


Part no.	В	D	Н	L	MM	Т	Χ	Mounting bolt
RB10-X331	19	5.5 drill, 9.5 counterbore depth 5.4	9.5	40	M10 x 1.0	12	25	M5
RB14-X331	25	9 drill, 14 counterbore depth 8.6	12.5	54	M14 x 1.5	16	34	M8
RB20-X331	38	11 drill, 17.5 counterbore depth 10.8	19	70	M20 x 1.5	22	44	M10
RB27-X331	50	13.5 drill, 20 counterbore depth 13	25	80	M27 x 1.5	34	52	M12

Shock Absorber: Short Type

RBQ Series

Allowable eccentric angle is 5°



Allowable eccentic angle $\theta_1 \le 5^{\circ}$ Ideal for absorption of rotating energy



With bumper RBQC series

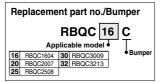
Basic type RBQ series

Specifications

Model	Basic type	RBQ1604	RBQ2007	RBQ2508	RBQ3009	RBQ3213		
Specifications	With bumper	RBQC1604	RBQC2007	RBQC2508	RBQC3009	RBQC3213		
Max. energy absorption (J) Note)		1.96	11.8	19.6	33.3	49.0		
Thread O.D. size		M16 x 1.5	M20 x 1.5	M25 x 1.5	M30 x 1.5	M32 x 1.5		
Stroke absorption (mm)		4	7	8	8.5	13		
Collision speed (m/s)		0.05 to 3						
Max. operating frequence	Max. operating frequency (cycle/min)		60	45	45	30		
Max. allowable th	rust (N)	294	490	686	981	1177		
Ambient tempera	ature (C°)			-10 to 80				
Spring force (N)	Extended	6.08	12.75	15.69	21.57	24.52		
Spring force (N)	Retracted	13.45	27.75	37.85	44.23	54.23		
Weight (g)		28	60	110	182	240		
Option/Stopper r	nut	RBQ16S	RB20S	RBQ25S	RBQ30S	RBQ32S		

Note) The maximum energy absorption and maximum operating frequency are measured at room temperature (20 to 25°C).

How to Order



* 2 mounting hexagon nuts are attached as standard.

	F	<u>RBQ</u>	C	20	07			
Shock absorber Short type								
		Тур	e 🖢					
	Nil	Basic ty	ре					
	С	With bum	per					
O.D. thread size/Stroke								
Stroke	Symbol	O.D. thr	ead siz	e Str	roke			

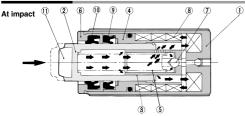
Hex. nut	Stopper nut
2 pcs.	_
3 pcs.	_
_	_
2 pcs.	1 pc.
3 pcs.	1 pc.
_	1 pc.
	2 pcs.

Option

Symbol	O.D. thread size	Stroke	Symbol	O.D. thread size	Stroke	
1604	16 mm	4 mm	3009	30 mm	9 mm	
2007	20 mm	7 mm	3213	32 mm	13 mm	
2508	25 mm	8 mm				

Bumper cannot be mounted for basic type. Please place an order with bumper type from the beginning.

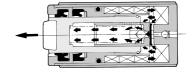
Construction



An impact object that strikes against the piston rod end pressurizes oil inside the piston. Thus, pressurized oil jets out through the orifice inside the piston, thereby generating hydraulic resistance to absorb the energy of the impacting object.

The oil jetted out through the orifice is collected inside the outer tube by means of the stretching action of the accumulator.

At returning



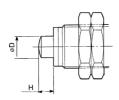
When the impact object is removed, the return spring pushes out the piston rod, and negative pressure, generated at the same time, opens the check ball to permit oil to return to the inside of the piston rod and the piston, making the shock absorber ready for the next impact.

Component Parts

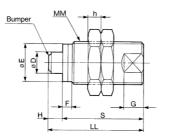
No.	Description	Material	Treatment
1	Outer tube	Rolled steel	Black electroless nickel plated
2	Piston rod	Special steel	Heat treated, Hard chrome plated
3	Piston	Special steel	Heat treated
4	Bearing	Special bearing material	
5	Return spring	Piano wire	Zinc chromated
6	Stopper	Carbon steel	Zinc chromated

No.	Description	Material	Treatment
7	Check ball	Bearing steel	
8	Accumulator	Fluororubber	Foam rubber
9	Rod seal	NBR	
10	Scraper	NBR	
11	Bumper	Polyurethane	Only with bumper

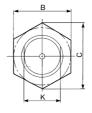
Dimensions



RBQ series Basic type



RBQC series With bumper



Me		Shock absorber						Hexagon nut					
Basic type	With bumper	D	E	F	Н	K	G	LL	MM	S	В	С	h
RBQ1604	RBQC1604	6	14.2	3.5	4	14	7	31	M16 x 1.5	27	22	25.4	6
RBQ2007	RBQC2007	10	18.2	4	7	18	9	44.5	M20 x 1.5	37.5	27	31.2	6
RBQ2508	RBQC2508	12	23.2	4	8	23	10	52	M25 x 1.5	44	32	37	6
RBQ3009	RBQC3009	16	28.2	5	8.5	28	12	61.5	M30 x 1.5	53	41	47.3	6
RBQ3213	RBQC3213	18	30.2	5	13	30	13	76	M32 x 1.5	63	41	47.3	6

Hexagon Nut

(2 pcs. standard equipment)



Material: Special steel Treatment: Zinc trivalent chromated

Part no.	MM	h	В	С			
RBQ16J	M16 x 1.5	6	22	25.4			
RB20J (1)	M20 x 1.5	6	27	31.2			
RBQ25J	M25 x 1.5	6	32	37			
RBQ30J	M30 x 1.5	6	41	47.3			
RBQ32J	M32 x 1.5	6	41	47.3			

Note 1) In the case of RB20J, RB and RBQ are common.

Option





Material: Carbon steel Treatment: Zinc trivalent ch

Treatment. Zine thvalent emonia								
Part no.	В	С	h1	MM				
RBQ16S	22	25.4	12	M16 x 1.5				
RB20S(2)	27	31.2	16	M20 x 1.5				
RBQ25S	32	37	18	M25 x 1.5				
RBQ30S	41	47.3	20	M30 x 1.5				
RBQ32S	41	47.3	25	M32 x 1.5				

Note 2) In the case of RB20S, RB and RBQ are common.

Replacement Parts

Bumper



These are the replace-ment part for the with bumper type. Not avail-able for the basic type.

		Material: Polyurethane				
Part no.	Α	В	С			
RBQC16C	3.5	4	4.7			
RBQC20C	4.5	8	8.3			
RBQC25C	5	8.3	9.3			
RBQC30C	6	11.3	12.4			
RBQC32C	6.6	13.1	14.4			

911

RJ

RB

Shock Absorber: Short Type

RBQ Series

Technical Data:

Model Selection

Model Selection Step

1. Type of impact

- □ Cylinder stroke at load (Horizontal) □ Cylinder stroke at load (Downward) □ Cylinder stroke at load (Upward)
- Conveyor stroke at load (Horizontal)
- □ Free dropping impact
- Rotating impact (With torque)

2. Enumeration of operating conditions

Unit kg
s ka
m/sec
m
rad/sec
m
mm
re MPa
N
N · m
cycle/min
• °C

- 3. Specifications and operational instructions Ensure that the collision speed, thrust operation cycle, the ambient temperature and atmosphere fall within the specifications.
- *Be aware of the min. installation radius in the case of rotating impacts.
- Calculation of kinetic energy E₁ Using the equation suitable for the classification of impact.

In the case of cylinder stroke at load and free horizontal impact. substitute respective figures for Data A in order to calculate E1.

5. Calculation of thrust energy E2

Select any shock absorber as a provisional

In the case of thrust energy of cylinder E2, substitute respective figures for Data B or Data C.

6. Calculation of corresponding mass of impacting object Me

Absorbed energy E = E1 + E2

Corresponding mass of impacting object $\mathbf{Me} = \frac{2}{2n^2} \cdot \mathbf{E}$

Substitute both absorbed energy E and collision speed v for Data A in order to calculate the corresponding mass of the impacting object Me.

7. Selection of applicable model

Taking into consideration the corresponding mass of the impacting object Me, calculated using Data D and collision speed v, check provisional model compatibility with the condition of application. If this is satisfactory, then the said provisional model will be the applicable one

Caution on Selection

In order for the shock absorbers to operate accurately for long hours, it is necessary to select a model that is well-suited to your operating conditions. If the impact energy is smaller than 5% of the maximum energy absorption, select a model that is one class

Selection Example

1. Type of impact	Cylinder stroke at load (Horizontal) Shock absorber Fi Cylinder Cylinder					
Collision speed $^{(1)}$	υ					
Kinetic energy E ₁	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$					
Thrust energy E ₂	F ₁ · S					
Absorbed energy E	E ₁ + E ₂					
Corresponding (2) mass of impacting object Me	<u>2</u> ⋅ E					
2. Operating conditions						

Specifications and operational

 Confirmation of specifications $\upsilon \cdots 0.7 < 3 \text{ (max.)}$ $t \cdots -10 \text{ (min.)} < 25 < 80 \text{ (max.)}$ $F \cdots F_1 \cdots 628 < 686 \text{ (max.)}$

instructions

Calculation of kinetic energy E₁

YES Kinetic energy E

Use Formula to calculate E1 Suitable 20 for **m** and 0.7 for v E₁ ≅ 4.9 J

Thrust energy E2

Calculation of thrust eneray E2

Provisionally select a mod RBQ2508 and make the use of Data B . According to d = 40, E2

$E_2\cong 5.0\ J$

Calculation of corresponding mass of impacting

obiect Me

model

Corresponding mass of impacting object Me

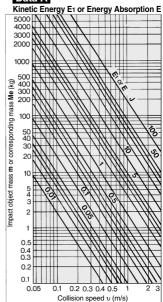
Use the formula "Absorbed energy E = E1 + E2 = 4.9 + 5.0 = 9.9 J" to calculate Me. Substitute 9.9 J for E and 0.7 for u

Me ≅ 40 kg

 Selection of applicable model According to Data D , the tentatively selected RBQ2508 satisfies **Me** = 40 kg < 60 kg at v = 0.7. Ultimately, it will result in an operating Selection of frequency of n...30 < 45, without applicable causing a problem



Data A



1. Type of Impact

	Cylinder stroke at load (Downward)	Cylinder stroke at load (Upward)	Conveyor stroke at load (Horizontal)	Free dropping impact	Rotating impact (With torque)	
Type of impact	Cylinder	v Cylinder	Load m d	Load m	a (3)	
Collision speed (1)	υ	υ	υ	$\sqrt{2 \text{ gh}}$	ω·R	
Kinetic energy E ₁	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	$\frac{1}{2} \cdot \mathbf{m} \cdot v^2$	m · g · h	$\frac{1}{2} \cdot I \cdot \omega^2$	
Thrust energy E2	$F_1 \cdot S + m \cdot g \cdot S$	$F_1 \cdot S - m \cdot g \cdot S$	m · g · μ · S	m · g · S	T · S	
Absorbed energy E	E1 + E2	E ₁ + E ₂	E ₁ + E ₂	E ₁ + E ₂	E1 + E2	
Corresponding (2) mass of impacting object Me	<u>2</u> ⋅ E	<u>2</u> ⋅ E	<u>2</u> ⋅ E	<u>2</u> ⋅ E	<u>2</u> ⋅ E	

Note 1) Collision speed is momentary velocity at which object is impacting against shock absorber.

The collision speed is $\upsilon = 2\overline{\upsilon}$ when the speed (average speed $\overline{\upsilon}$) is calculated from the air cylinder's stroke time.

Note 2) An "Impact body equivalent mass" is the mass of an impact object without involving thrust, into which an object's total energy has been converted. Hence, $E = \frac{1}{2}$ -Me- \mathbb{U}^2

Note 3) R: The distance between rotational center and impact point. Set R at the minimum installation radius (page 916) or higher.

Data B

Thrust Energy of Cylinder F1 · S (Operating pressure 0.5 MPa) (J)

Till dat Ellergy of Cylinder 1 1 to (openamy processe one in a) (
Model		RBQ□1604	RBQ□2007	RBQ□2058	RBQ□3009	RBQ□3213		
	absorption nm)	4	7	8	8.5	13		
	6	0.057	0.099	0.113	0.120	0.184		
	10	0.157	0.274	0.314	0.334	0.511		
	15	0.353	0.619	0.707	0.751	1.15		
	20	0.628	1.10	1.26	1.34	2.04		
	25	0.982	1.72	1.96	2.09	3.19		
	32	1.61	2.81	3.22	3.42	5.23		
Ē	40	2.51	4.40	5.03	5.34	8.17		
(mm)	50	3.93	6.87	7.85	8.34	12.8		
0	63	6.23	10.9	12.5	13.2	20.3		
size	80	10.1	17.6	20.1	21.4	32.7		
Bore	100	15.7	27.5	31.4	33.4	51.1		
ĕ	125	24.5	43.0	49.1	52.2	79.8		
	140	30.8	53.9	61.6	65.4	100		
	160	40.2	70.4	80.4	85.5	131		
	180	50.9	89.1	102	108	165		
	200	62.8	110	126	134	204		
	250	98.2	172	196	209	319		
	300	141	247	283	300	459		

Operating pressure other than 0.5 MPa: Multiply by the following coefficient.

Operating pressure (MPa)	1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
Coefficient	0.2	0.4	0.6	0.8	1.0	1.2	1.4	1.6	1.8

Symbol

Symbol	Specifications	Unit
d	Bore size	mm
E	Absorbed energy	J
E ₁	Kinetic energy	J
E ₂	Thrust energy	J
F ₁	Cylinder thrust	N
g	Acceleration of gravity (9.8)	m/s ²
h	Dropping height	m
I (4)	Moment of inertia around the center of gravity	kg-m²
n	Operating frequency	cycle/min
р	Cylinder operation pressure	MPa
R	Distance between axis of cylinder and impact point	m
S	Shock absorber stroke	m
Т	Torque	N⋅m
t	Ambient temperature	∘c
υ	Collision speed	m/s
m	Impact object mass	kg
Ме	Corresponding mass of impact object	kg
ω	Angle speed	rad/s
μ	Friction coefficient	_

Note 4) For the formula of moment of inertia I $(kg \cdot m^2)$, refer to the catalog of rotary actuator.

D-□

RJ

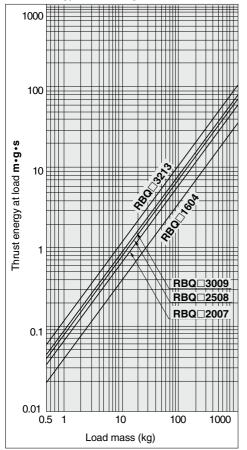
-X□



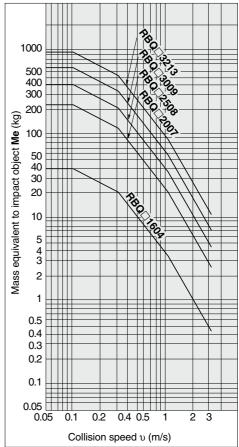
RBQ Series

Data C

Thrust Energy at Load m · g · s



Data D Corresponding Mass of Impacting Object Me



The corresponding mass graph shows the values at room temperature (20 to 25 $^{\circ}$ C).



RBQ Series **Specific Product Precautions 1**

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions.

Selection

🗥 Danger

1. Energy absorption

Select a model so that the aggregated energy of impact object should not exceed the maximum absorption energy. Otherwise, it could cause changes in properties or result in damaging the shock absorber.

2. Corresponding mass of impacting object

Make a model selection, so that the corresponding mass of impacting object does not exceed the allowable range. Pulsation will occur in buffer and deceleration force, thus making it difficult to absorb shock smoothly.

3. Collision speed

Use it in the conditions that collision speed is within the specified range. It could cause the changes in buffer characteristics or lead to damage a shock absorber

♠ Warning

Design the system, so that any other forces than the buffer capacity or impacts should not be applied to the piston rod which is stopped at the retracted state

∕**.**∖ Caution

1. Maximum operating frequency

Design the system in the conditions under which it is not used at the frequency exceeding the specified maximum operating frequency.

2. Stroke

The maximum absorption energy in the specifications cannot be exerted unless the full stroke is used

3. Work surface of an impact object

The contact surface of the impact object with which the piston rod comes into contact must be highly rigid.

In the case without a cap, a high surface compression load is applied to the contact surface of the impact body with which the piston rod comes into contact. Therefore, the contact surface must be highly rigid (hardness of HRC35 or more).

4. Be aware of the return force of the impact object.

If used in a conveyor drive, after the shock absorber has absorbed energy, it could be pushed back by the spring that is built-in. For the spring force in the specifications, refer to the column (page 910).

5. Selection of size

As the number of operation proceeds, the maximum absorption energy of shock absorbers will be decreased by the following reasons such as abrasion, or deterioration, etc. of the internal working fluid. Taking this into consideration, selecting a size which is 20 to 40% affordable against the amount of absorption energy is recommended.

∕**∴** Caution

6. Drag characteristics

In general, the values of drag (reactive force generated during operation) generated by the operating speed will vary in hydraulic shock absorber. And then, by adopting "Porous orifice construction", the RB series can adapt to such this fast/slow speed and can absorb shock smoothly in a wide range of speed.

But, the speed reduction (speed reduction G) would be larger around the stroke terminal, depending upon the operating conditions. Please note that it might be encountered that stroke time is long, motion is not smooth, etc. If this would be a problem, we recommend that stroke amount should be restricted by using our optional component like "Stopper nut", etc.

7. Parallel usage

When using multiple shock absorbers in parallel, energy will not be divided evenly because of differences in product dimensions and devices. For this reason, select the following options.

E: Energy used per shock absorber

Ea: All energies

N: The number of shock absorbers used in parallel

Operating Environment

⚠ Danger

1. Operation in an environment which requires explosion-proof

. When mounting in places where static electricity is accumulated, implement a distribution of electrical energy by grounding.

. Do not use the materials for buffer face which might cause to spark by collision

∕∿ Warning

Do not use it in the vacuum state, which is substantially different from the atmospheric pressure (above sea level) and in the atmosphere under being pressurized.

2. Using inside a clean room

Do not use the shock absorber in a clean room, as it could contaminate the clean room.

∕!∖ Caution

1. Temperature range

Do not use it, exceeding the specified allowable temperature range. Seal could be softened or hardened or worn out, or leading to leak a working fluid, deterioration, or impact characteristic changes.

2. Deterioration by atmosphere

Do not use the product in an environment where the product may be damaged by salt or air which contains organic solvent, phosphoester operating oil, sulfurous acid gas, chlorine gas or other acids. It may deteriorate seals or corrode metals.

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RBQ Series Specific Product Precautions 2

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions.

Operating Environment

3. Deterioration by ozone

Do not use it under the direct sunlight on the beach, or by the mercury lamp, or the ozone generator, because the rubber material will be deteriorated by ozone.

4. Cutting oil, water, blown dust

Do not use the product under the condition, where the liquid such as cutting oil, water, solvent, etc. is exposed either directly or in atomized form to the piston rod, or where blown dust could be adhered around the piston rod. This could cause malfunction.

5. Vibration

When vibrations are applied on impact objects, implement a secure guide on impact objects.

Mounting

 Before performing installation, removal, or stroke adjustment, make sure to cut the power supply to the equipment and verify that the equipment has stopped.

2. Installation of protective cover

We recommend the protective cover should be installed in the case workers might be getting close during the operation.

3. The rigidity of the mounting frame

The mounting frame must have sufficient rigidity.

Load on mounting plate can be calculated as follows.

$$\label{eq:Load on mounting plate} \text{Load on mounting plate} \quad N \cong 2 \, \frac{\text{E (Absorbed energy : J)}}{\text{S (Stroke : m)}}$$

Depending on the impact conditions, a load applied to the mounting frame may exceed the calculated value.

When setting the rigidity of the mounting frame, the sufficient safety ration must be taken into account in the calculated value.

916

1. Tightening torque of mounting nut should be as follows.

When threading on a mounting frame in order to mount a shock absorber directly, prepared hole dimensions are referred to the table helow

For tightening torque of a nut for shock absorber, kindly abide by the table below.

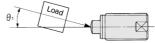
If the tightening torque that is applied to the nut exceeds the value given below, the shock absorber itself could become damaged.

Model	RBQ(C)1604	RBQ(C)2007	RBQ(C)2508	RBQ(C)3009	RBQ(C)3213
O.D. thread (mm)	M16 x 1.5	M20 x 1.5	M25 x 1.5	M30 x 1.5	M32 x 1.5
Thread prepared bore (mm)	ø14.7 ^{+0.1}	ø18.7 ^{+0.1}	ø23.7 ^{+0.1}	ø28.7 ^{+0.1}	ø30.7 ^{+0.1}
Tightening torque (N · m)	14.7	23.5	34.3	78.5	88.3

Mounting

2. Deviation of impact.

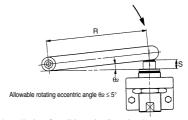
The installation must be designed so that the impact body is perpendicular to the shock absorber's axial center. An angle of deviation that exceeds 5° will place an excessive load on the bearings, leading to oil leaks within a short period of operation.



Allowable eccentric angle θ1 ≤ 5°

3. Rotating angle

If rotating impacts are involved, the installation must be designed so that the direction in which the load is applied is perpendicular to the shock absorber's axial center. The allowable rotating eccentric angle until the stroke end must be $\theta \ge 5$ 5°.



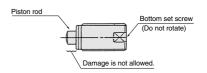
- !	Installation Conditions for Rotating Impact								
	Model	S (Stroke)	θ ₂ (Allowable rotating angle)	R (Min. installation radius)					
	RBQ□1604	4		46					
	RBQ□2007	7]	80					
	RBQ□2508	8] 5°	92					
	RBQ□3009	8.5]	98					
	RBQ□3213	13		149					

Do not scratch the sliding portion of the piston rod or the outside threads of the outer tube.

Failure to observe this precaution could scratch or gouge the sliding potion of the piston rod, or damage the seals, which could lead to oil leakage and malfunction. Furthermore, damage to outside threaded portion of the outer tube could prevent the shock absorber from being mounted onto the frame, or its internal components could deform, leading to a malfunction.

5. Never turn the screw on the bottom of the body.

This is not an adjusting screw. Turning it could result in oil leakage.





RBQ Series Specific Product Precautions 3

Be sure to read this before handling the products. Refer to back page 50 for Safety Instructions.

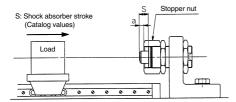
Mounting

⚠ Caution

6. Adjust the stopping time through the use of the stopper nut, as follows:

Control the stopping time of the impact object by turning the stopper nut in or out (thus changing length "a"). After establishing the stopper nut position, use a hexagon nut to secure the stopper nut in place.

Capacity of shock absorbers deteriorate in accordance with usage. When crashing sounds or vibrations are generated during the operation, adjust the stopper nut and make the effective stroke (a) longer, or give the stroke enough leeway beforehand.



Maintenance

⚠ Caution

1. Check the mounting nut is not loosen.

The shock absorber could become damaged if it is used in a loose state.

2. Pay attention to any abnormal impact sounds or vibrations.

If the impact sounds or vibrations have become abnormally high, the shock absorber may have reached the end of its service life. If this is the case, replace the shock absorber. If use is continued in this state, it could lead to equipment damage.

3. Confirm that abnormality, oil leakage, etc. in the outward surface.

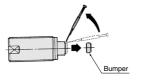
When a large amount of oil is leaking, replace the product, because it is believed to be happening something wrong with it. If it keeps on using, it may cause to break the equipment which is mounted by this product.

4. Inspect the bumper for any cracks or wear.

If the shock absorber comes with a bumper, the damper could wear first. To prevent bumper to the impact object, replace the bumper often.

5. How to replace bumper

The bumper inserted into the piston rod can be removed easily by a small screwdriver. When reassembling, push the smaller end of the bumper inside the piston.



Storage

1. Piston rod position while stored

If a piston rod is stored as pushed in for a long period of time (over 30 days), absorption capacity may decrease.

Avoid storing like this for a long time.

Service Life and Replacement Period of Shock Absorber

 Allowable operating cycle under the specifications set in this catalog is shown below.

2 million cycles

Note) Specified service life (suitable replacement period) is the value at room temperature (20 to 25°C). The period may vary depending on the temperature and other conditions. In some cases the absorber may need to be replaced before the allowable operating cycle above.

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